

Thomas Ehrhard's 60 birthday

∂ is for Dialectica

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Work in collaboration with Pierre-Marie Pédro

Thank you Thomas

... For the opportunity to finally understand **differentiation**.

What's differentiation ?

Thank you Thomas

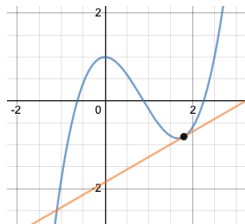
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What's differentiation ?

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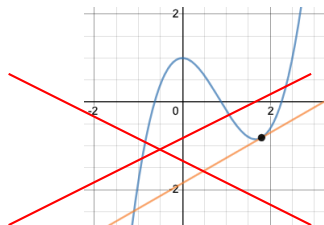
What's differentiation ?



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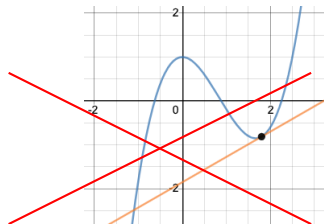
What's differentiation ?



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What's differentiation ?



$$\frac{d}{dx}(c) = 0$$

$$\frac{d}{dx}(u \pm v \pm \dots) = \frac{du}{dx} \pm \frac{dv}{dx} \pm \dots$$

$$\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$$

$$\frac{d}{dx}(u^a) = au^{a-1} \frac{du}{dx}$$

$$\frac{d}{dx}e^u = e^u \frac{du}{dx}$$

$$\frac{d}{dx}\ln u = \frac{1}{u} \frac{du}{dx}$$

$$\frac{d}{dx}\sin u = \cos u \frac{du}{dx}$$

$$\frac{d}{dx}\cos u = -\sin u \frac{du}{dx}$$

$$\frac{d}{dx}(a) = 0$$

$$\frac{d}{dx}(au) = a \frac{du}{dx}$$

$$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$$

$$\frac{d}{dx}\log_e u = \frac{\log_e e}{u} \frac{du}{dx}$$

$$\frac{d}{dx}a^u = a^u \ln a \frac{du}{dx}$$

$$\frac{d}{dx}u^v = v u^{v-1} \frac{du}{dx} + u^v \ln u \frac{dv}{dx}$$

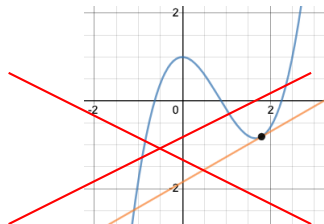
$$\frac{d}{dx}\cot u = -\csc^2 u \frac{du}{dx}$$

$$\frac{d}{dx}\sec u = \sec u \tan u \frac{du}{dx}$$

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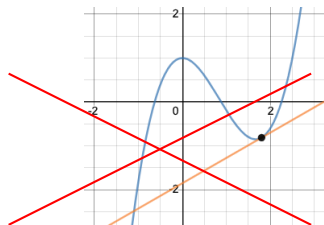


$\frac{d}{dx}(c) = 0$	$\frac{d}{dx}(a) = 0$
$\frac{d}{dx}(u \pm v \pm \dots) = \frac{du}{dx} \pm \frac{dv}{dx} \pm \dots$	$\frac{d}{dx}(au) = a \frac{du}{dx}$
$\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$	$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$
$\frac{d}{dx}(u^a) = au^{a-1} \frac{du}{dx}$	$\frac{d}{dx} \ln u = \frac{1}{u} \frac{du}{dx}$
$\frac{d}{dx} a^u = a^u \ln a \frac{du}{dx}$	$\frac{d}{dx} u^a = a u^{a-1} \frac{du}{dx}$
$\frac{d}{dx} \sin u = \cos u \frac{du}{dx}$	$\frac{d}{dx} \cos u = -\sin u \frac{du}{dx}$
$\frac{d}{dx} \cosh u = \sinh u \frac{du}{dx}$	$\frac{d}{dx} \sinh u = \cosh u \frac{du}{dx}$

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What's differentiation ?



~~| | |
|---|--|
| $\frac{d}{dx}(x) = 1$ | $\frac{d}{dx}(a) = 0$ |
| $\frac{d}{dx}(u \pm v \pm \dots) = \frac{du}{dx} \pm \frac{dv}{dx} \pm \dots$ | $\frac{d}{dx}(au) = a \frac{du}{dx}$ |
| $\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$ | $\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$ |
| $\frac{d}{dx}(u^a) = au^{a-1} \frac{du}{dx}$ | $\frac{d}{dx} \log_a u = \frac{\log_a e}{u} \frac{du}{dx}$ |
| $\frac{d}{dx} a^u = a^u \ln a \frac{du}{dx}$ | $\frac{d}{dx} u^a = u^{a-1} \frac{du}{dx} + a u^a \ln u \frac{du}{dx}$ |
| $\frac{d}{dx} \sin u = \cos u \frac{du}{dx}$ | $\frac{d}{dx} \cos u = -\sin u \frac{du}{dx}$ |
| $\frac{d}{dx} \cos u = -\sin u \frac{du}{dx}$ | $\frac{d}{dx} \sec u = \sec u \tan u \frac{du}{dx}$ |~~

That's differentiation !

$$\frac{\partial}{\partial x}((\lambda z.t)u) \cdot s = \left(\frac{\partial(\lambda z.t)}{\partial x} \cdot s\right)u + (D(\lambda z.y) \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

