

CM 4 Compilation : bottom-up Parsers (LR)

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Parseur LR in motion

The parser only read the names of constructed tokens

On a ST, it only looks at the root label.

Grammar :

$$\langle \text{exp} \rangle ::= \langle \text{exp} \rangle - \langle \text{terme} \rangle$$
$$| \langle \text{terme} \rangle$$
$$\langle \text{terme} \rangle ::= \langle \text{terme} \rangle * \langle \text{fac} \rangle$$
$$| \langle \text{fac} \rangle$$
$$\langle \text{fac} \rangle ::= (\langle \text{exp} \rangle)$$
$$| - \langle \text{fac} \rangle$$
$$| \langle \text{NB} \rangle$$

Reconstructing the tree :

$\langle \text{NB} \rangle$	*	$\langle \text{NB} \rangle$	-	$\langle \text{NB} \rangle$	*	$\langle \text{NB} \rangle$
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3

7

42

0

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Grammar :

$$\begin{aligned} \langle \text{exp} \rangle &::= \langle \text{exp} \rangle - \langle \text{terme} \rangle \\ &\quad | \langle \text{terme} \rangle \\ \langle \text{terme} \rangle &::= \langle \text{terme} \rangle * \langle \text{fac} \rangle \\ &\quad | \langle \text{fac} \rangle \\ \langle \text{fac} \rangle &::= (\langle \text{exp} \rangle) \\ &\quad | - \langle \text{fac} \rangle \\ &\quad | \langle \text{NB} \rangle \end{aligned}$$

Reconstructing the tree :

$\langle \text{fac} \rangle$	*	$\langle \text{NB} \rangle$	-	$\langle \text{NB} \rangle$	*	$\langle \text{NB} \rangle$
$\langle \text{NB} \rangle$		7		42		0
3						

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 $\langle \text{exp} \rangle ::= \langle \text{exp} \rangle - \langle \text{terme} \rangle$   
          |  $\langle \text{terme} \rangle$   
 $\langle \text{terme} \rangle ::= \langle \text{terme} \rangle * \langle \text{fac} \rangle$   
          |  $\langle \text{fac} \rangle$   
 $\langle \text{fac} \rangle ::= (\langle \text{exp} \rangle)$   
          |  $-\langle \text{fac} \rangle$   
          |  $\langle \text{NB} \rangle$ 
```

Reconstructing the tree :

$\langle \text{terme} \rangle$	*	$\langle \text{NB} \rangle$	-	$\langle \text{NB} \rangle$	*	$\langle \text{NB} \rangle$
$\langle \text{fac} \rangle$		7		42		0
$\langle \text{NB} \rangle$						
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$\langle \text{terme} \rangle$	*	$\langle \text{fac} \rangle$	-	$\langle \text{NB} \rangle$	*	$\langle \text{NB} \rangle$
$\langle \text{fac} \rangle$		$\langle \text{NB} \rangle$		42		0
$\langle \text{NB} \rangle$		7				
3						

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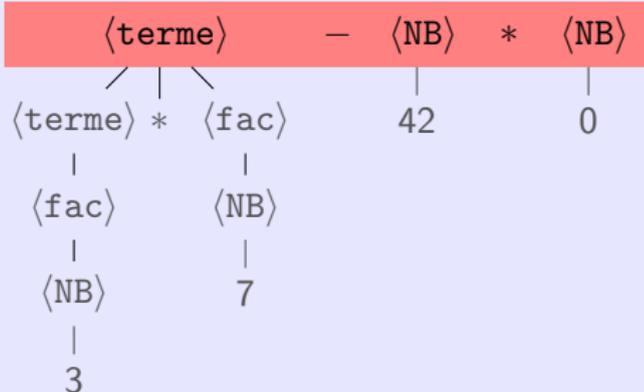
On a ST, it only looks at the root label.

Grammar :

```

<exp> ::= <exp>-<terme>
        | <terme>
<terme> ::= <terme>*<fac>
          | <fac>
<fac> ::= (<exp>)
        | -<fac>
        | <NB>
    
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Reconstructing the tree :



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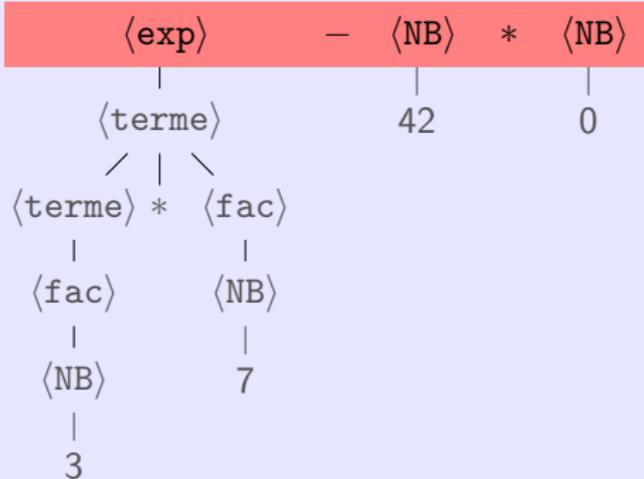
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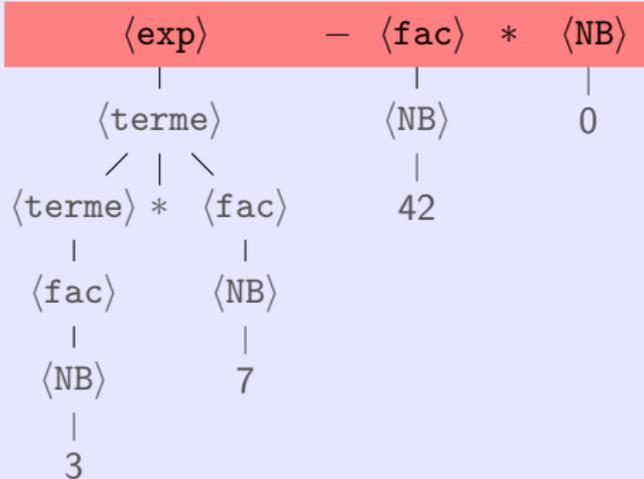
$$\quad \quad \quad | \langle \text{fac} \rangle$$

$$\langle \text{fac} \rangle ::= (\langle \text{exp} \rangle)$$

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Reconstructing the tree :



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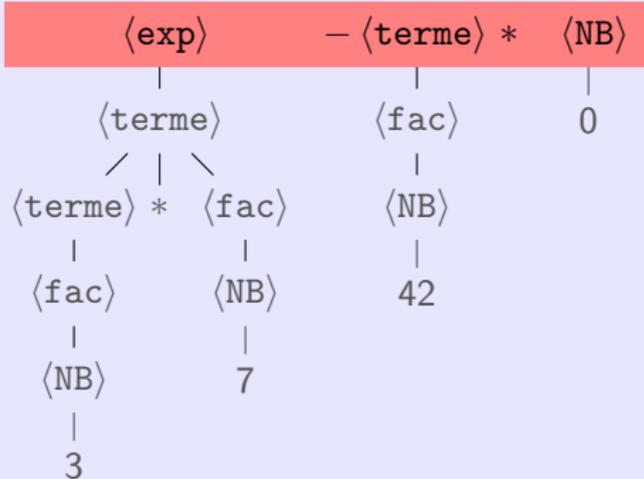
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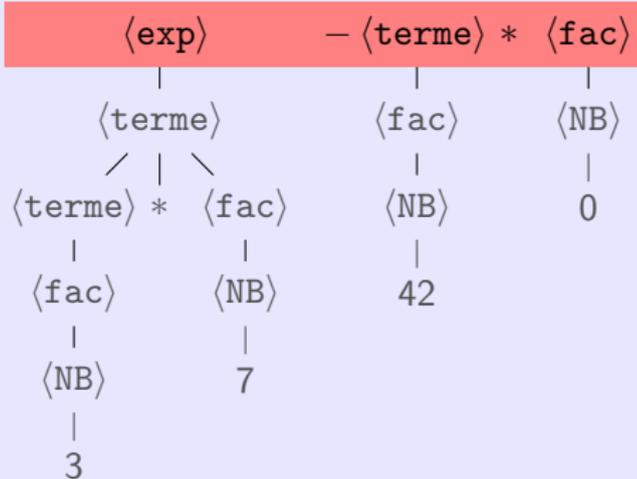
| $\langle \text{fac} \rangle$

$\langle \text{fac} \rangle ::= (\langle \text{exp} \rangle)$

| $- \langle \text{fac} \rangle$

| $\langle \text{NB} \rangle$

Reconstructing the tree :



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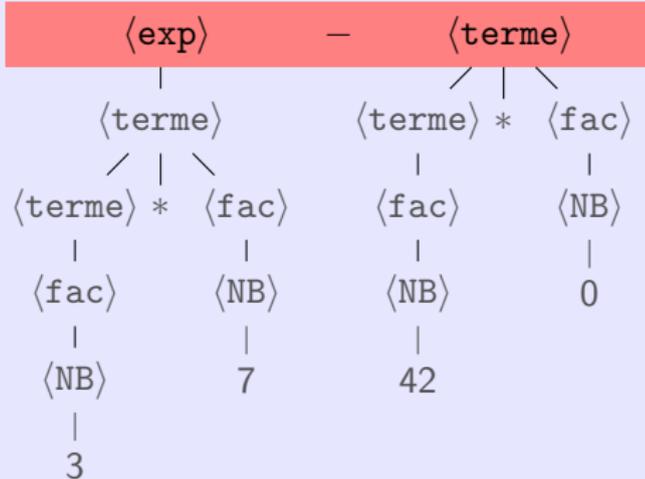
| $\langle \text{fac} \rangle$

$\langle \text{fac} \rangle ::= (\langle \text{exp} \rangle)$

| $-\langle \text{fac} \rangle$

| $\langle \text{NB} \rangle$

Reconstructing the tree :



Parseur LR in motion

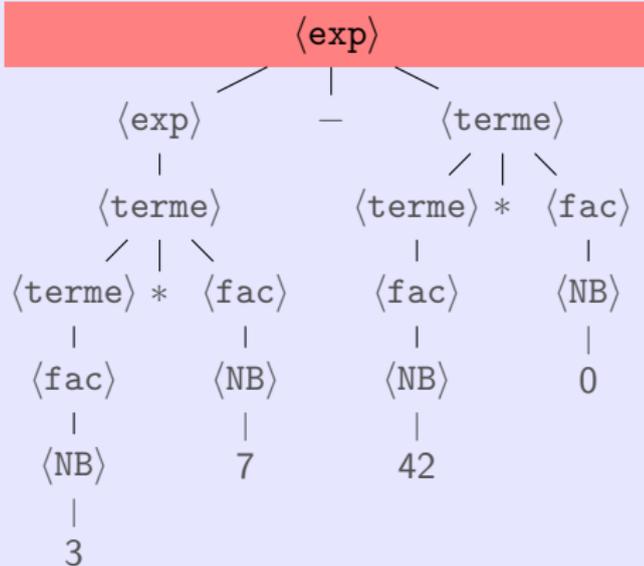
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Reconstructing the tree :



Concept of the non-deterministic parser

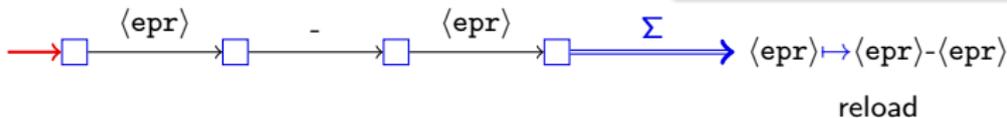
Idea : write a non-deterministic shift-action automaton

Shifts :

- read a word of terminal and non terminals
- look for the pattern of a rule.

Action :

- apply the uncovered rule,
- create a node,
- reload the automaton (beginning).



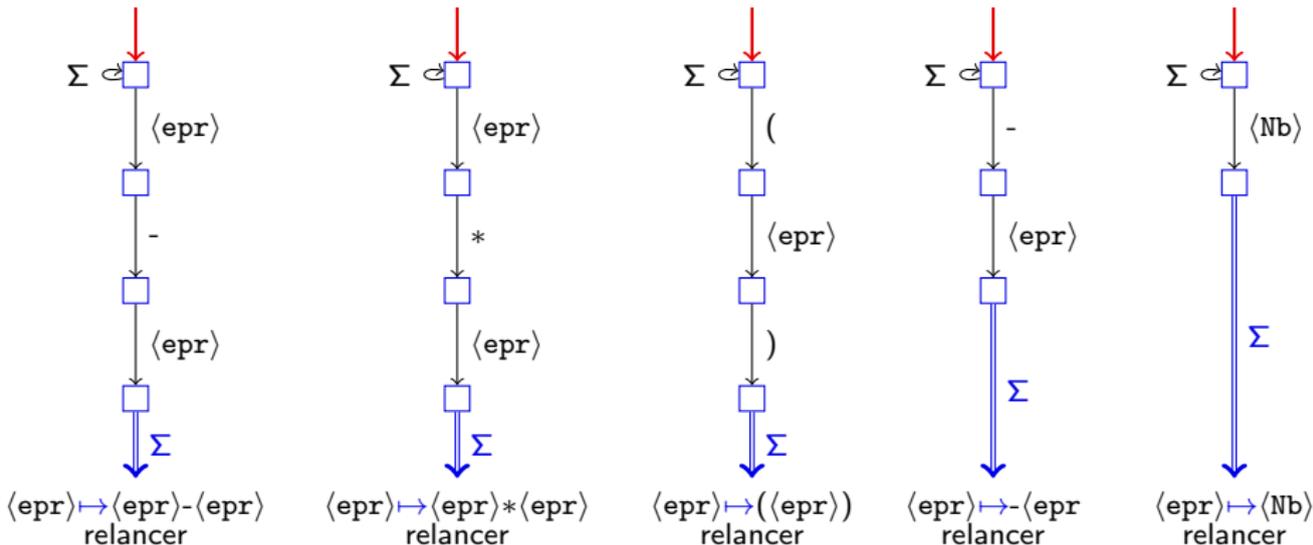
Remark : Σ remplace Char
 $\Sigma = \mathcal{T} \cup \mathcal{N}$ is the set of terminals + non-terminals

First attempt

Idea : Same as for the lexer

- a small automaton for each rule that “test” the pattern,
- preceded by a delaying loop,
- adds actions and takes the sum.