What's this talk is about

Joining **Dialectica** and **Differential λ -calculus**
through
Reverse Differentiation

What's this talk is about

Joining **Dialectica** and **Differential Linear Logic**
through
Reverse Differentiation

What's this talk is about

Joining **Dialectica** and **Differential Categories**
through
Reverse Differentiation

What's this talk is about

Joining **Dialectica** and **Differential λ -calculus**
through
Reverse Differentiation

Gödel's Dialectica Transformation

1. $(F \wedge G)' = (\exists yv) (zw) [A(y, z, x) \wedge B(v, w, u)].$
2. $(F \vee G)' = (\exists yvf) (zw) [t=0 \wedge A(y, z, x) \vee t=1 \wedge B(v, w, u)].$
3. $[(s) F]' = (\exists Y) (sz) A(Y(s), z, x).$
4. $[(\exists s) F]' = (\exists sy) (z) A(y, z, x).$
5. $(F \supset G)' = (\exists VZ) (yw) [A(y, Z(yw), x) \supset B(V(y), w, u)].$
6. $(\neg F)' = (\exists \bar{Z}) (y) \neg A(y, \bar{Z}(y), x).$



Kurt Gödel (1958). Über eine bisher noch nicht benützte Erweiterung des finiten Standpunktes. Dialectica.

► Validates semi-classical axioms:

- Markov's principle : $\neg\neg\exists xA \rightarrow \exists xA$ when A is decidable.

► Numerous applications :

- Soundness results
- **Proof mining**: applying Dialectica to theorems in analysis extract quantitative information.

”There are infinitely many prime numbers.”

\Downarrow

”For any m there exists some $m < p \leq \lceil e^{m-\gamma} \rceil$ such that p is prime.

And now for something completely different : Automatic Differentiation

How does one compute the differentiation of an algebraic expression, computed as a sequence of elementary operations ?

$$\begin{array}{lll} \text{E.g. : } z = y + \cos(x^2) & x_1 = x_0^2 & x'_1 = 2x_0x'_0 \\ & x_2 = \cos(x_1) & x'_2 = -x'_0 \sin(x_0) \\ & z = y + x_2 & z' = y' + 2x_2x'_2 \end{array}$$

Derivative of a sequence of instruction



sequence of instruction \times sequence of derivatives

Forward Mode differentiation [Wengert, 1964]

$$(x_1, x'_1) \rightarrow (x_2, x'_2) \rightarrow (z, z').$$

Reverse Mode differentiation: [Speelpenning, Rall, 1980s]

$x_1 \rightarrow x_2 \rightarrow z \rightarrow z' \rightarrow x'_2 \rightarrow x'_1$ while keeping formal the unknown derivative.

I hate graphs

$$D_u(f \circ g) = D_{g(u)}f \circ D_u(g)$$

► **Forward Mode differentiation :**

$$g(u) \rightarrow D_u g \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_{g(u)}f \circ D_u(g).$$

► **Reverse Mode differentiation:**

$$g(u) \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_u(g) \rightarrow D_{g(u)}f \circ D_u(g)$$

The choice of an algorithm is due to complexity considerations:

► **Forward mode** for $f \circ g : \mathbb{R} \rightarrow \mathbb{R}^n$.

► **Reverse mode** for $f \circ g : \mathbb{R}^n \rightarrow \mathbb{R}$

\rightsquigarrow *Differentiable programming* is a new research area triggered by the advances of deep learning algorithms on neural networks, it tries to attach two very old domains: lambda-calculus and automatic differentiation, with *correctness* and *modularity* goals in mind.

Functorial Forward AD

$$\mathbf{D}_u(f \circ g) = \mathbf{D}_{g(u)}f \circ \mathbf{D}_u(g)$$

Non-functorial !!!

How to make differentiation functorial ? **Make it act on pairs !**

Forward Mode differentiation :

$$g : E \Rightarrow F \rightsquigarrow \overrightarrow{D}g : E \Rightarrow E \multimap F.$$

Functorial forward differentiation :

$$\overrightarrow{D}(g) : \begin{cases} E \times E \rightarrow F \times F \\ (a, x) \mapsto (f(a), (\mathbf{D}_a f \cdot x)) \end{cases}$$

Reverse functorial differentiation

Linear implication

$$A^\perp \equiv A \multimap \perp \equiv \mathcal{L}(A, \mathbb{R}) \equiv A'$$

Reverse functorial differentiation

Linear implication

$$A^\perp \equiv A \multimap \perp \equiv \mathcal{L}(A, \mathbb{R}) \equiv A'$$

► Reverse Mode differentiation:

$$g(u) \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_{g(u)}f \circ D_u(g)$$

$$D_u(g) : F' \multimap E'; \ell \mapsto \ell \circ D_u g$$

$$g : E \Rightarrow F \rightsquigarrow \overleftarrow{D}g : E \Rightarrow F^\perp \multimap E^\perp.$$

[Mazza, Pagani, POPL2020]

Reverse functorial differentiation

Linear implication

$$A^\perp \equiv A \multimap \perp \equiv \mathcal{L}(A, \mathbb{R}) \equiv A'$$

► Reverse Mode differentiation:

$$g(u) \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_{g(u)}f \circ D_u(g)$$

$$D_u(g) : F' \multimap E'; \ell \mapsto \ell \circ D_u g$$

$$g : E \Rightarrow F \rightsquigarrow \overleftarrow{D}g : E \Rightarrow F^\perp \multimap E^\perp.$$

[Mazza, Pagani, POPL2020]

► Reverse functorial differentiation :

$$(f, \overleftarrow{D}(f)) : (E \Rightarrow F) \times (E \Rightarrow F^\perp \multimap E^\perp)$$

Outline of the talk

- Reverse differentiation and differentiable programming.
- Dialectica acting on formulas.
- Dialectica acting on λ -terms.
- Factorizing Dialectica through differential linear logic.
- Applications and related work.