Remark : such an action is called **reduct**

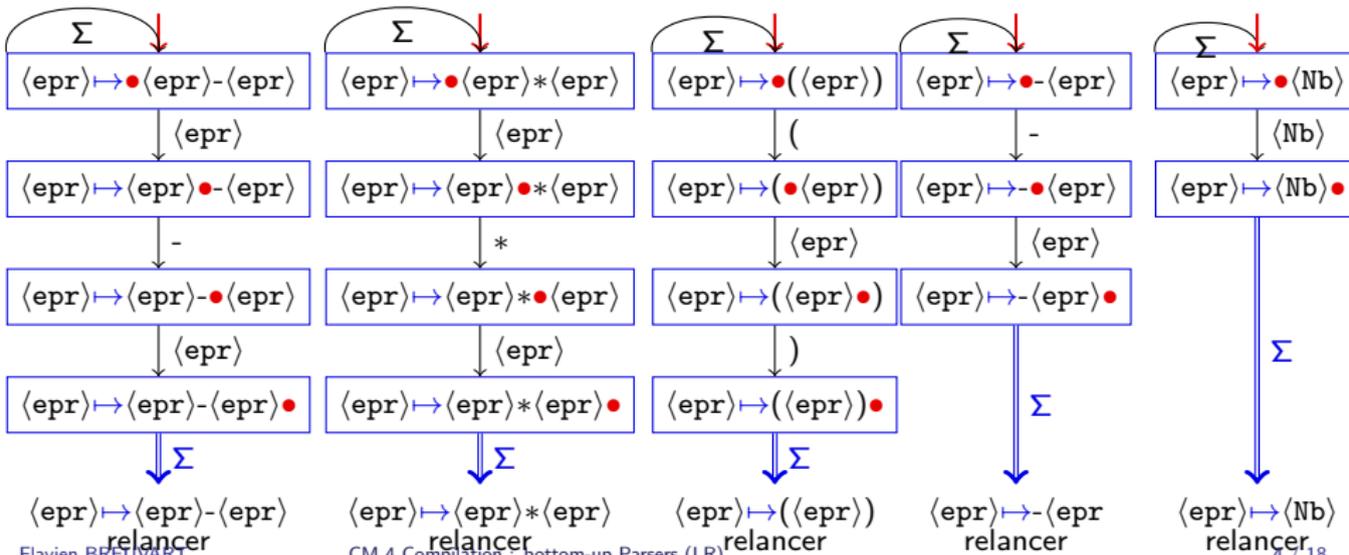


First attempt

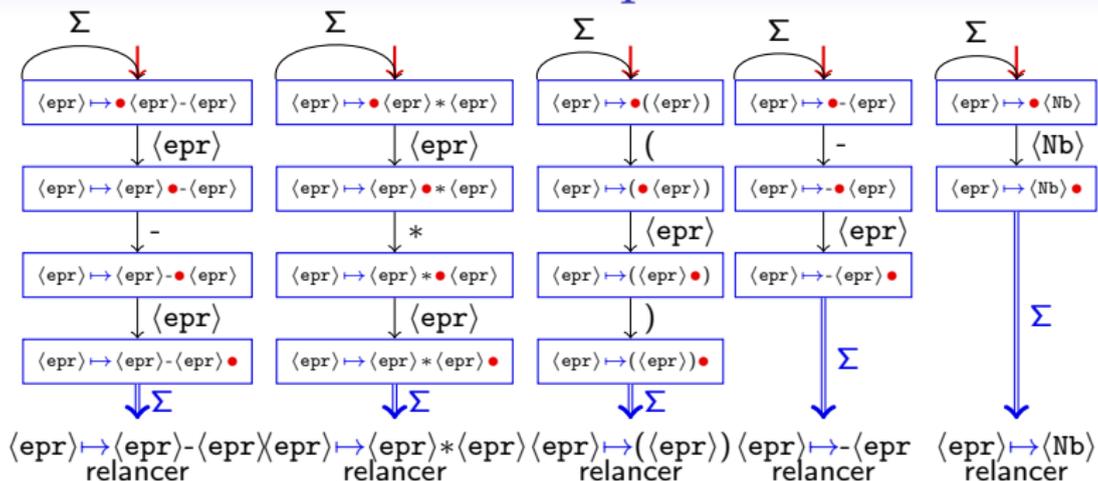
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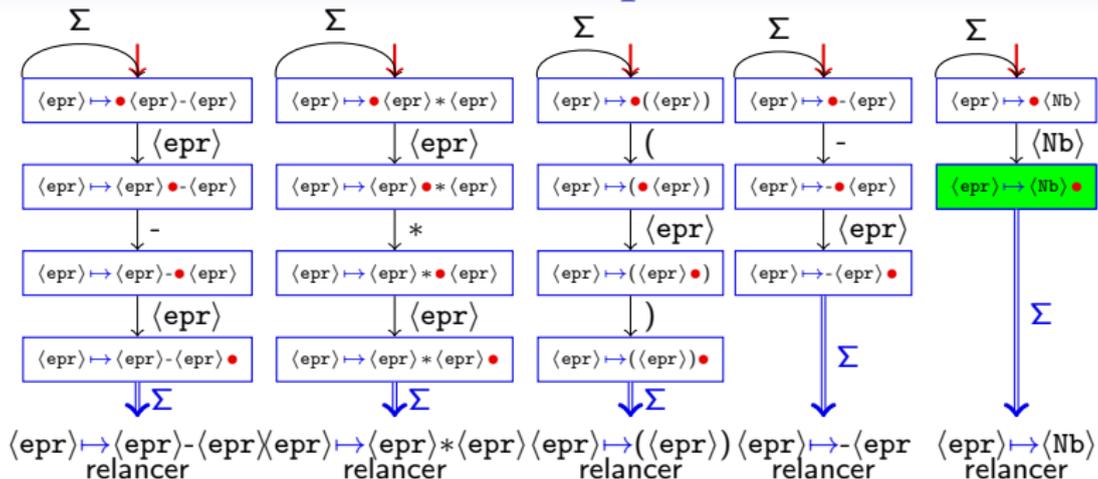


Automaton of the LR parser in motion



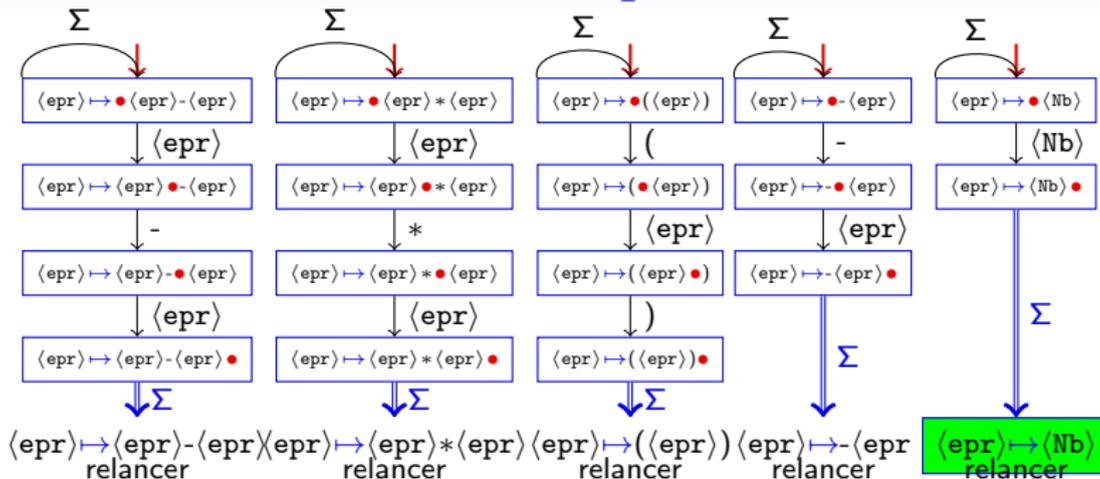
$\langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad - \quad \langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad \$$
 | | | |
 3 7 42 0

Automaton of the LR parser in motion



$\langle NB \rangle$ $*$ $\langle NB \rangle$ $-$ $\langle NB \rangle$ $*$ $\langle NB \rangle$ $\$$
 | | | | |
 3 7 42 0

Automaton of the LR parser in motion

 $\langle \text{expr} \rangle$ $\langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad - \quad \langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad \$$

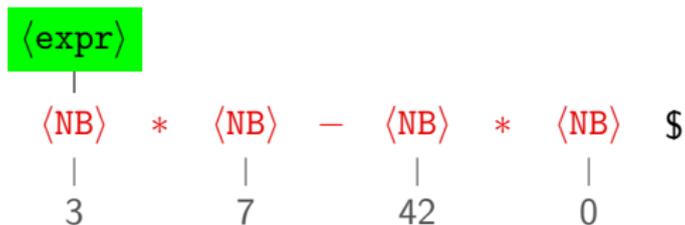
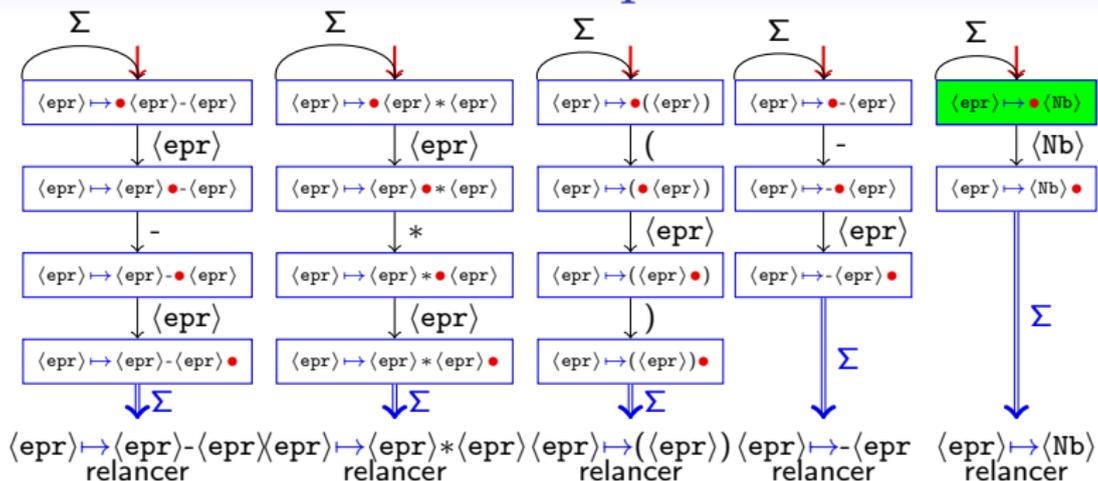
3

7

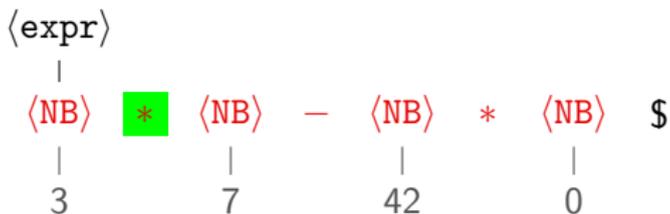
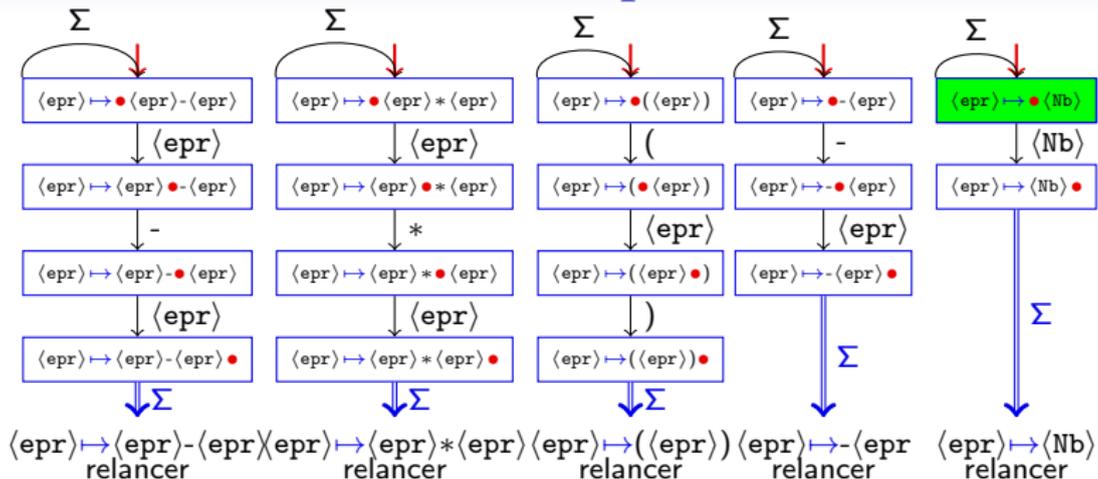
42

0

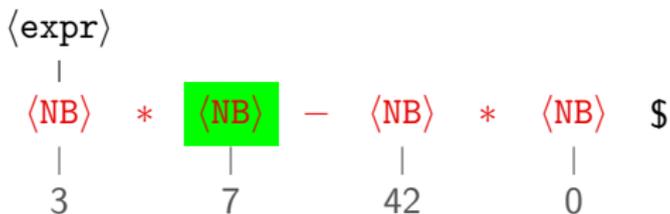
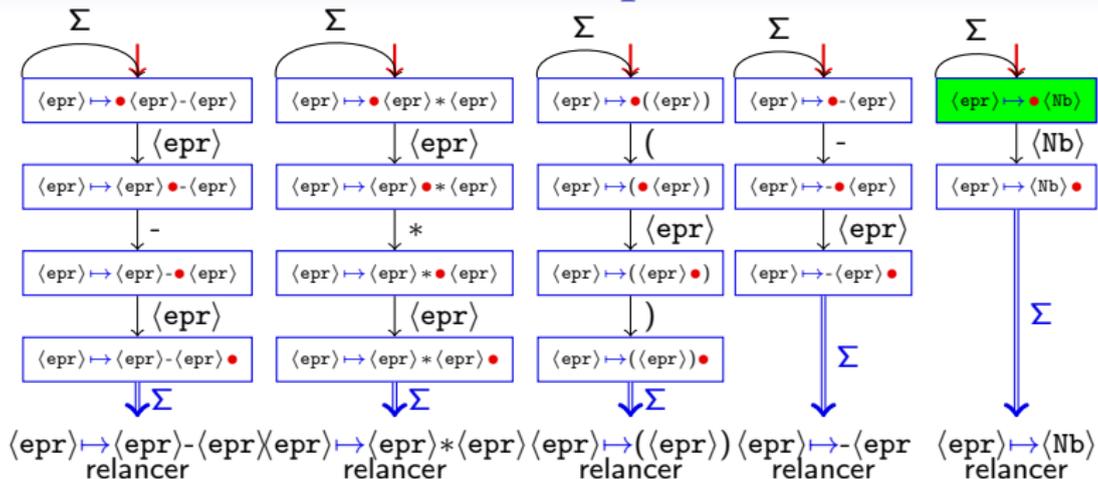
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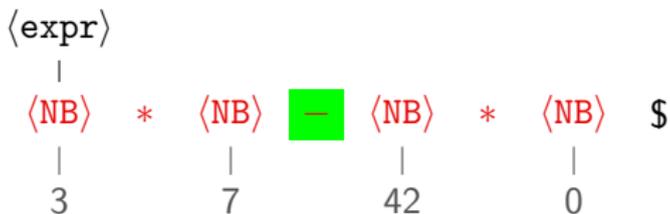
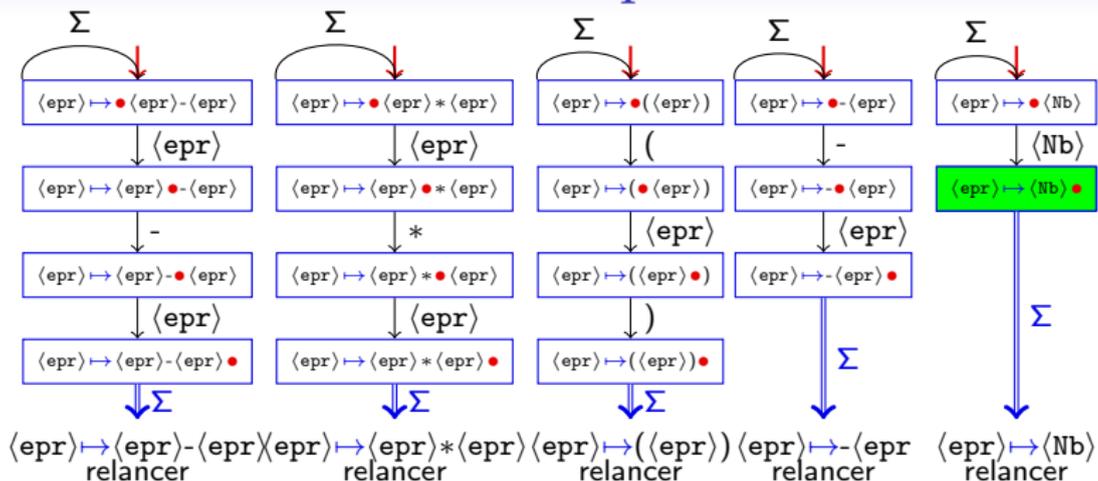
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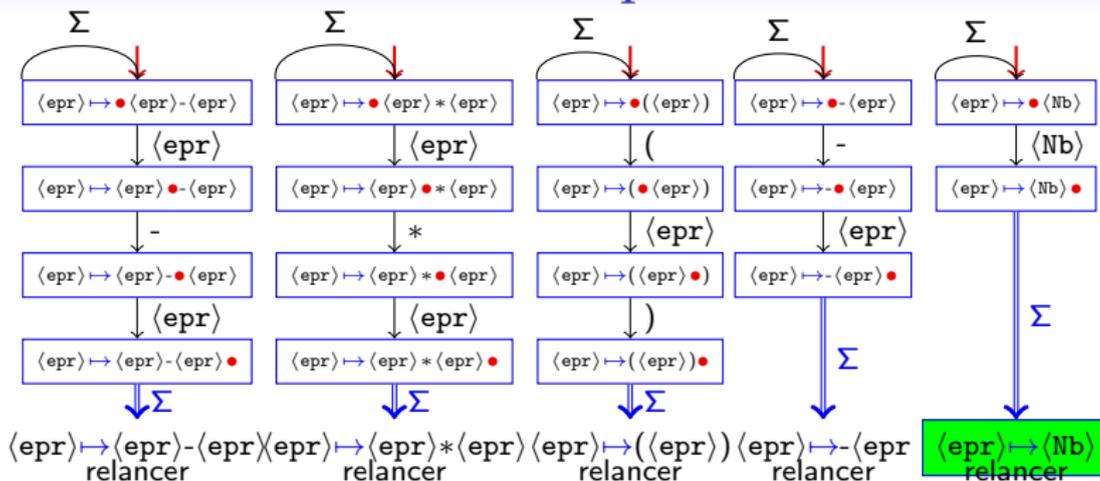
Automaton of the LR parser in motion



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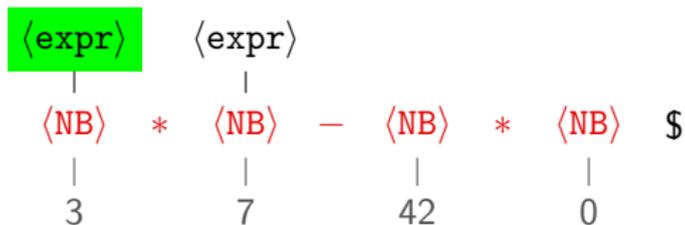
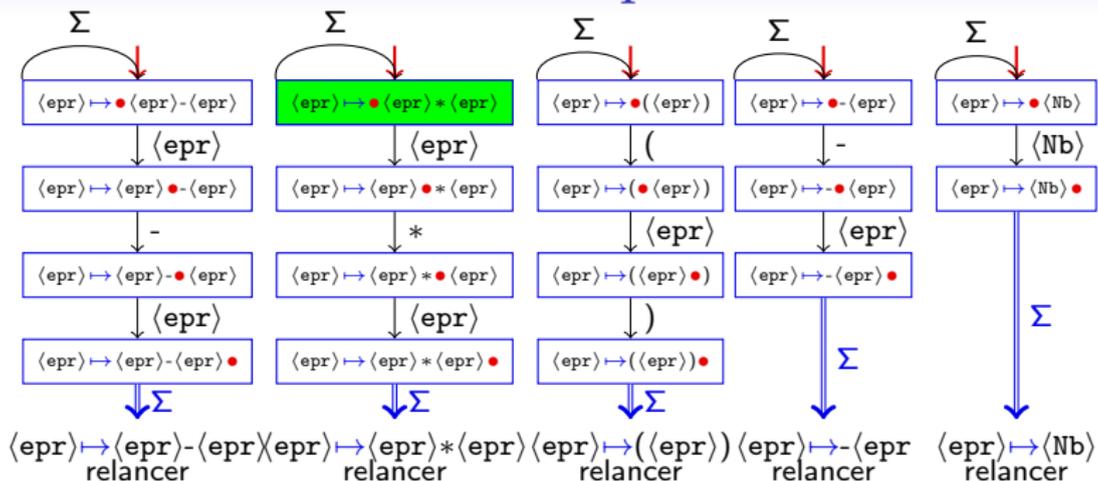


Automaton of the LR parser in motion

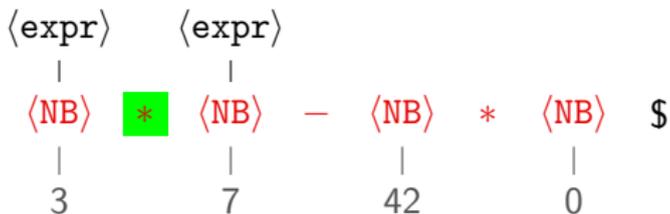
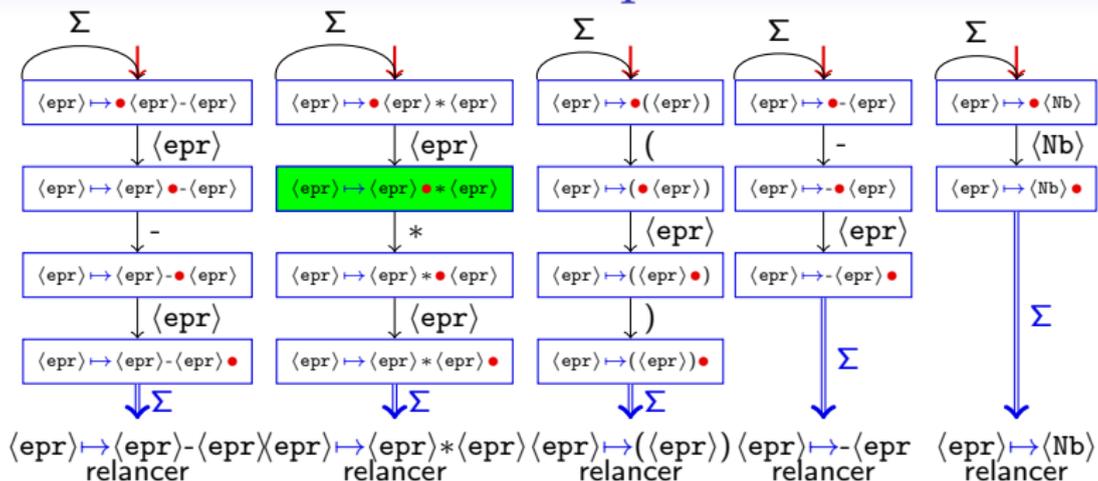


$\langle \text{expr} \rangle$ $\langle \text{expr} \rangle$
 | |
 $\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ - $\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ \$
 | | | |
 3 7 42 0