A Dialectica Transformation

- Gödel Dialectica transformation [1958] : a translation from intuitionistic arithmetic to a finite type extension of primitive recursive arithmetic.

$$A \rightsquigarrow \exists u : \mathbb{W}(A), \forall x : \mathbb{C}(A), A^D[u, x]$$

- De Paiva [1991]: the linearized Dialectica translation operates on Linear Logic (types) and λ -calculus (terms).
- Pedrot [2014] A *computational* Dialectica translation preserving β -equivalence, via the introduction of an "abstract multiset constructor" on types on the target.

Gödel's Dialectica

1. $(F \wedge G)' = (\exists yv) (zw) [A(y, z, x) \wedge B(v, w, u)].$
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5. $(F \supset G)' = (\exists VZ) (yw) [A(y, Z(yw), x) \supset B(V(y), w, u)].$
6. $(\neg F)' = (\exists \tilde{Z}) (y) \neg A(y, \tilde{Z}(y), x).$



Kurt Gödel (1958). Über eine bisher noch nicht benützte Erweiterung des finiten Standpunktes. Dialectica.

Gödel's Dialectica

- ▶ Validates semi-classical axioms:
 - ▶ Markov's principle : $\neg\neg\exists xA \rightarrow \exists xA$ when A is decidable.
 - ▶ Independent of premises : $(A \rightarrow \exists xB) \rightarrow (\exists x.(A \rightarrow B))$
- ▶ Numerous applications :
 - ▶ Soundness results
 - ▶ Proof mining

A further distinguishing feature of the D-interpretation is its nice behavior with respect to modus ponens. In contrast to cut-elimination, which entails a global (and computationally infeasible) transformation of proofs, the D-interpretation extracts constructive information through a purely local procedure: when proofs of φ and $\varphi \rightarrow \psi$ are combined to yield a proof of ψ , witnessing terms for the antecedents of this last inference are combined to yield a witnessing term for the conclusion. As a result of this modularity, the interpretation of a theorem can be readily obtained from the interpretations of the lemmata used in its proof.



Jeremy Avigad and Solomon Feferman (1999). Gödel's functional ("Dialectica") interpretation

A peek into Dialectica interpretation of functions

$$(A \rightarrow B)_D = \exists f g \forall x y (A_D(x, gxy) \rightarrow B_D(fx, y))$$

Usual explanation : least unconstructive prenexation.

- ▶ Start from $\exists x, \forall u, A_D[x, u] \rightarrow \exists y, \forall v, B_D[y, v]$.
- ▶ Obvious prenexation : $\forall x (\forall u, A_D[x, u] \rightarrow \exists y, \forall v, B_D[y, v])$
- ▶ Weak form of IP : $\forall x \exists y (\forall u, A_D[x, u] \rightarrow \forall v, B_D[y, v])$
- ▶ Prenexation : $\forall x \exists y, \forall v, \forall \neg \neg \exists u (A_D[x, u] \rightarrow B_D[y, v])$.
- ▶ Markov : $\forall x, \exists y, \forall v, \exists u (A_D[x, u] \rightarrow B_D[y, v])$
- ▶ Axiom of choice : $\exists f, \exists g, \forall u, \forall v, (A_D(u, guv) \rightarrow B_D(fu, v))$.

Dynamic behaviour : agrees to a chain rule.

Mathematical meaning : it's some kind of approximation.

Dialectica verifies the chain rules

$$(A \Rightarrow B)_D[\phi_1; \psi_1, u_1; v_1] := A_D(u_1, \psi_1 u_1 v_1) \Rightarrow B_D(\phi_1 u_1, v_1)$$

$$(B \Rightarrow C)_D[\phi_2; \psi_2, u_2; v_2] := B_D(u_2, \psi_2 u_2 v_2) \Rightarrow C_D(\phi_2 u_2, v_2)$$

$$(A \Rightarrow C)_D[\phi_3; \psi_3, u_3; v_3] := A_D(u_3, \psi_3 u_3 v_3) \Rightarrow C_D(\phi_3 u_3, v_3)$$

The Dialectica interpretation amounts to the following equations:

$$u_3 = u_1$$

$$\psi_3 u_3 v_3 = \psi_1 u_1 v_1$$

$$v_3 = v_2$$

$$\phi_2 u_2 = \phi_1 u_1$$

$$u_2 = \phi_1 u_1$$

$$v_2 = \phi_1 u_1 v_1$$

which can be simplified to:

$$\phi_3(u_3) = \phi_2(\phi_1 u_3) \text{ composition of functions}$$

$$\psi_3 * (u_3 v_3) = \psi_2(\phi_1 u_3) (\psi_1 u_3 v_3) \text{ composition of their differentials}$$

Types !