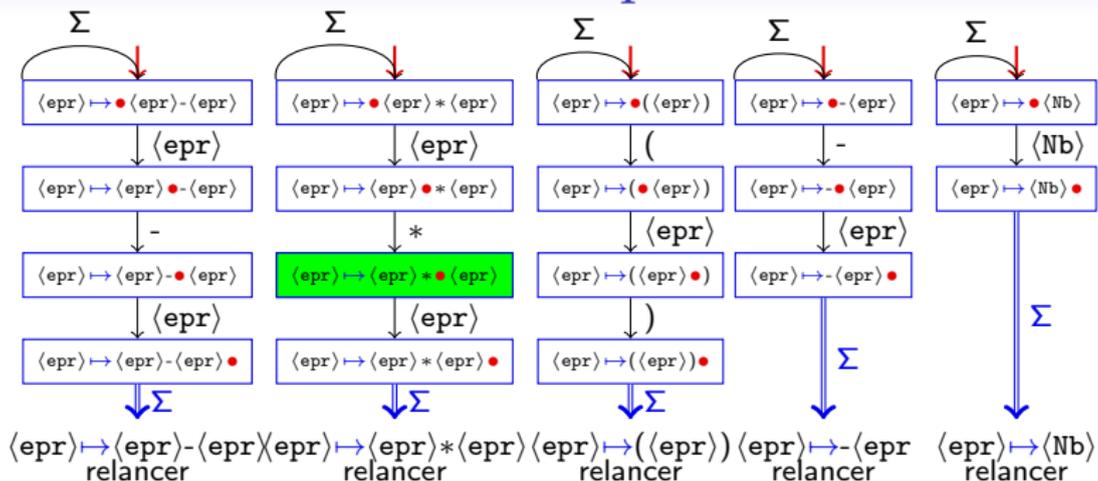
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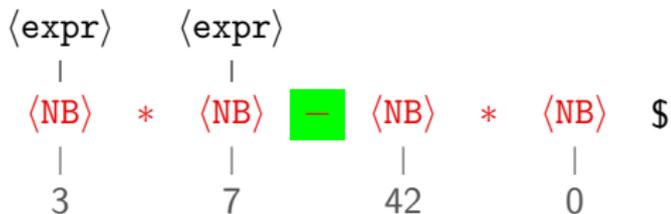
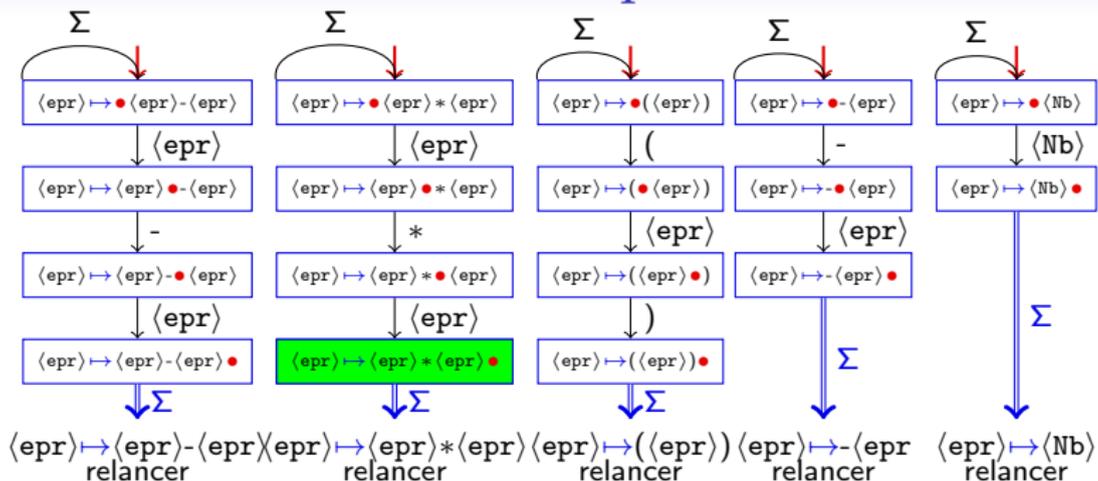
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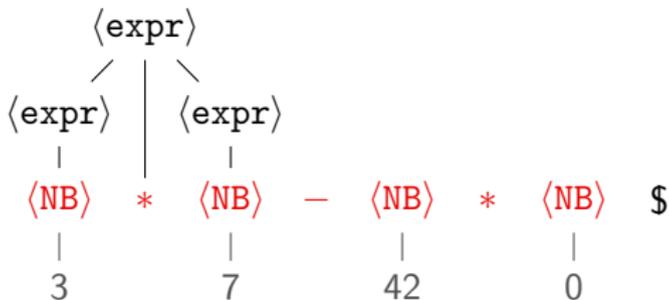
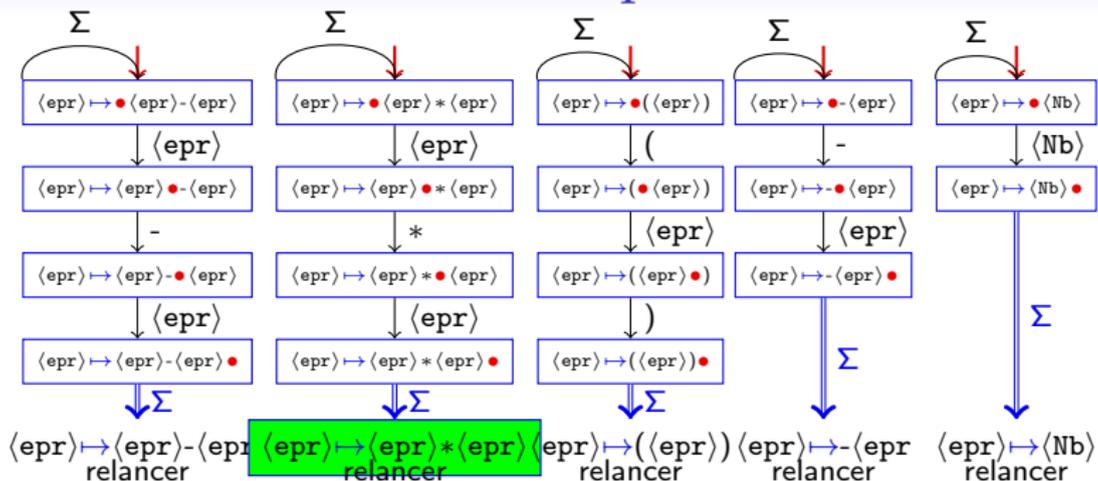
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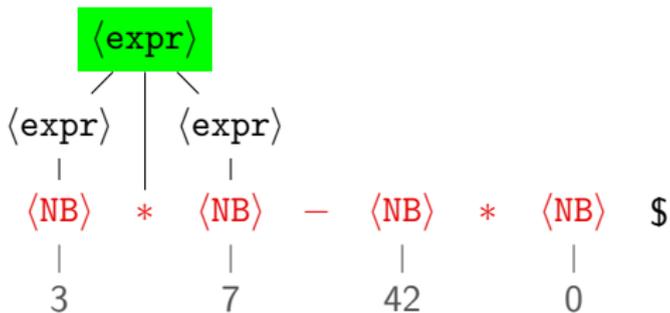
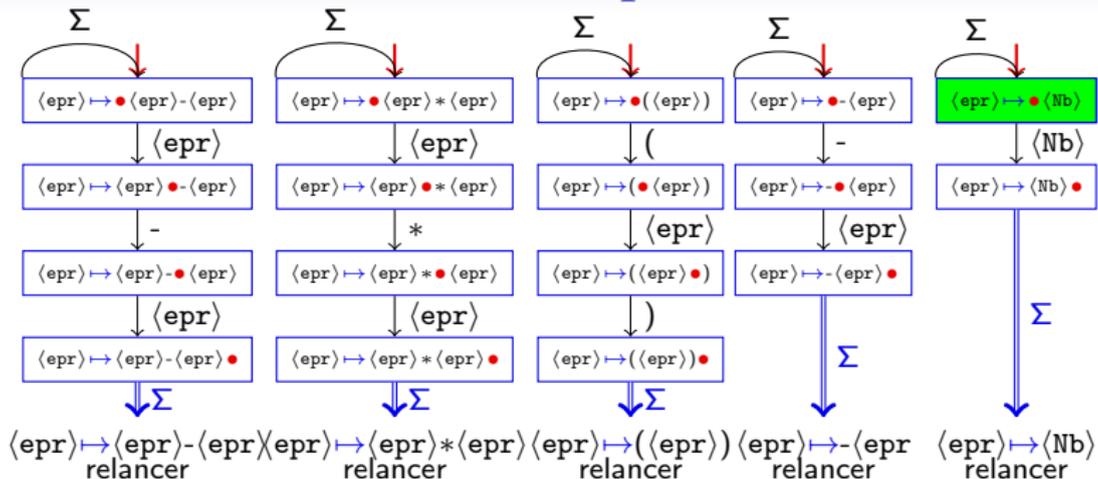
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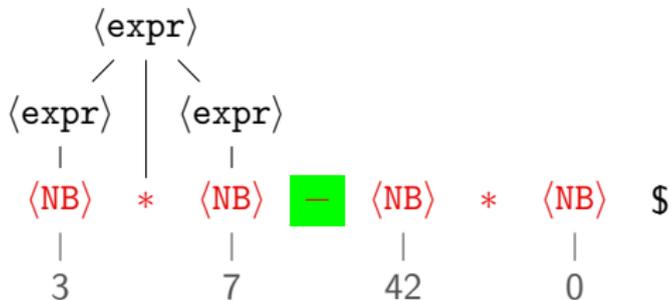
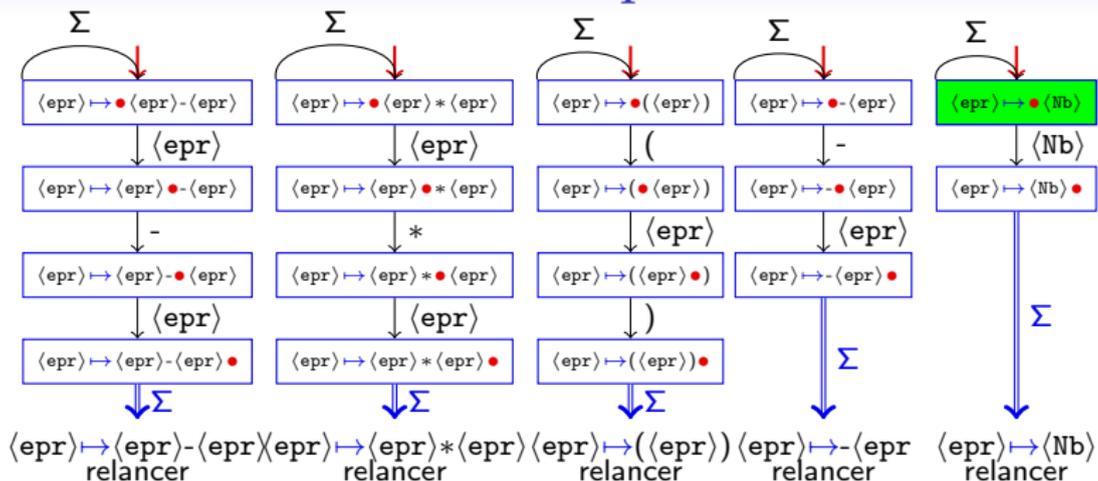
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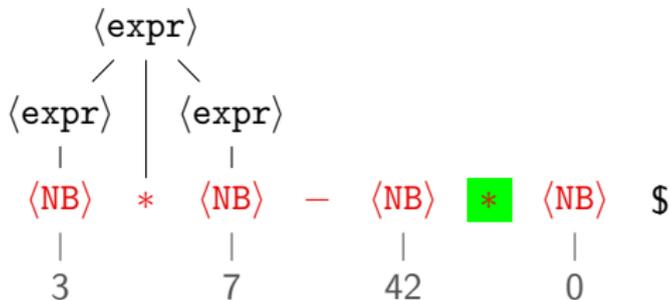
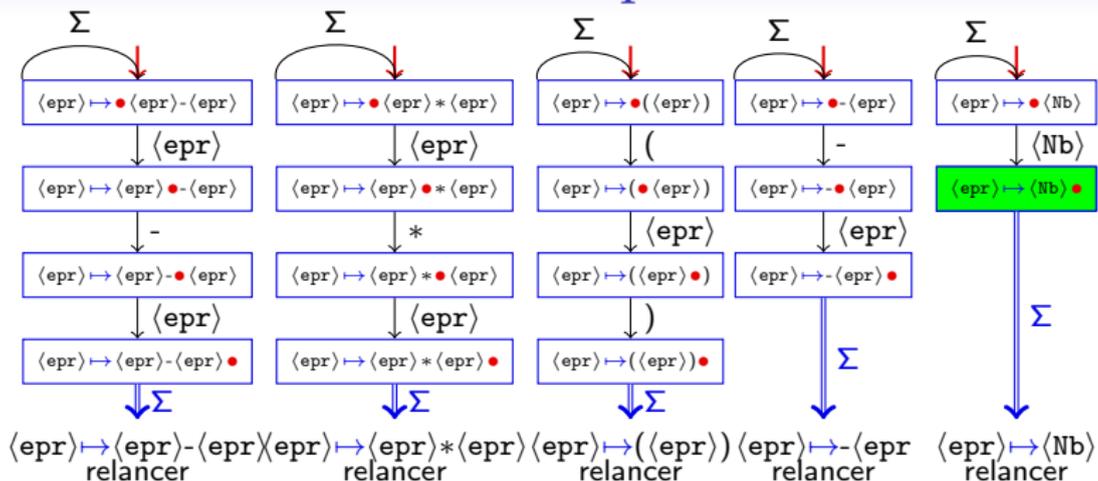
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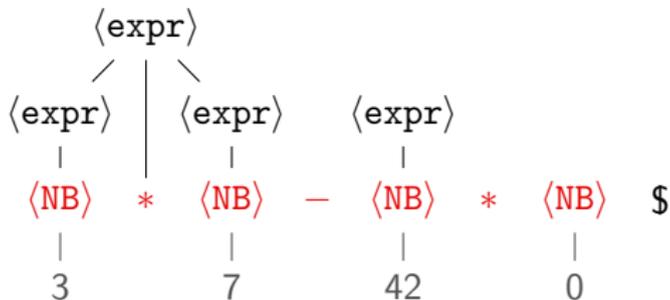
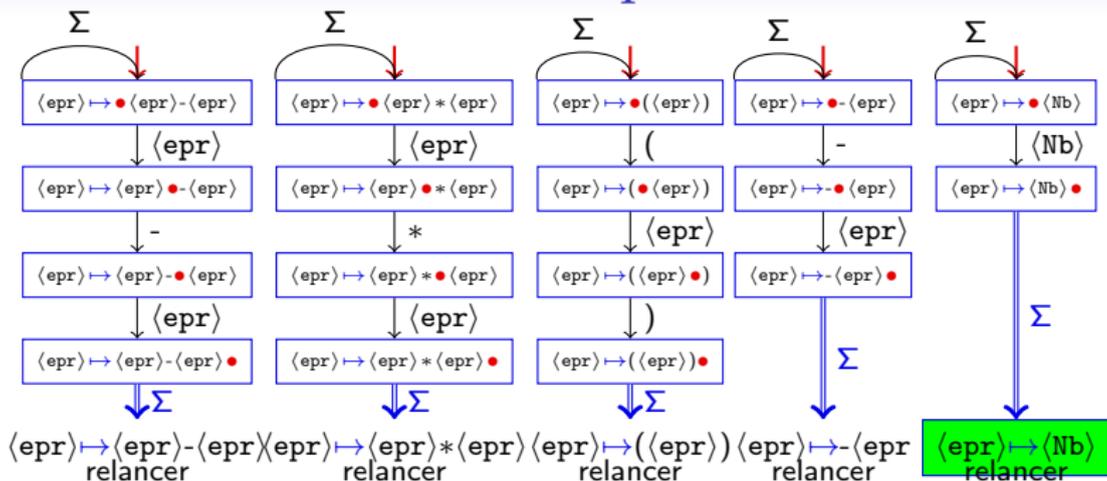
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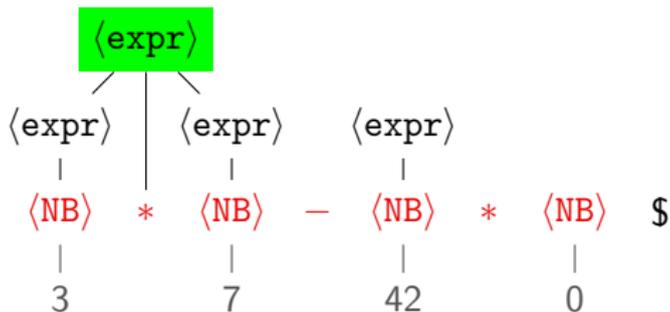
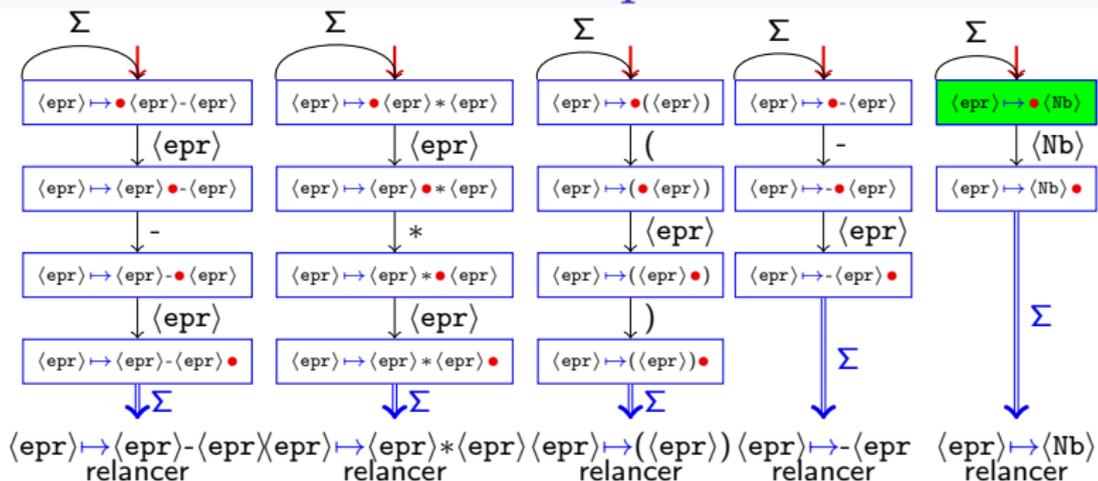
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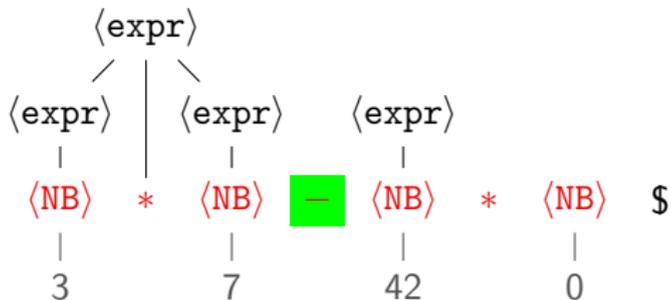
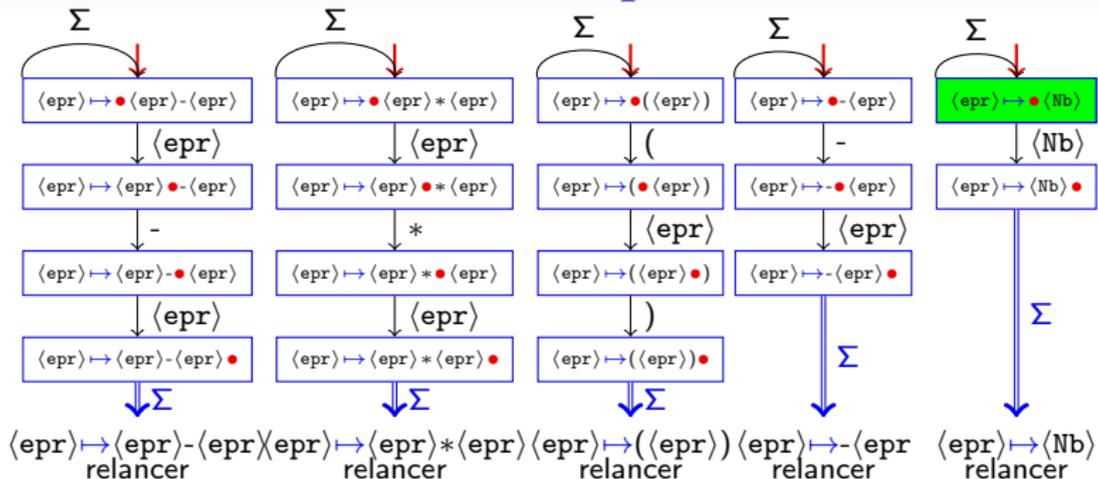
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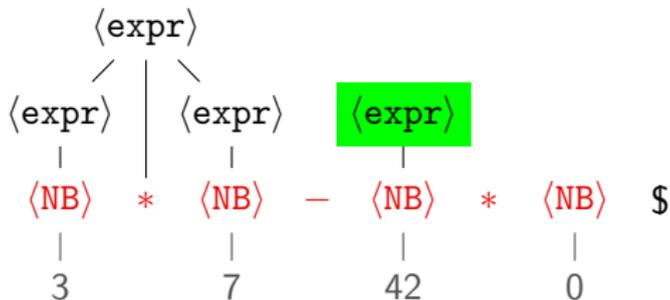
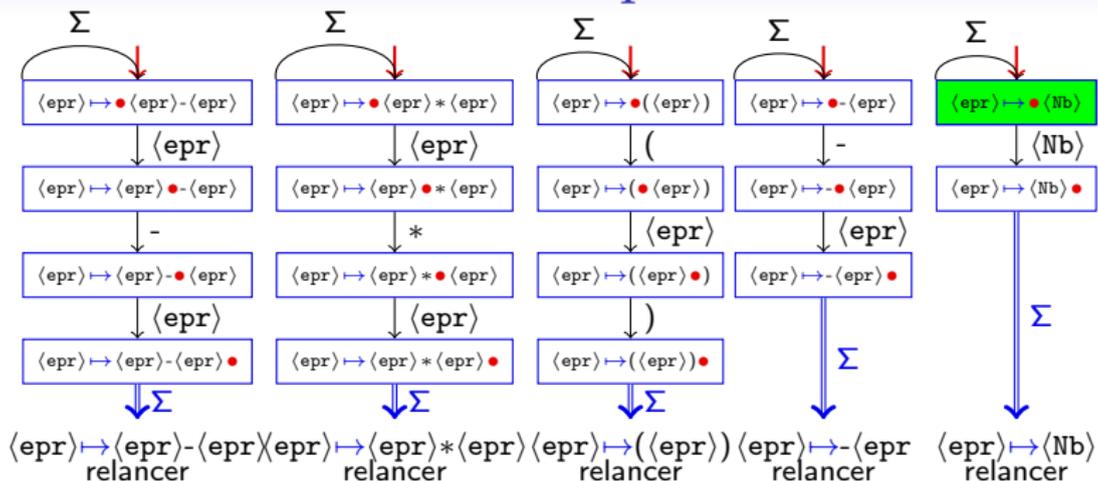
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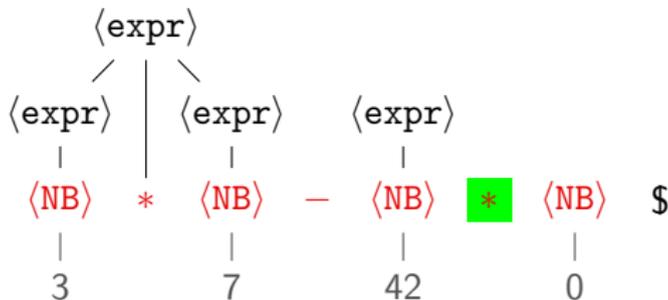
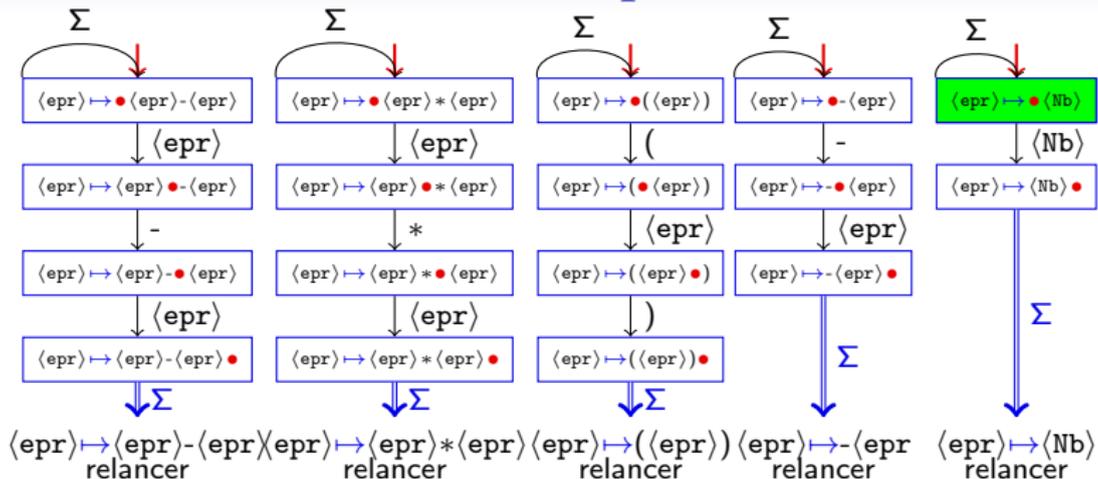
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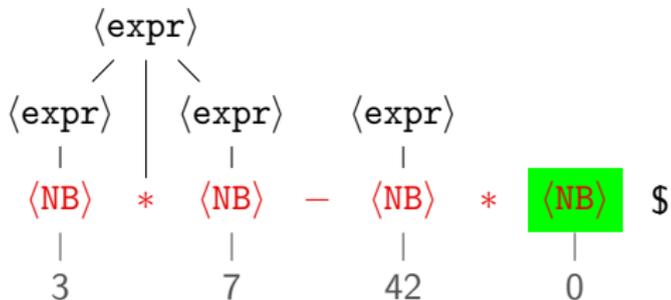
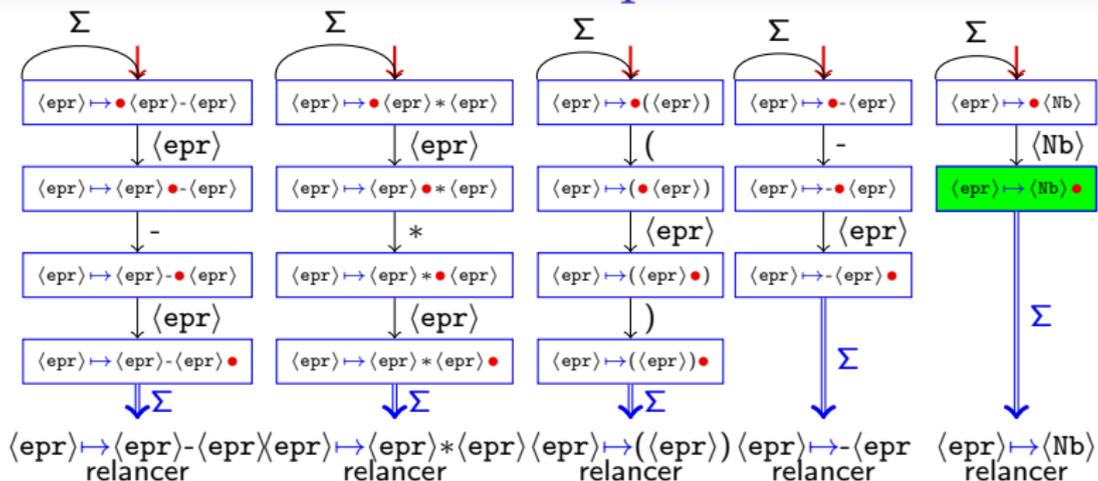
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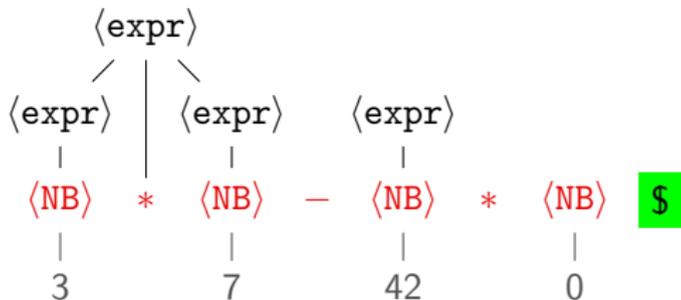
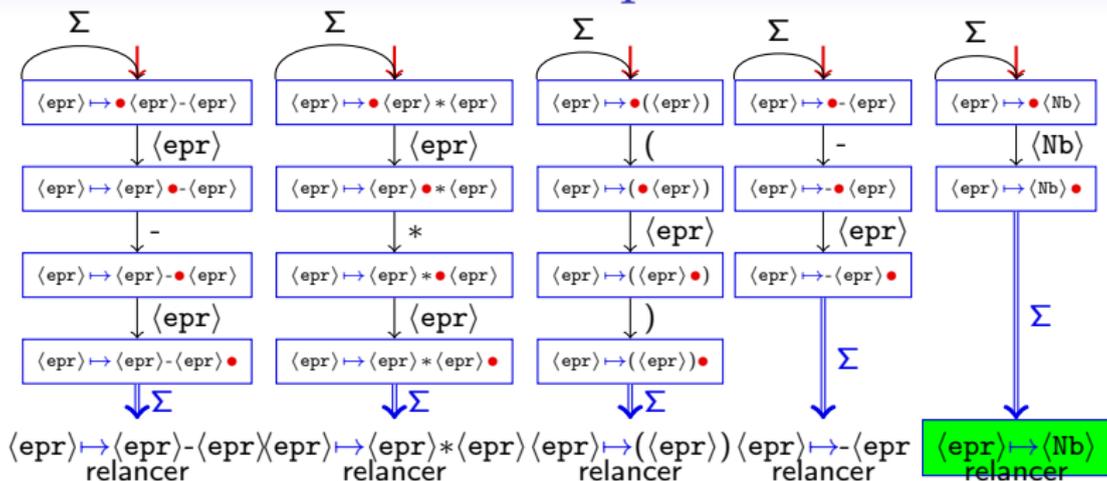
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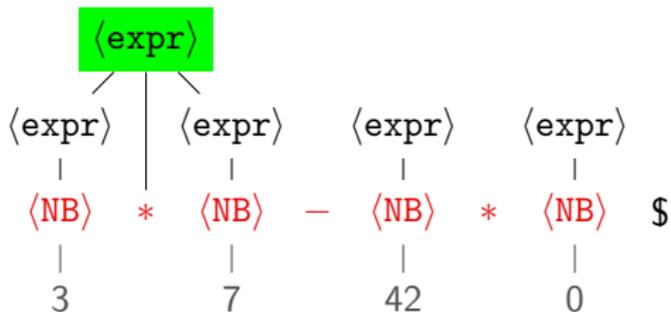
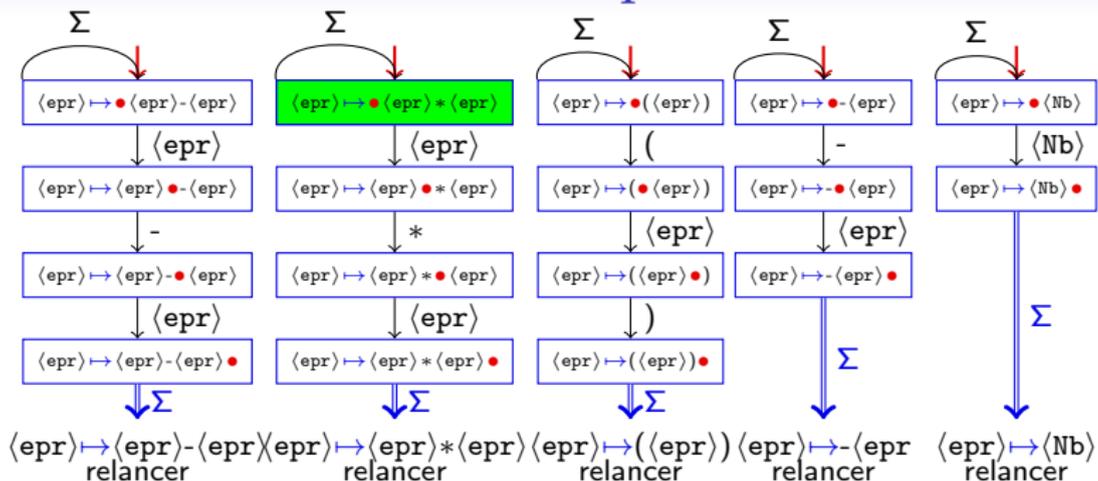
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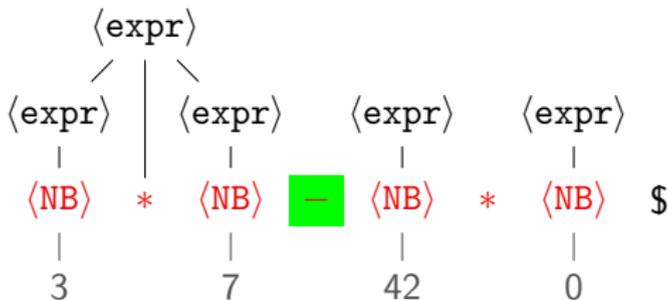
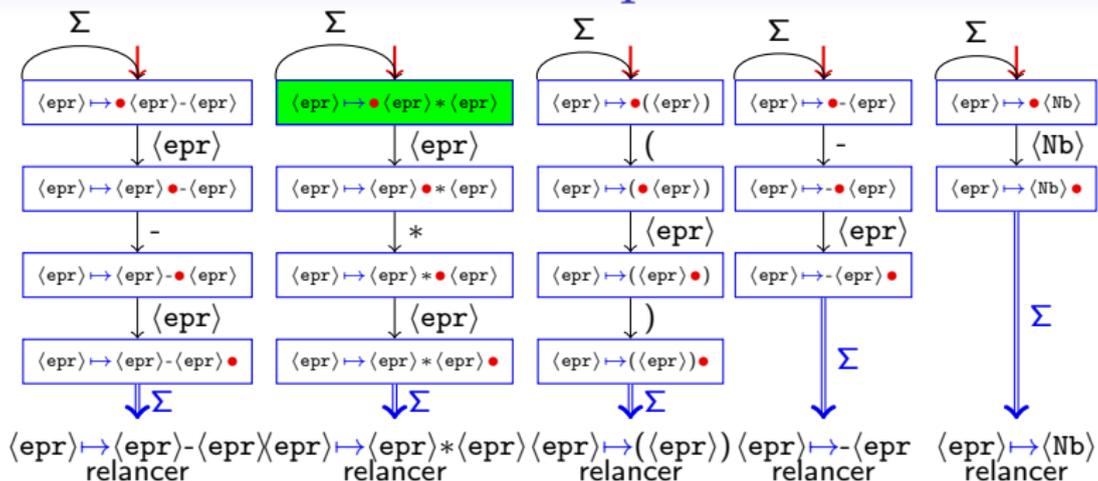
Automaton of the LR parser in motion



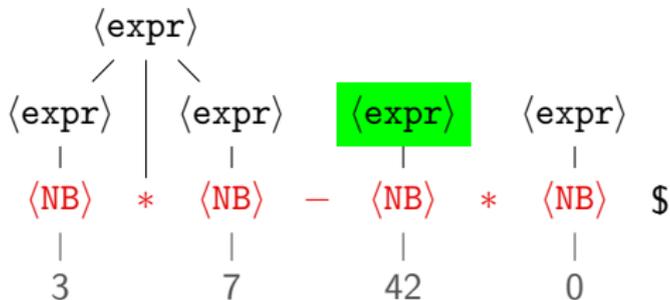
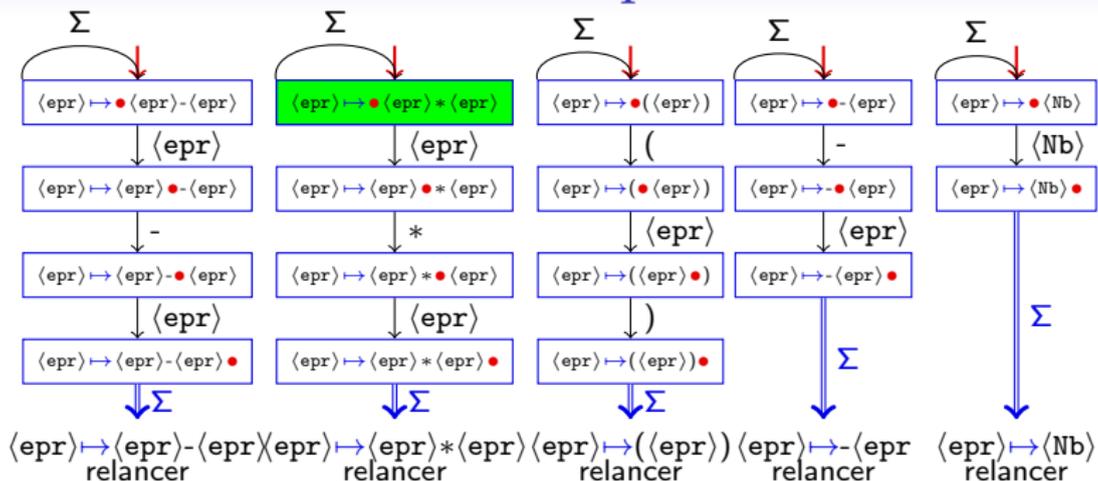
Automaton of the LR parser in motion



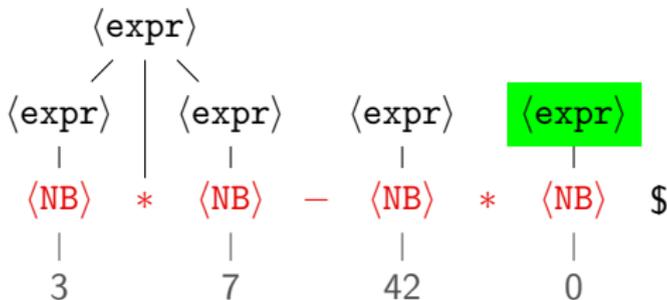
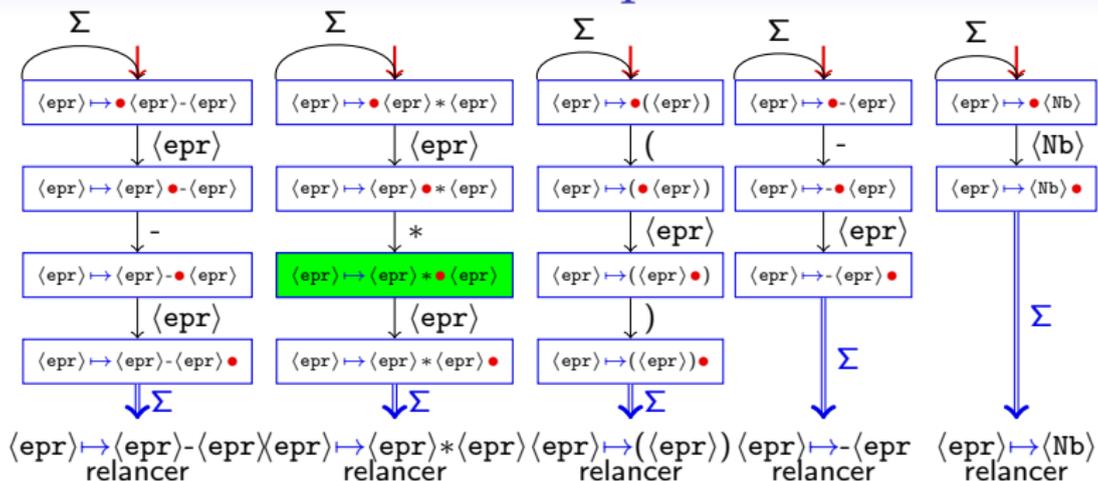
Automaton of the LR parser in motion



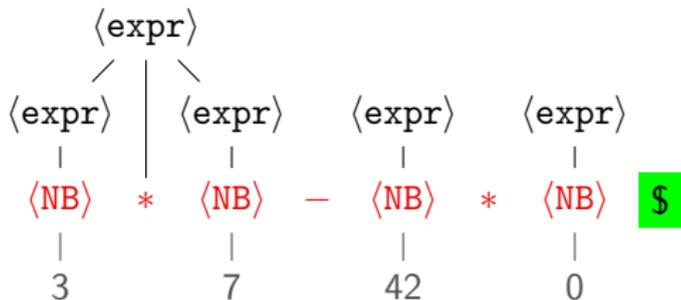
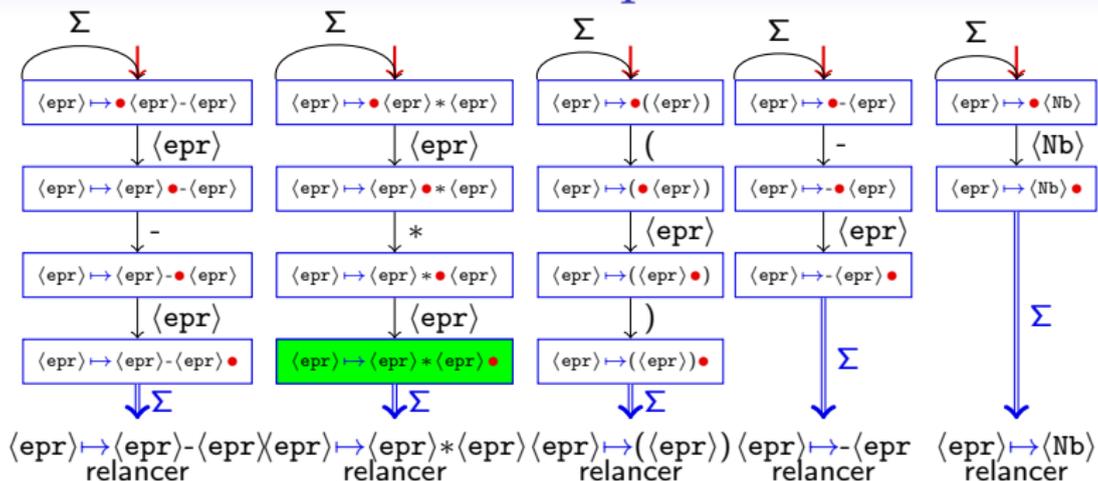
Automaton of the LR parser in motion



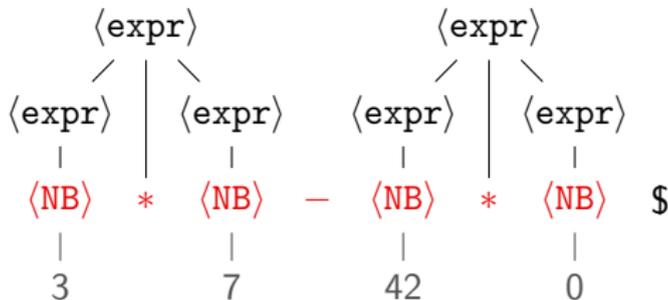
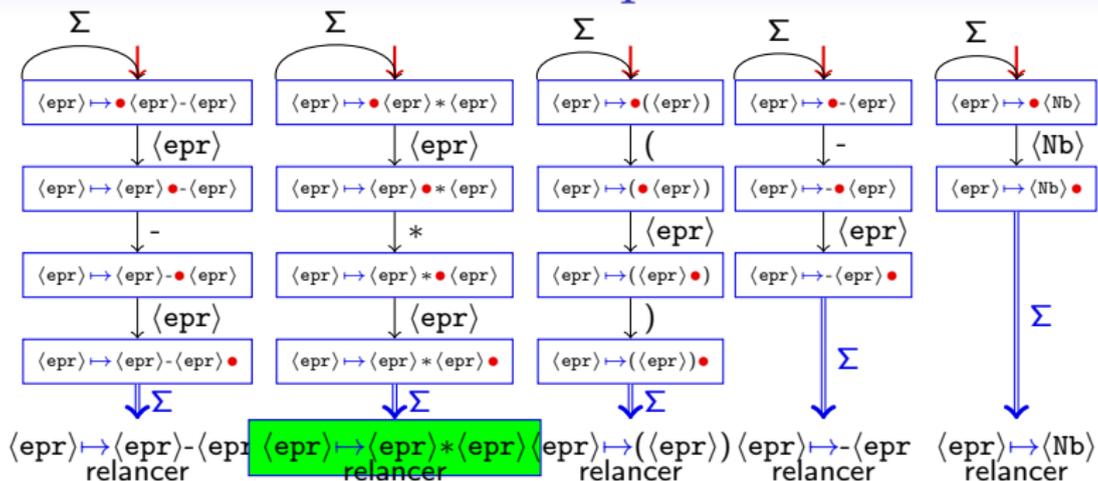
Automaton of the LR parser in motion