Programs and variable are **typed**
by logical formulas which describe their behavior

$$A \rightsquigarrow \exists \overbrace{x : \mathbb{W}(A)}^{\text{witness}}, \forall \underbrace{u : \mathbb{C}(A)}_{\text{opponent}}, A_D[x, u]$$

Witness and counter types :

$$\mathbb{C}(A \Rightarrow B) = \mathbb{C}(A) \times \mathbb{C}(B)$$

$$\mathbb{W}(A \Rightarrow B) = (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \times (\mathbb{W}(A) \Rightarrow \mathbb{C}(B) \Rightarrow \mathbb{C}(A))$$

Types !

Programs and variable are **typed**
by logical formulas which describe their behavior

$$A \rightsquigarrow \exists \overbrace{x : \mathbb{W}(A)}^{\text{global witness}}, \forall \underbrace{u : \mathbb{C}(A)}_{\text{local opponent}}, A_D[x, u]$$

Witness and counter for implication types :

$$\mathbb{C}(A \Rightarrow B) = \mathbb{W}(A) \times \mathbb{C}(B)$$

$$\mathbb{W}(A \Rightarrow B) = \overbrace{(\mathbb{W}(A) \Rightarrow \mathbb{W}(B))}^{\text{function}} \times \left(\mathbb{W}(A) \Rightarrow \underbrace{\mathbb{C}(B) \Rightarrow \mathbb{C}(A)}_{\text{reverse derivative}} \right)$$

Reverse Mode differentiation:

$$\text{Functorial} : (h, \overleftarrow{D}h) : (A \Rightarrow B) \times (A \Rightarrow B^\perp \multimap A^\perp)$$

However:

- ▶ Having the same type does not mean you're the same program.
- ▶ We (linear logicians) know what program differentiation is.

The computational Dialectica : a reverse Differential λ -calculus

A computational Dialectica

Making Dialectica act on λ -terms instead of formulas:

An abstract multiset $\mathfrak{M}(-)$

$$\begin{array}{c} \frac{}{\Gamma \vdash \emptyset : \mathfrak{M} A} \qquad \frac{\Gamma \vdash m_1 : \mathfrak{M} A \quad \Gamma \vdash m_2 : \mathfrak{M} A}{\Gamma \vdash m_1 \circledast m_2 : \mathfrak{M} A} \\[1em] \frac{\Gamma \vdash t : A}{\Gamma \vdash \{t\} : \mathfrak{M} A} \qquad \frac{\Gamma \vdash m : \mathfrak{M} A \quad \Gamma \vdash f : A \Rightarrow \mathfrak{M} B}{\Gamma \vdash m \ggg f : \mathfrak{M} B} \end{array}$$

$$\begin{aligned} \mathbb{W}(A \Rightarrow B) &:= (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \\ &\quad \times (\mathbb{C}(B) \Rightarrow \mathbb{W}(A) \Rightarrow \mathfrak{M} \mathbb{C}(A)) \\ \mathbb{C}(A \Rightarrow B) &:= \mathbb{W}(A) \times \mathbb{C}(B) \end{aligned}$$

Pédrot's Dialectica Transformation

Soundness [Ped14]

If $\Gamma \vdash t : A$ in the source then we have in the target

- ▶ $\mathbb{W}(\Gamma) \vdash t^\bullet : \mathbb{W}(A)$
- ▶ $\mathbb{W}(\Gamma) \vdash t_x : \mathbb{C}(A) \Rightarrow \mathfrak{M} \mathbb{C}(X)$ provided $x : X \in \Gamma$.

A global and a local transformation

$$\begin{array}{ll} x^\bullet & := x & (\lambda x. t)^\bullet & := (\lambda x. t^\bullet, \lambda \pi x. t_x \pi) \\ x_x & := \lambda \pi. \{\pi\} & (\lambda x. t)_y & := \lambda \pi. (\lambda x. t_y) \pi.1 \pi.2 \\ x_y & := \lambda \pi. \emptyset \text{ if } x \neq y & (t u)^\bullet & := (t^\bullet.1) u^\bullet \end{array}$$

$$(t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \circledast ((t^\bullet.2) \pi u^\bullet \gg= u_y)$$

Flashback: Differential λ -calculus [Ehrhard, Regnier 04]

Inspired by denotational models of Linear Logic in vector spaces of sequences, it introduces a differentiation of λ -terms.

$D(\lambda x.t)$ is the **linearization** of $\lambda x.t$, it substitute x linearly, and then it remains a term t' where x is free.

Syntax:

$$\begin{aligned}\Lambda^d : S, T, U, V &::= 0 \mid s \mid s + T \\ \Lambda^s : s, t, u, v &::= x \mid \lambda x.s \mid sT \mid \mathbf{D}s \cdot t\end{aligned}$$

Operational Semantics:

$$\begin{aligned}(\lambda x.s)T &\rightarrow_{\beta} s[T/x] \\ \mathbf{D}(\lambda x.s) \cdot t &\rightarrow_{\beta_D} \lambda x. \frac{\partial s}{\partial x} \cdot t\end{aligned}$$

where $\frac{\partial s}{\partial x} \cdot t$ is the **linear substitution** of x by t in s .

The linear substitution ...