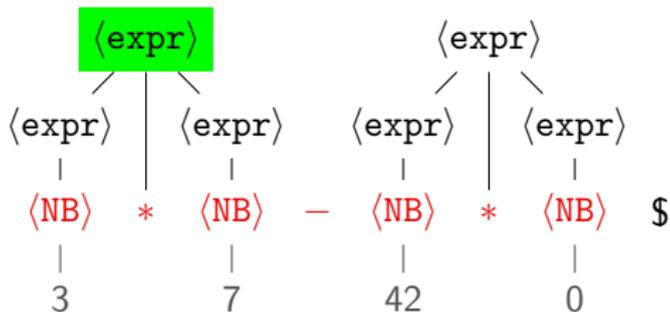
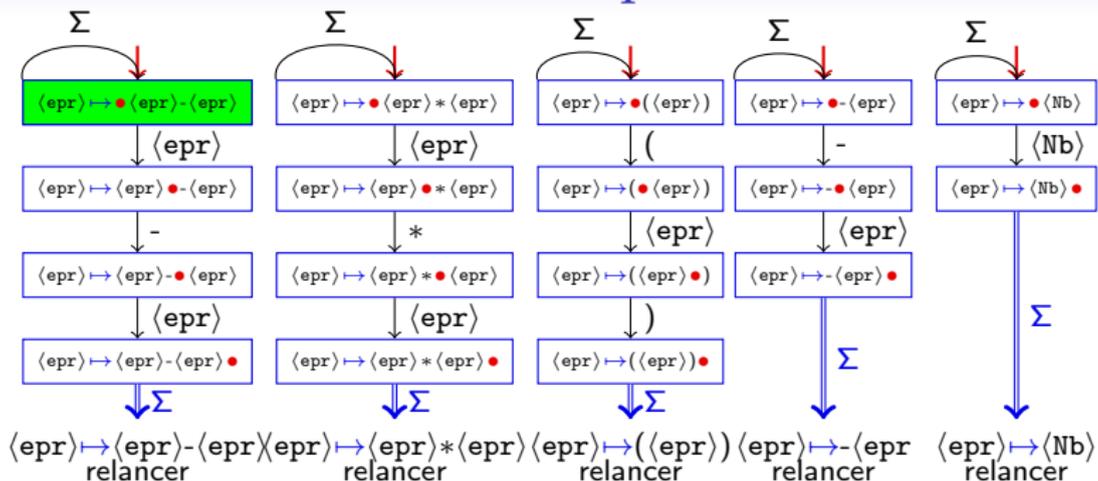
Automaton of the LR parser in motion



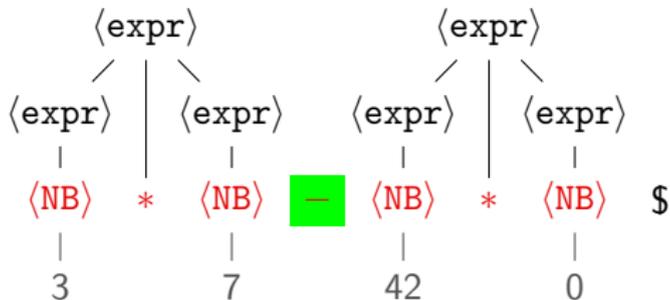
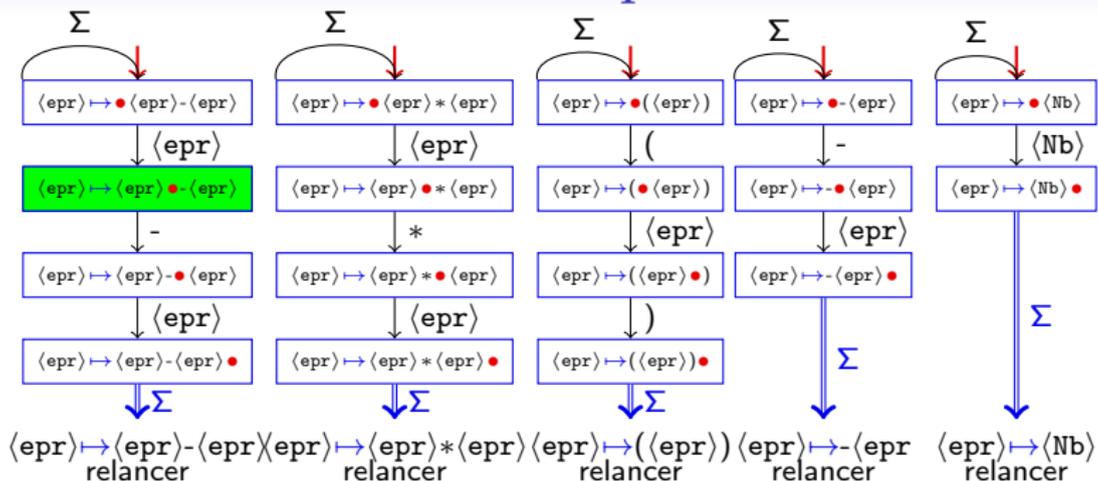
Automaton of the LR parser in motion



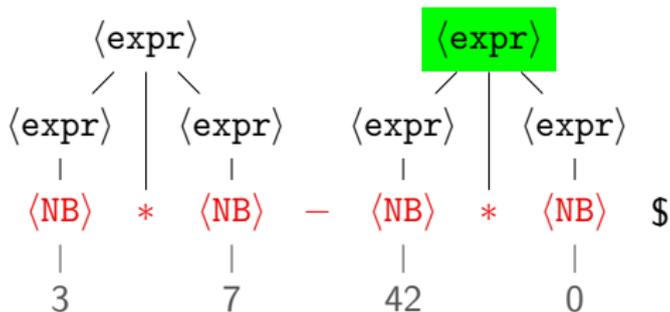
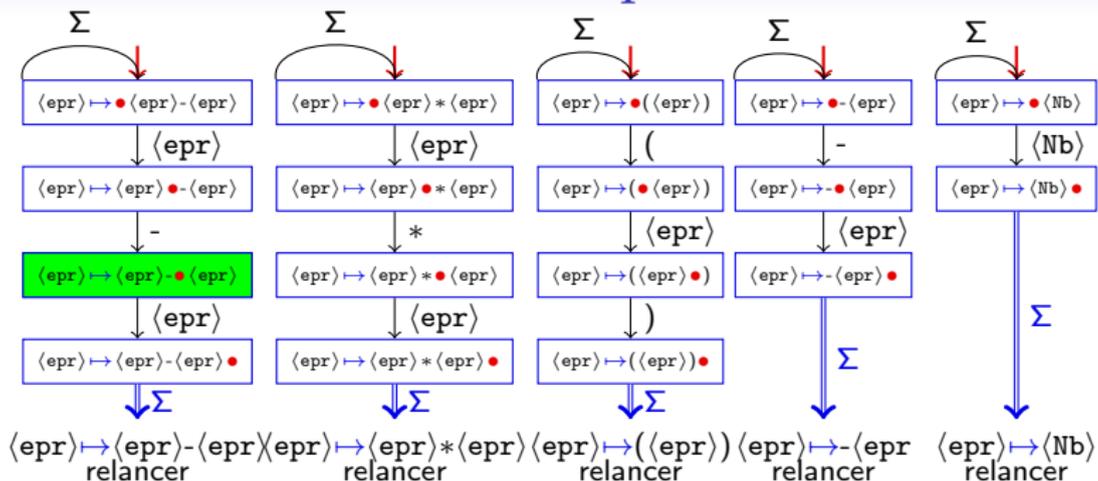
Automaton of the LR parser in motion



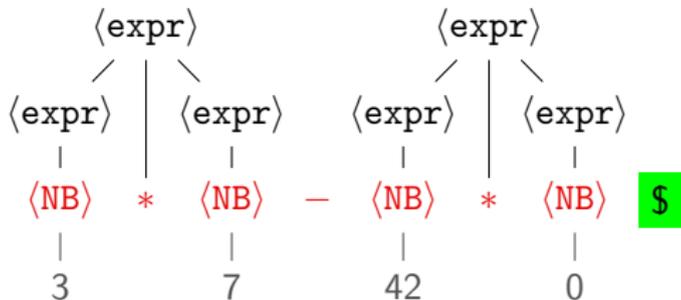
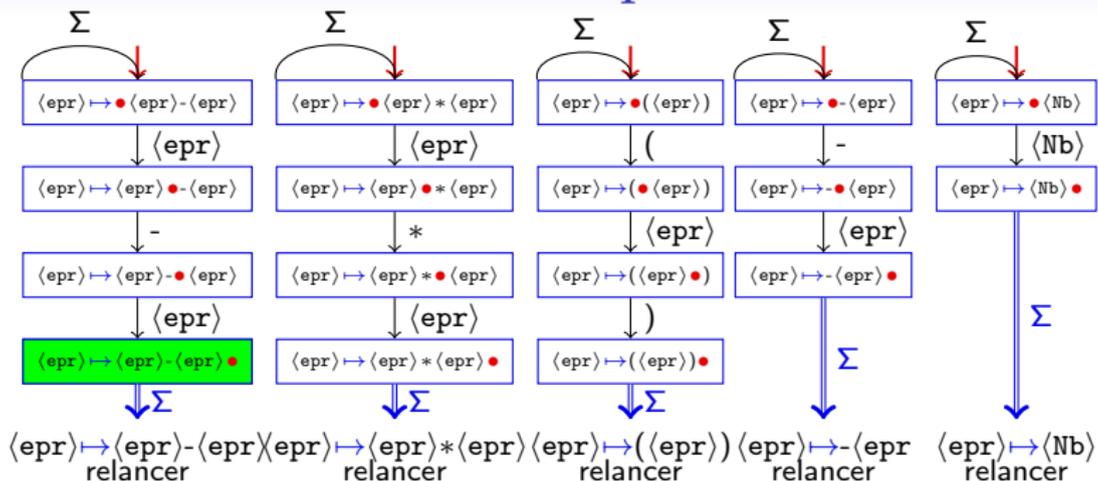
Automaton of the LR parser in motion



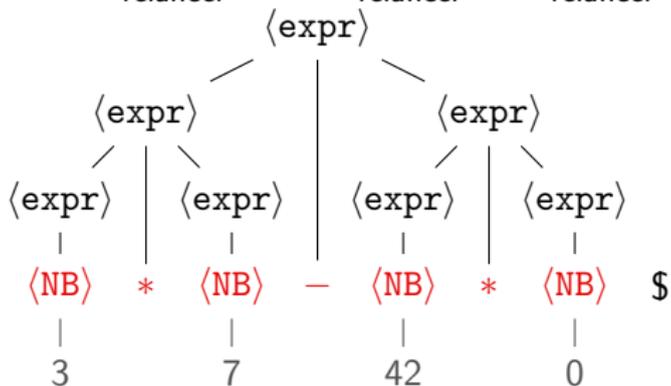
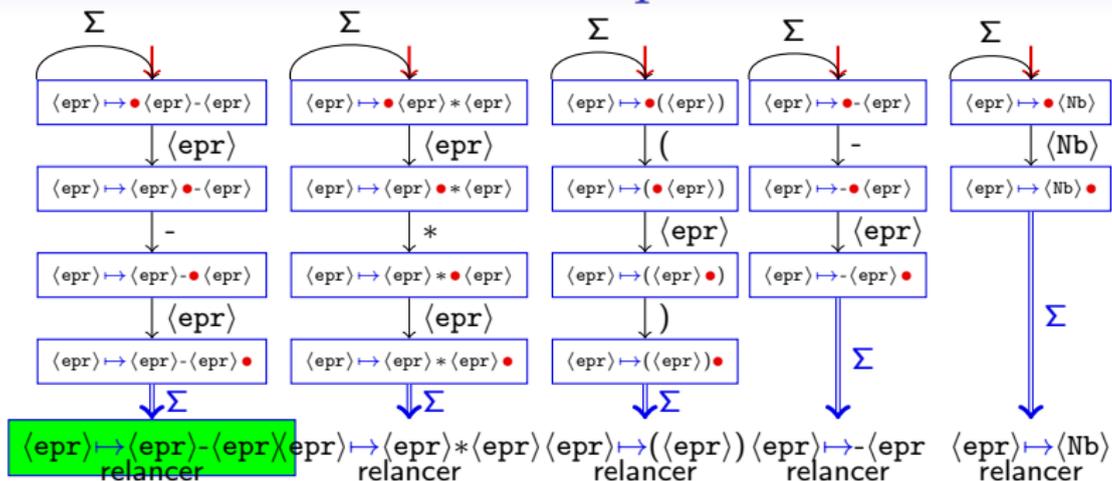
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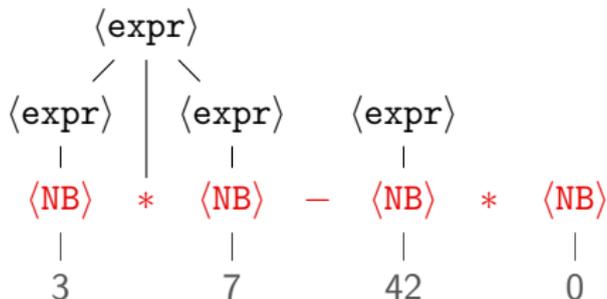
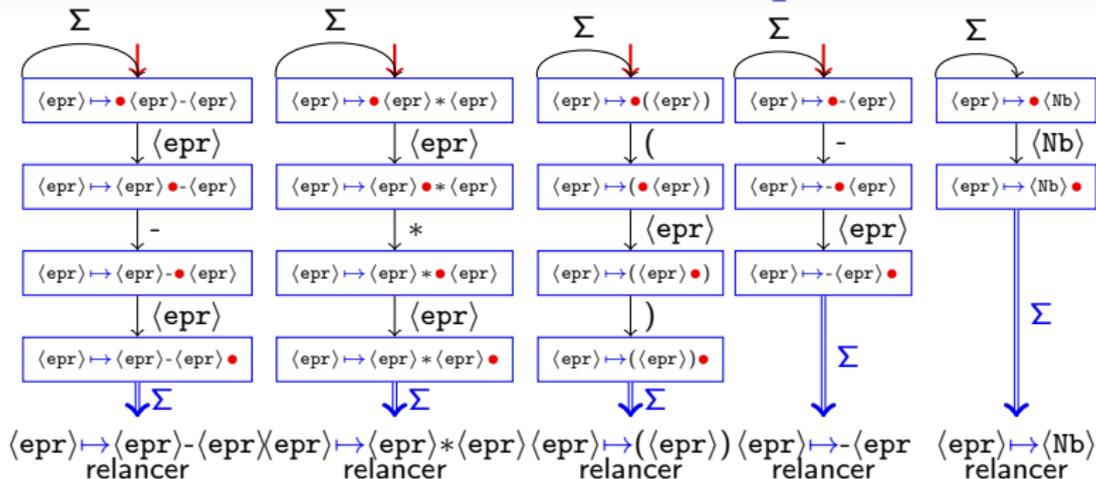
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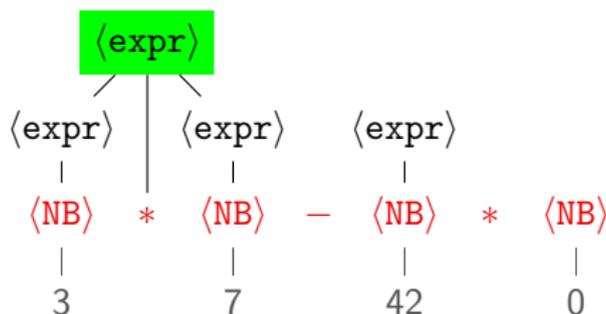
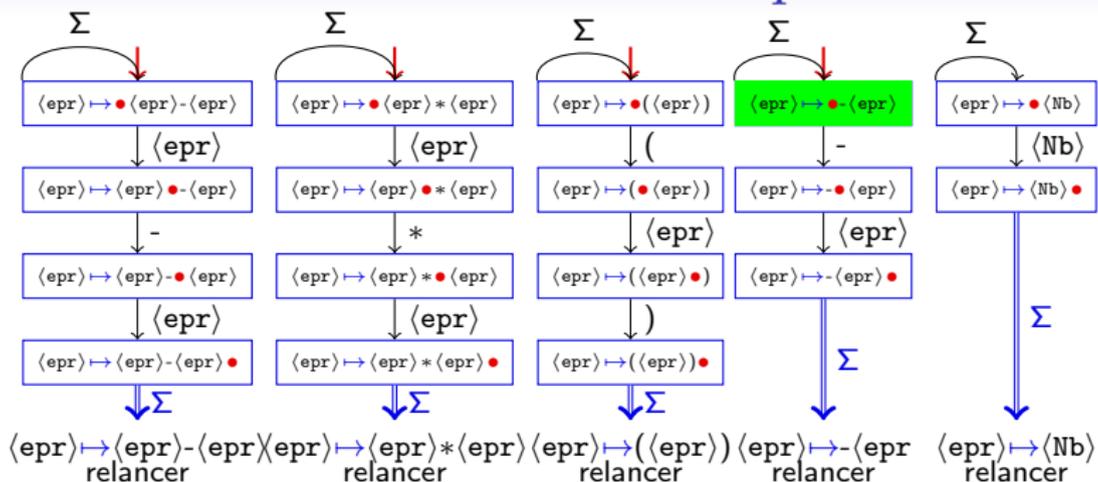
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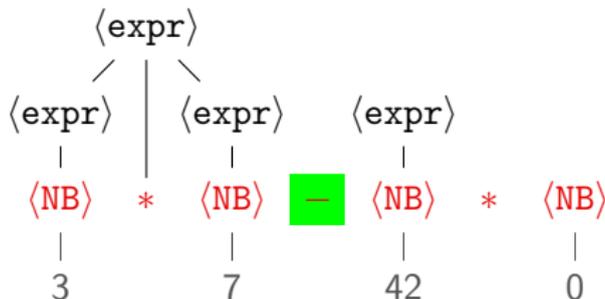
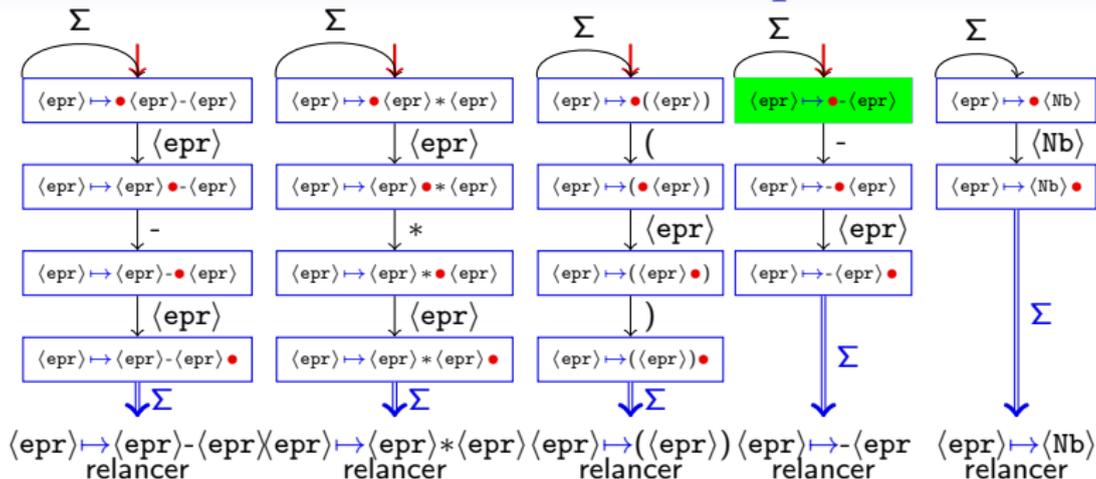
Failure of our attempt