... which is not exactly a substitution

$$\frac{\partial y}{\partial x} \cdot t = \begin{cases} t & \text{if } x = y \\ 0 & \text{otherwise} \end{cases}$$

$$\frac{\partial}{\partial x}(tu) \cdot s = \left(\frac{\partial t}{\partial x} \cdot s\right)u + (Dt \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

$$\frac{\partial}{\partial x}(\lambda y.s) \cdot t = \lambda y. \frac{\partial s}{\partial x} \cdot t$$

$$\frac{\partial}{\partial x}(Ds \cdot u) \cdot t = D\left(\frac{\partial s}{\partial x} \cdot t\right) \cdot u + Ds \cdot \left(\frac{\partial u}{\partial x} \cdot t\right)$$

$$\frac{\partial 0}{\partial x} \cdot t = 0$$

$$\frac{\partial}{\partial x}(s + u) \cdot t = \frac{\partial s}{\partial x} \cdot t + \frac{\partial u}{\partial x} \cdot t$$

$\frac{\partial s}{\partial x} \cdot t$ represents s where x is linearly (i.e. one time) substituted by t .

The linear substitution ...

The computational Dialectica

$$\frac{\partial y}{\partial x} \cdot t = \begin{cases} t & \text{if } x = y \\ 0 & \text{otherwise} \end{cases}$$

$$\frac{\partial}{\partial x}(tu) \cdot s = \left(\frac{\partial t}{\partial x} \cdot s\right)u + (Dt \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

$$x_y \cdot \pi = \begin{cases} \pi & \text{if } x = y \\ \emptyset & \text{otherwise} \end{cases}$$

$$(t \ u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \circ ((t^\bullet.2) \pi u^\bullet \ggg u_y)$$

$$\frac{\partial}{\partial x}(\lambda y. s) \cdot t = \lambda y. \frac{\partial s}{\partial x} \cdot t$$

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Tracking differentiation in Dialectica

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That's reverse differentiation

- ▶ $(-)^\bullet$ obeys the chain rule, $(-)^\bullet$ is the functorial differentiation.
- ▶ t_x is contravariant in x , representing a reverse linear substitution.

Tracking differentiation in Dialectica

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Theorem [K. Pédrot 22]

$$\llbracket u \gg= t_x[\Gamma \leftarrow \overrightarrow{r}^\bullet] \rrbracket \equiv_{\beta, \eta} \lambda z. (\llbracket u \rrbracket ((\partial x. t[\Gamma \leftarrow \overrightarrow{r}^\bullet])z))$$

A Linear Logic Refinement

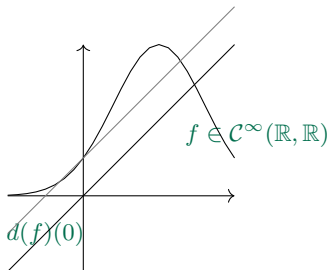
Differential Linear Logic

$$\frac{\vdash \ell : A \multimap B}{\vdash \ell : !A \multimap B} \textcolor{red}{d}$$

A linear proof
is in particular non-linear.

$$\frac{\vdash f : !A \multimap B}{\vdash D_0 f : A \multimap B} \textcolor{red}{\bar{d}}$$

*From a non-linear proof
we can extract a linear proof*



Differential interaction nets, Ehrhard and Regnier, TCS (2006)

Exponential rules of Differential Linear Logic

$$\frac{\vdash \Gamma}{\vdash \Gamma, \textcolor{red}{cst}_1 : ?A} w$$

$$\frac{\vdash \Gamma, \textcolor{red}{f} : ?A, \textcolor{red}{g} : ?A}{\vdash \Gamma, f.g : ?A} c$$

$$\frac{\vdash \Gamma, \textcolor{red}{\ell} : A}{\vdash \Gamma, \textcolor{red}{\ell} : ?A} d$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, \textcolor{red}{\delta}_0 : !A} \bar{w}$$

$$\frac{\vdash \Gamma, \textcolor{red}{\phi} : !A \quad \vdash \Delta, \textcolor{red}{\psi} : !A}{\vdash \Gamma, \Delta, \textcolor{red}{\psi} * \textcolor{red}{\phi} : !A} \bar{c}$$

$$\frac{\vdash \Gamma, \textcolor{red}{x} : A}{\vdash \Gamma, D_0(-)(\textcolor{red}{x}) : !A} \bar{d}$$

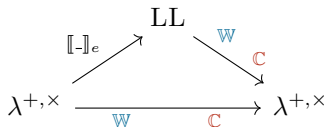
$$\frac{?\Gamma \vdash \textcolor{red}{x} : A}{?\Gamma \vdash \textcolor{red}{\delta}_x : !A} p$$

Dialectica factorizes through Linear Logic

The call by name arrow

$$A \Rightarrow B := !A \multimap B := (!A)^\perp \otimes B$$

$$\begin{array}{llll} \mathbb{W}(A^\perp) & := & \mathbb{C}(A) & \mathbb{C}(A^\perp) & := & \mathbb{W}(A) \\ \mathbb{W}(A \oplus B) & := & \mathbb{W}(A) + \mathbb{W}(B) & \mathbb{C}(A \oplus B) & := & \mathbb{C}(A) \times \mathbb{C}(B) \\ \mathbb{W}(!A) & := & \mathbb{W}(A) & \mathbb{C}(!A) & := & \mathbb{W}(A) \Rightarrow \mathbb{C}(A) \\ \\ \mathbb{W}(A \otimes B) & := & \mathbb{W}(A) \times \mathbb{W}(B) & & & \\ \mathbb{C}(A \otimes B) & := & (\mathbb{W}(A) \Rightarrow \mathbb{C}(B)) \times (\mathbb{W}(B) \Rightarrow \mathbb{C}(A)) & & & \end{array}$$



Valeria de Paiva, 1989, A dialectica-like model of linear logic.

Dialectica factorizes through Differential Linear Logic

Witnesses are functorial reverse derivative

$$\mathbb{W}(A \Rightarrow B) = (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \times (\mathbb{W}(A) \Rightarrow \mathbb{C}(B) \Rightarrow \mathbb{C}(A))$$

$$\begin{aligned}\mathbb{W}(!A) &:= !\mathbb{W}(A) & \mathbb{C}(!A) &:= !\mathbb{W}(A) \multimap \mathbb{C}(A) \\ \mathbb{W}(A \otimes B) &:= \mathbb{W}(A) \otimes \mathbb{W}(B) \\ \mathbb{C}(A \otimes B) &:= (\mathbb{W}(A) \multimap \mathbb{C}(B)) \oplus (\mathbb{W}(B) \multimap \mathbb{C}(A)) \\ \mathbb{W}(A \multimap B) &:= (\mathbb{W}(A) \multimap \mathbb{W}(B)) \& (\mathbb{C}(B) \multimap \mathbb{C}(A)) \\ \mathbb{C}(A \multimap B) &:= \mathbb{W}(A) \otimes \mathbb{C}(B)\end{aligned}$$

If $\Gamma \vdash A$ in LL, then $\mathbb{W}(\Gamma) \vdash \mathbb{W}(A)$ in classical DiLL.

$$\frac{\frac{\frac{}{\vdash A, A^\perp} \text{ax}}{\vdash A, !A^\perp} \bar{d}}{\vdash ?A, A, !A^\perp} \bar{c} \quad \frac{\frac{}{\vdash ?A, !A^\perp} \text{ax}}{\vdash ?A, A, !A^\perp} \bar{c} \quad \frac{\frac{}{\Gamma \vdash ?A} \pi}{\Gamma \vdash ?A, A} \text{cut}$$

Dialectica factorizes through Differential Linear Logic

The economical translation

$$\llbracket A \Rightarrow B \rrbracket_e := !A \multimap B$$

$$\llbracket A \times B \rrbracket_e := A \& B$$

$$\llbracket A + B \rrbracket_e := A \oplus B$$

$$\begin{array}{ccc} \text{ILL} & \xrightarrow[\text{C}]{\text{W}} & \text{IDiLL} \\ \llbracket - \rrbracket_e \uparrow & & \downarrow \dots \\ \lambda^{+, \times} & \xrightarrow[\text{C}]{\text{W}} & \lambda^{+, \times} \end{array}$$

IDILL : Intuitionnistic Differential Linear Logic ? Oh no ...

Dialectica is differentiation in categories

What's categorical differentiation ?

To cook a good differential category, one needs :

- ▶ A category of regular/continuous/non-linear functions

$$\mathbb{C}(A, B) = !A \multimap B .$$

- ▶ A category of linear functions, in which differentiation embeds

$$\mathcal{L}(A, B) = A \multimap B .$$

- ▶ Something which linearizes :

$$\bar{d} : A \rightarrow !A$$

- ▶ A notion of duality, if one wants to encode reverse. differentiation.

\rightsquigarrow Basically, one wants a categorical model of DiLL.

Dialectica categories

Categories representing specific relations

Consider a category \mathcal{C} . $\mathbf{Dial}(\mathcal{C})$ is constructed as follows:

- Objects : relations $\alpha \subseteq U \times X$, $\beta \subseteq V \times Y$.
- Maps from α to β :

$$(f : U \rightarrow V, F : U \times Y \rightarrow X)$$

- Composition : the chain rule !

Consider

$$\begin{array}{lcl} (f, F) : \alpha \subseteq (A, X) & \rightarrow & \beta \subseteq (B, Y) \\ \text{and } (g, G) : \beta \subseteq (B, Y) & \rightarrow & \gamma \subseteq (C, Z) \end{array}$$

two arrows of the Dialectica category. Then their composition is defined as

$$(g, G) \circ (f, F) := (g \circ f, (a, z) \mapsto G(f(a), F(a, z))).$$

Dialectica categories through Differential Categories

In a $*$ -autonomous differential category : from $f : !A \rightarrow B$ one constructs :

$$\overleftarrow{D}(f) \in \mathcal{L}(!A \otimes B^\perp, A^\perp).$$

Dialectica categories factorize through differential categories

If \mathcal{L} is a model of DILL such that $\mathcal{L}_!$ has finite limits:

$$\left\{ \begin{array}{lll} \mathcal{L}_! & \rightarrow & \mathcal{D}(\mathcal{L}_!) \\ A & \mapsto & A \times A^\perp \\ f & \mapsto & (f, \overleftarrow{D}(f)) \end{array} \right.$$

We have an obvious forgetful functor:

$$\mathcal{U} : \left\{ \begin{array}{lll} \mathcal{D}(\mathcal{L}_!) & \rightarrow & \mathcal{L}_! \\ \alpha \subseteq A \times X & \mapsto & A \\ (f, F) & \mapsto & f \end{array} \right.$$

which is left adjoint to \mathcal{R} , forming a reflection on \mathcal{L}_{oc} .