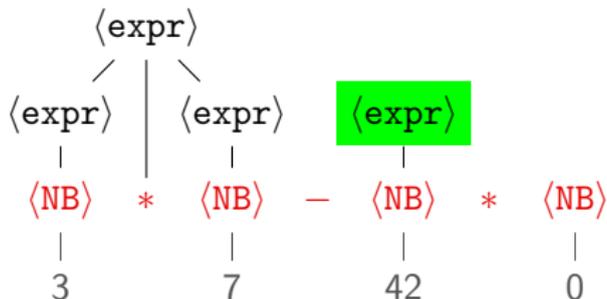
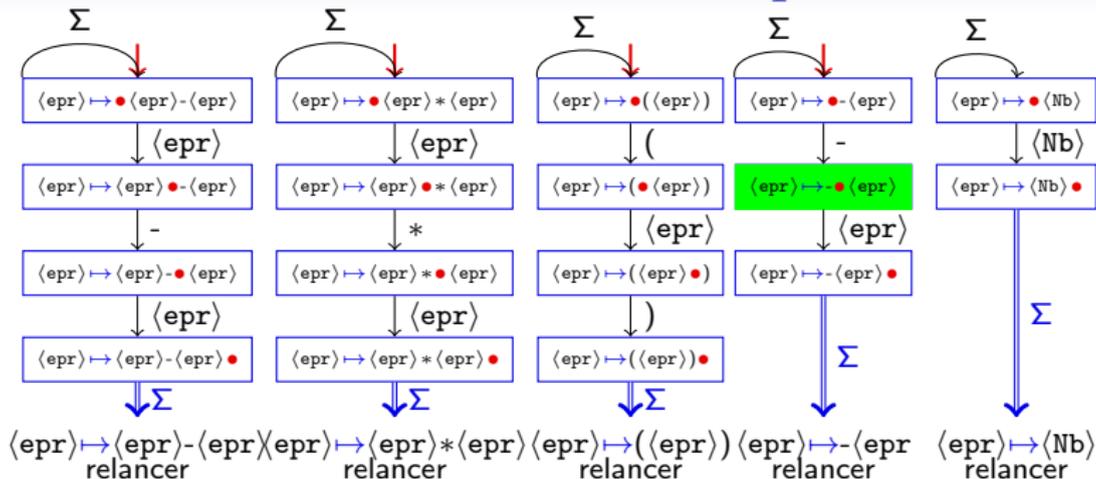
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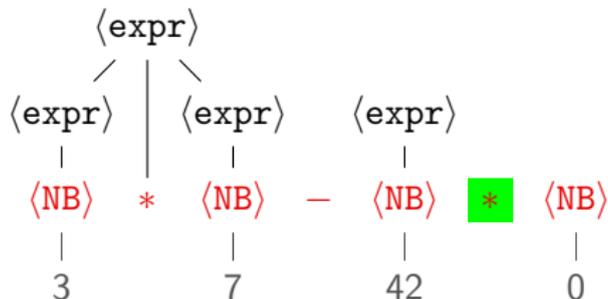
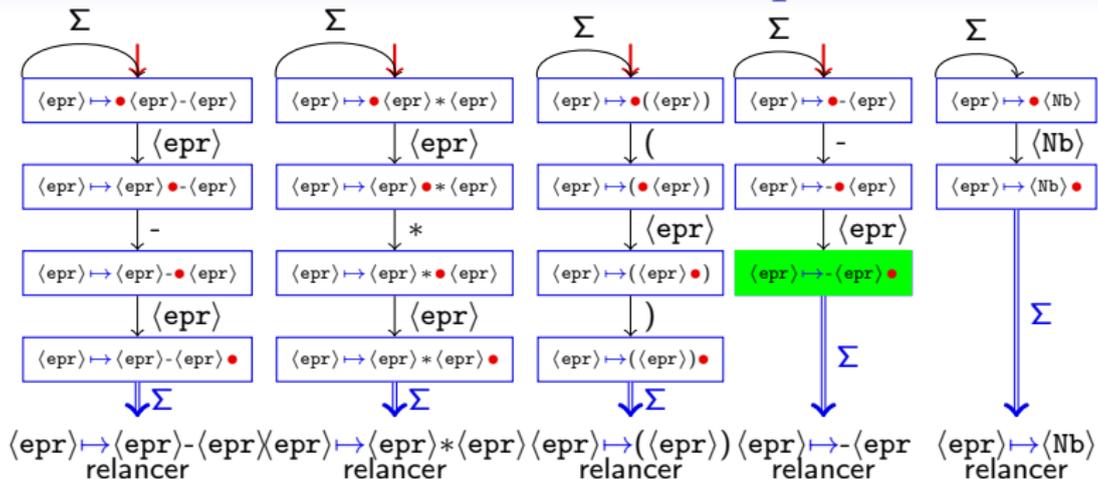
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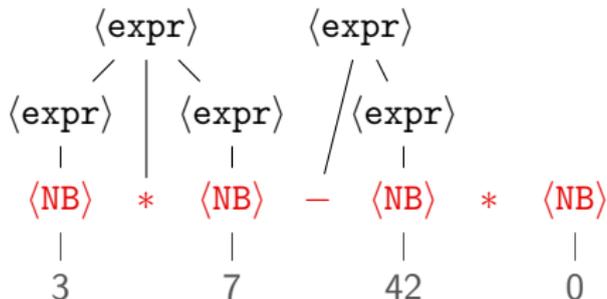
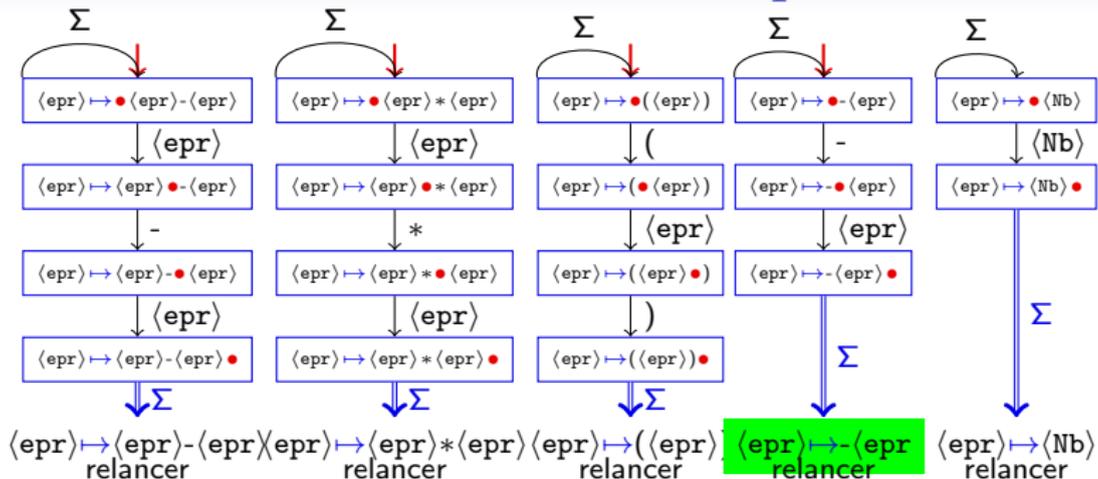
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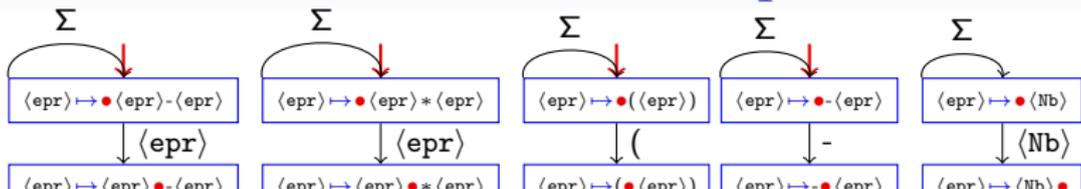
Failure of our attempt



Failure of our attempt



Failure of our attempt

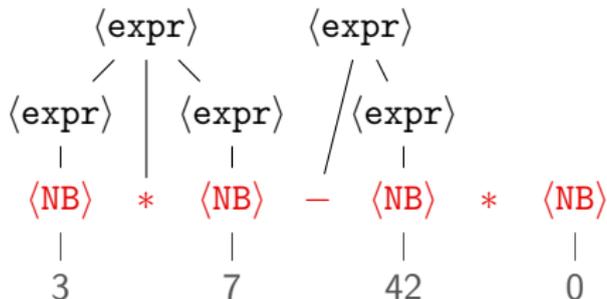


Why is it critical ?

(Conflict resolutions may resolve this ?)

The unary '-' has precedence over everything else, it will thus be selected before everything else in any reasonable determinisation...

We can have similar issues with non-ambiguous grammars.



What can we do ???

Force the more elements in the ND automaton

Non-terminal are to be created when last seen.

Thus there is no way any non-terminal exist after the point of an action.

↳ Actions are only taken on terminal peak.

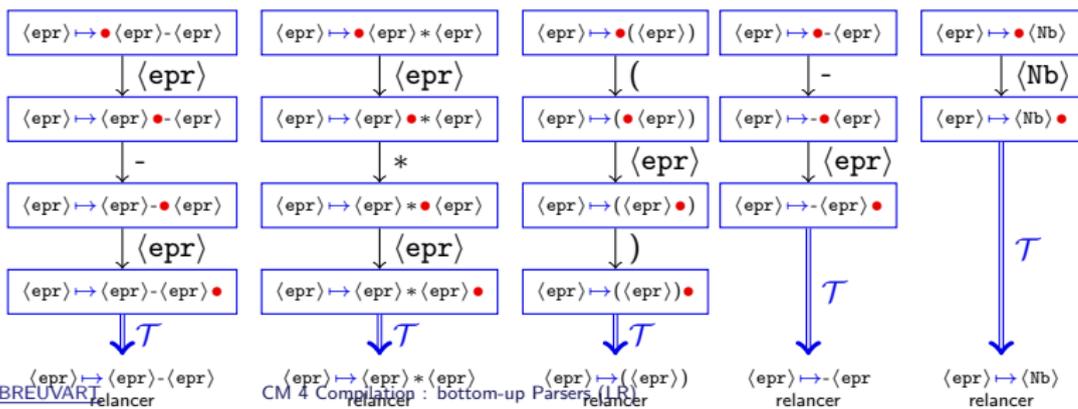
Only creat non terminal where we need them

Do not “test” each rule each step with a Σ -loop,

↳ try a rule where we may need the created non-terminal.

Second attempt

Actions taken on terminal peak are easy to deal with, but how to try a rule where we may need the created NT

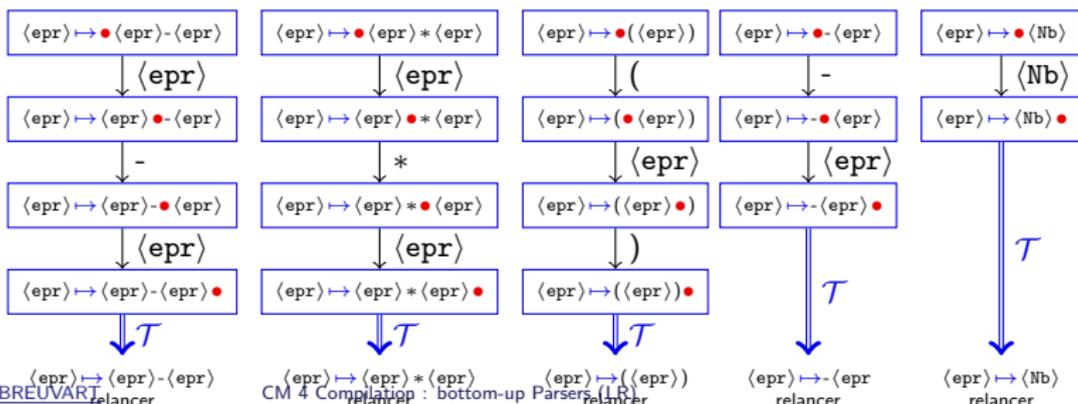


Second attempt

Actions taken on terminal peak are easy to deal with, but how to try a rule where we may need the created NT

- add a dummy state for each non-terminal N , meaning : "I need to create a N "

$\langle \text{epr} \rangle$

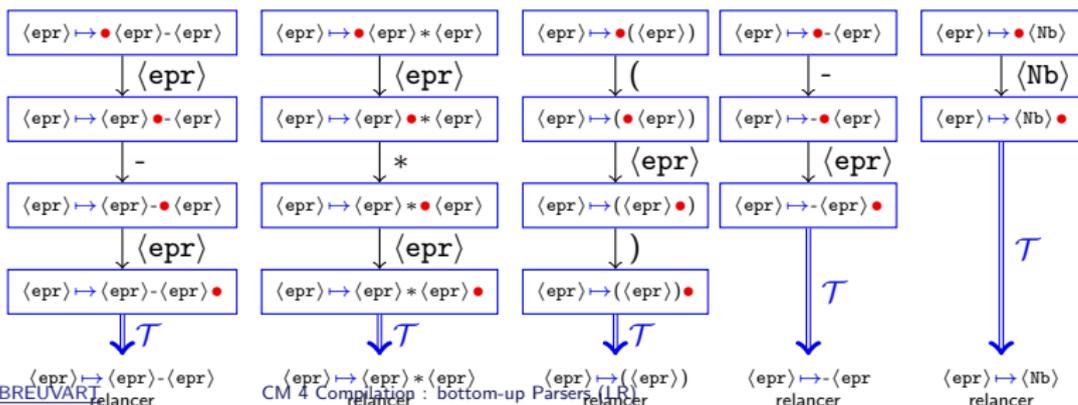


Second attempt

Actions taken on terminal peak are easy to deal with, but how to try a rule where we may need the created NT

- add a dummy state for each non-terminal N , meaning : "I need to create a N "
- only the principal one S is initial,