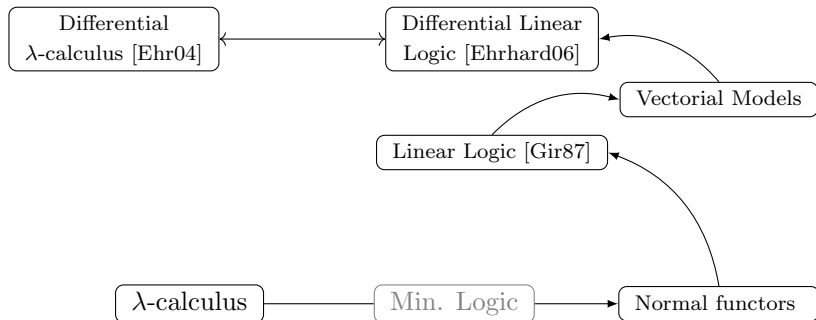
To be declined in reverse/cartesian differential categories...

Recap

Programs	Logic	Semantics
<code>fun (x:A)-> (t:B)</code>	Proof of $A \vdash B$	$f : A \rightarrow B.$
Types	Formulas	Objects
Execution	Cut-elimination	Equality

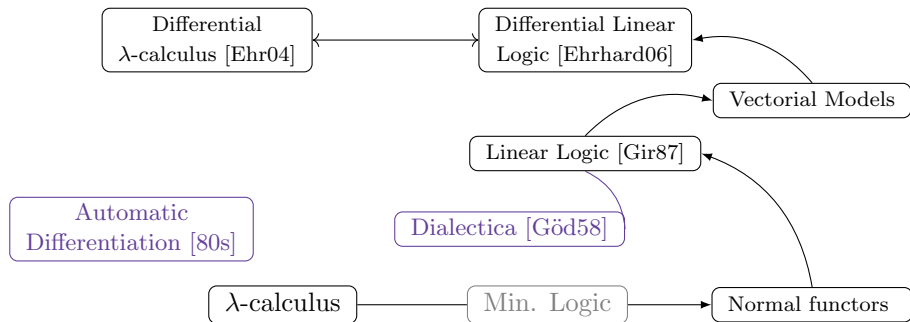
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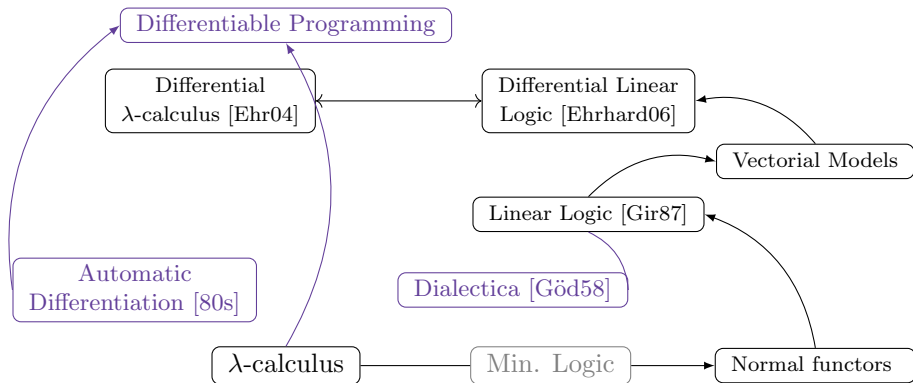
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Recap

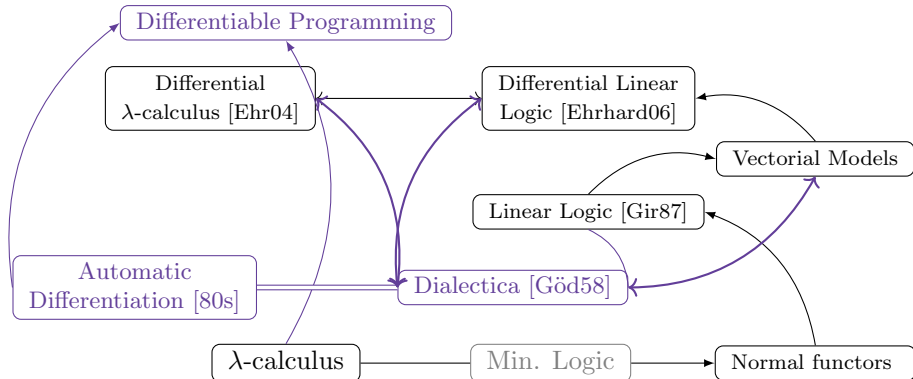
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A good point for logicians : Gödel invented Dialectica 40 years before reverse differentiation was put to light

Recap

Programs	Logic	Semantics
$\text{fun } (x:A) \rightarrow (t:B)$	Proof of $A \vdash B$	$f : A \rightarrow B.$
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Conclusion and applications

Take home message:

Dialectica is functorial reverse differentiation,
extracting ~~intensional~~ local content from proofs.

A new semantical correspondance between computations and mathematics :
~~intentional~~ meaning of program is local behaviour of functions.

Program	Proof	Function
Quantitative	Resources	Linearity
Control	Classical Principles	Differentiation
	Intentional	Local
	Extentional	Global

Related work and applications:

- ▶ Markov's principle and delimited continuations on positive formulas.
- ▶ Proof mining and backpropagation.

Dialectica is differentiation ...

... We knew it already !

The codereliction of differential proof nets: In terms of polarity in linear logic [23], the $\forall \multimap$ -free constraint characterizes the formulas of intuitionistic logic that can be built only from positive connectives (\oplus , \otimes , 0 , 1 , $!$) and the why-not connective (“?”). In this framework, Markov’s principle expresses that from such a $\forall \multimap$ -free formula A (e.g. $? \oplus_x (?A(x) \otimes ?B(x))$) where the presence of “?” indicates that the proof possibly used weakening (efq or throw) or contraction (catch), a linear proof of A purged from the occurrences of its “?” connective can be extracted (meaning for the example above a proof of $\oplus_x (A(x) \otimes B(x))$).

Interestingly, the removal of the “?”, i.e. the steps from $?P$ to P , correspond to applying the codereliction rule of differential proof nets [24].

Differentiation : $(?P = (P \multimap \perp) \Rightarrow \perp) \rightarrow ((P \multimap \perp) \multimap \perp) \equiv P$



Hugo Herbelin, “An intuitionistic logic that proves Markov’s principle”, LICS ’10 .

Differentiation and delimited continuations

Herbelin Lics'10

Markov's principle is proved by allowing **catch** and **throw** operations on hereditary positive formulas.

$$\boxed{\begin{array}{c} \frac{}{a : \neg\neg T \vdash_{\alpha:T} a : \neg\neg T} \text{AXIOM} \quad \frac{\frac{}{b : T \vdash_{\alpha:T} b : T} \text{AXIOM} \quad \frac{}{b : T \vdash_{\alpha:T} \text{throw}_{\alpha} b : \perp} \text{THROW}}{\vdash_{\alpha:T} \lambda b. \text{throw}_{\alpha} b : \neg T} \rightarrow_I \\ \frac{}{a : \neg\neg T \vdash_{\alpha:T} a : \neg\neg T} \text{AXIOM} \quad \frac{}{\vdash_{\alpha:T} \lambda b. \text{throw}_{\alpha} b : \neg T} \rightarrow_E \\ \frac{a : \neg\neg T \vdash_{\alpha:T} a : \neg\neg T \quad a : \neg\neg T \vdash_{\alpha:T} a (\lambda b. \text{throw}_{\alpha} b) : \perp}{a : \neg\neg T \vdash_{\alpha:T} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : T} \perp_E \\ \frac{a : \neg\neg T \vdash_{\alpha:T} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : T}{a : \neg\neg T \vdash \text{catch}_{\alpha} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : T} \text{CATCH} \\ \frac{}{\vdash \lambda a. \text{catch}_{\alpha} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : \neg\neg T \rightarrow T} \rightarrow_I \end{array}}$$

Figure 3. Proof of *MP*

Extracting quantitative information from proofs.

Effective moduli from ineffective uniqueness proofs. An unwinding of
de La Vallée Poussin's proof for Chebycheff approximation*

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Abstract

We consider uniqueness theorems in classical analysis having the form

$$(+) \forall u \in U, v_1, v_2 \in V_u \left(G(u, v_1) = 0 = G(u, v_2) \rightarrow v_1 = v_2 \right),$$

where U, V are complete separable metric spaces, V_u is compact in V and $G : U \times V \rightarrow \mathbb{R}$ is a constructive function.

If $(+)$ is proved by arithmetical means from analytical assumptions

$$(++) \forall x \in X \exists y \in Y_x \forall z \in Z \left(F(x, y, z) = 0 \right)$$

only (where X, Y, Z are complete separable metric spaces, $Y_x \subset Y$ is compact and $F : X \times Y \times Z \rightarrow \mathbb{R}$ constructive), then we can extract from the proof of $(++) \rightarrow (+)$ an effective modulus of uniqueness, i.e.

$$(+++) \forall u \in U, v_1, v_2 \in V_u, k \in \mathbb{N} \left(|G(u, v_1)|, |G(u, v_2)| \leq 2^{-\Phi u k} \rightarrow d_V(v_1, v_2) \leq 2^{-k} \right).$$

Extracting quantitative information from proofs.

$$\forall u, v_1 v_2, \text{Pol}(u, v_1) = \text{Pol}(u, v_2) \rightarrow v_1 = v_2$$

$$\Downarrow$$

$$\forall u, v_1 v_2, \forall \epsilon > 0, \exists \eta > 0, \|G(u, v_1) - G(u, v_2)\| < \eta \rightarrow d_V(v_1, v_2) < \epsilon$$

$$\Downarrow$$

$$\exists \phi, \forall u, k, v_1 v_2, \|G(u, v_1) - G(u, v_2)\| < 2^{-\phi(u, k)} \rightarrow d_V(v_1, v_2) < 2^{-k}.$$

Proof Mining

Markov's principle and the independence of premises are necessary for most of **mathematical analysis proofs** :

Proof mining allows to refine these proofs by taking away these principles as guaranteed by (some variant of) Dialectica's transformation.

Conjecture

Does it differentiate the function $(\epsilon \rightarrow \eta)$ in :

$$\forall u, v_1 v_2, \forall \epsilon > 0, \exists \eta > 0, \|G(u, v_1) - G(u, v_2)\| < \eta \rightarrow d_V(v_1, v_2) < \epsilon$$

?

Is proof mining (based on) [reverse differentiation applied to proofs](#)?

What else can we explain by differentiation ?