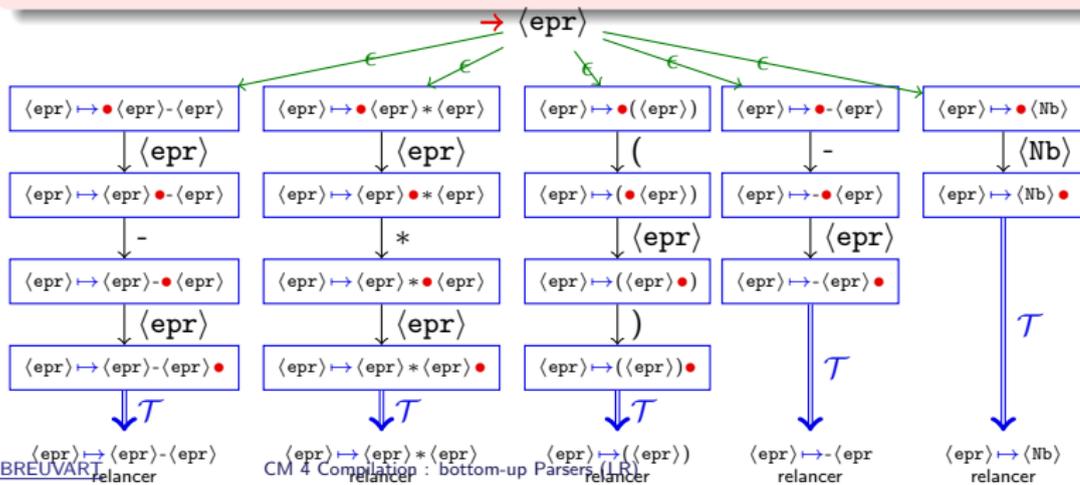
→ $\langle \text{epr} \rangle$



Second attempt

Actions taken on terminal peak are easy to deal with, but how to try a rule where we may need the created NT

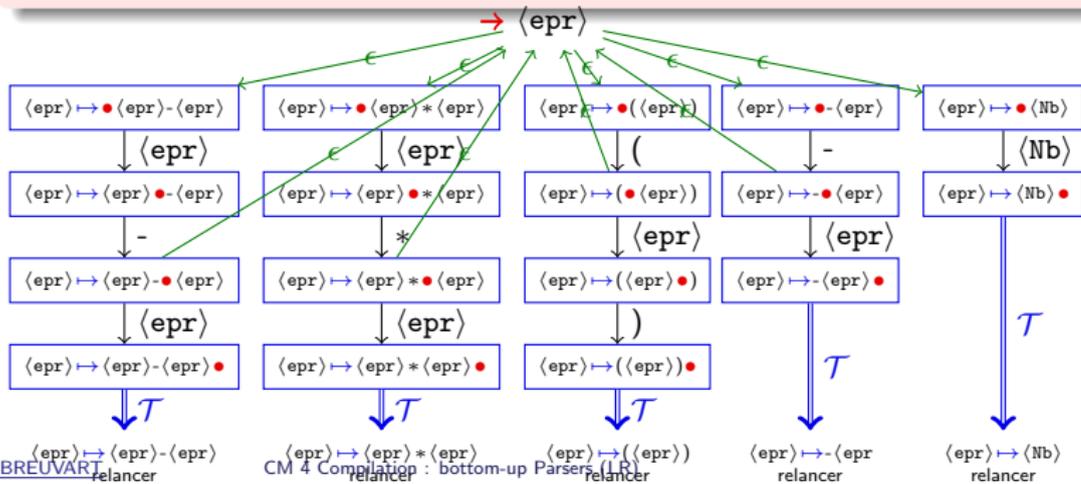
- add a dummy state for each non-terminal N , meaning : "I need to create a N "
- only the principal one S is initial,
- add ϵ -transitions toward rules, meaning : "choose a way to reduce it"



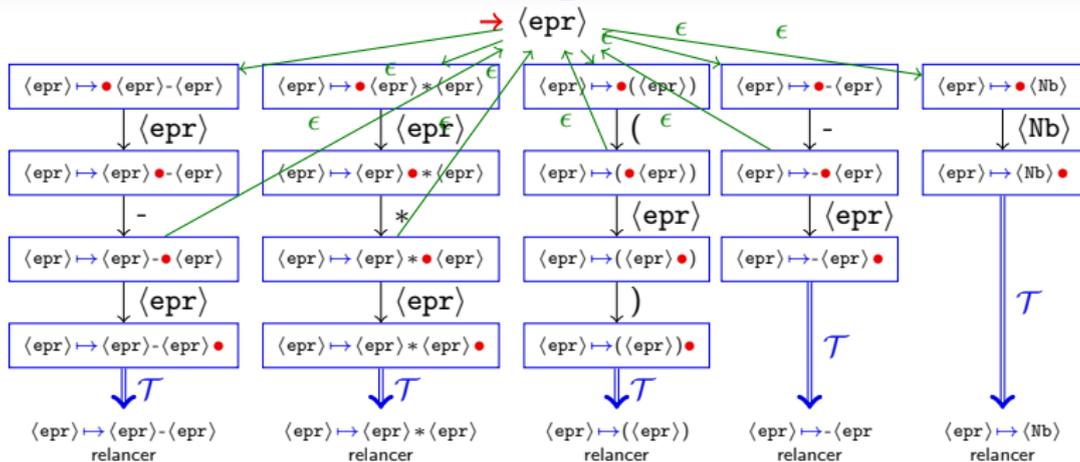
Second attempt

Actions taken on terminal peak are easy to deal with, but how to try a rule where we may need the created NT

- add a dummy state for each non-terminal N , meaning : "I need to create a N "
- only the principal one S is initial,
- add ϵ -transitions toward rules, meaning : "choose a way to reduce it"
- for each rules of the form $M \rightarrow w_1 \bullet N w_2$, add an ϵ -transition toward N meaning : "a N is expected here, we may create it"

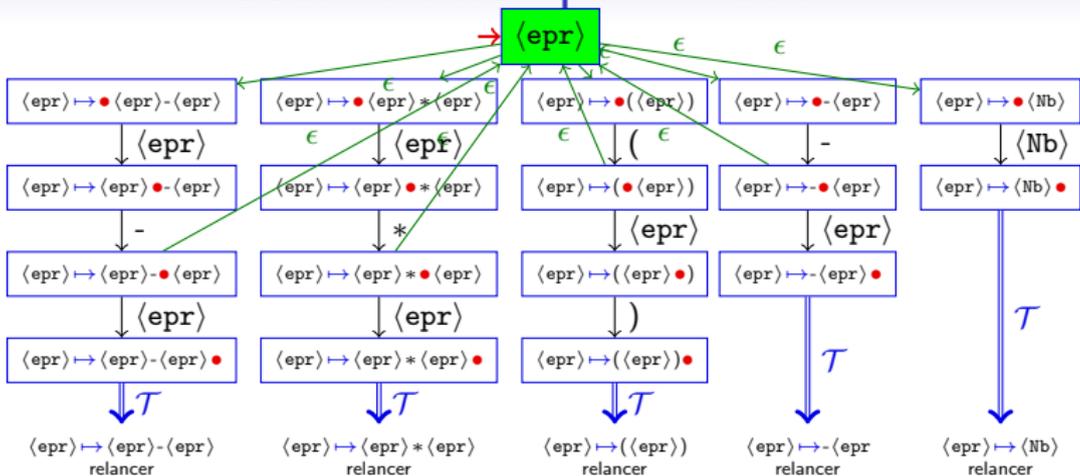


Second attempt in motion

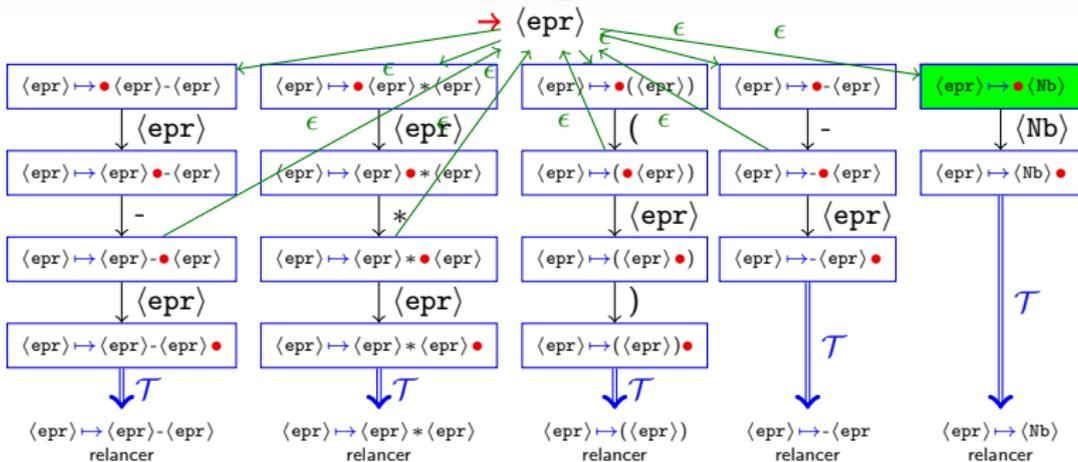


$\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ - $\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ \$
 | | | |
 3 7 42 0

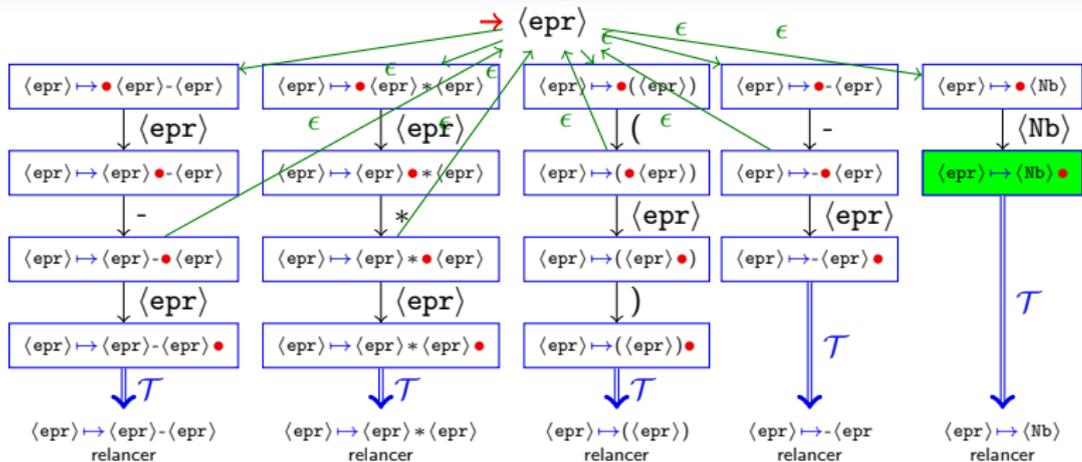
Second attempt in motion



Second attempt in motion

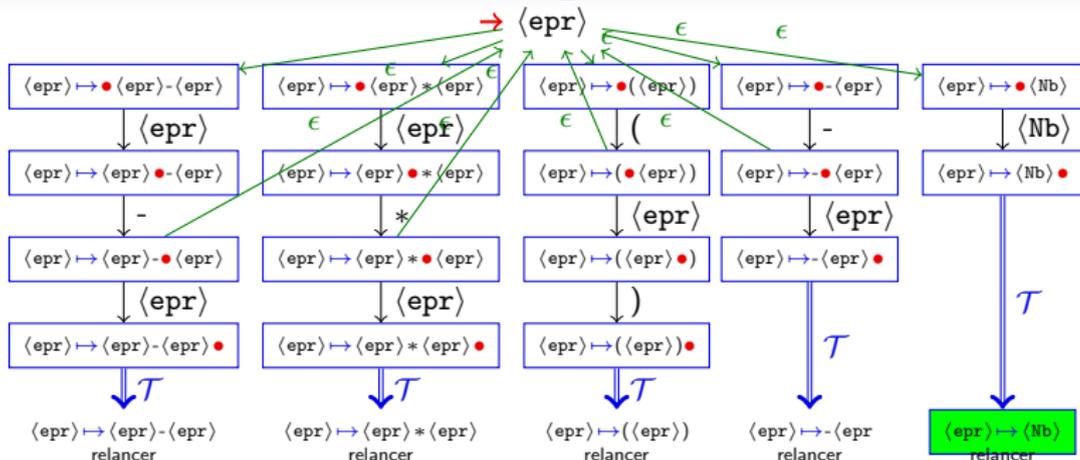


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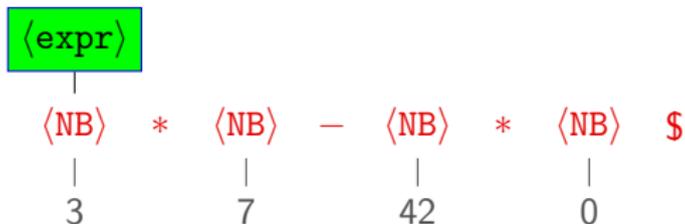
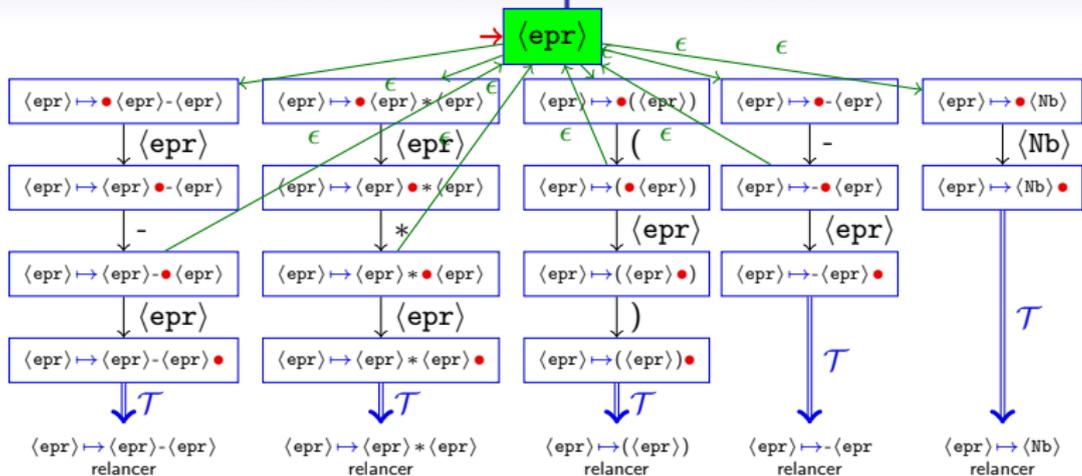
$\langle NB \rangle$ * $\langle NB \rangle$ - $\langle NB \rangle$ * $\langle NB \rangle$ \$
 | | | | |
 3 7 42 0

Second attempt in motion

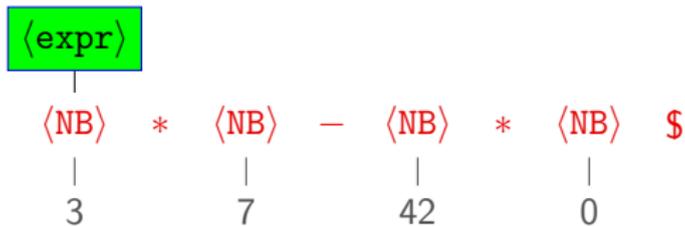
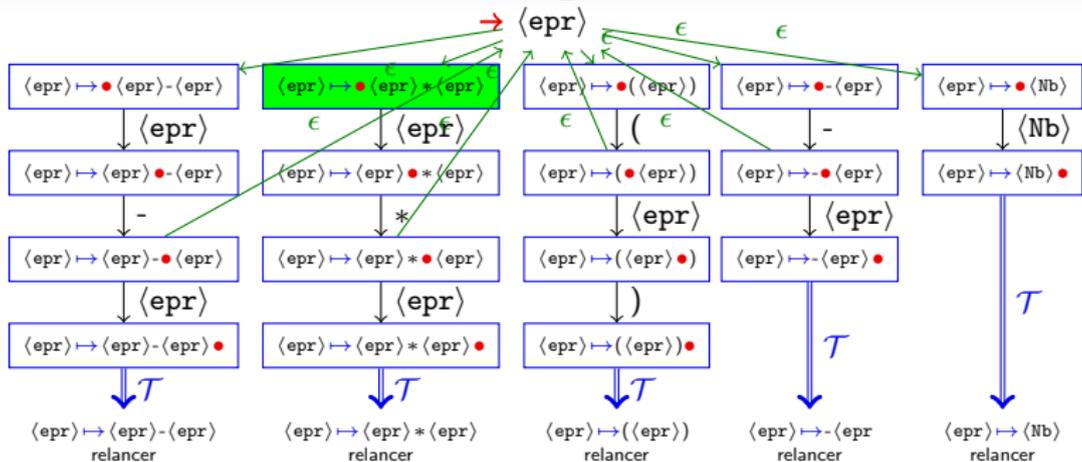


$\langle \text{expr} \rangle$
 |
 $\langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad - \quad \langle \text{NB} \rangle \quad * \quad \langle \text{NB} \rangle \quad \$$
 | | | |
 3 7 42 0

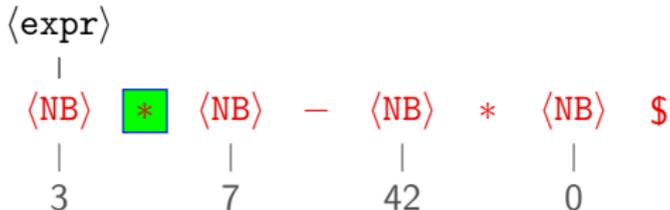
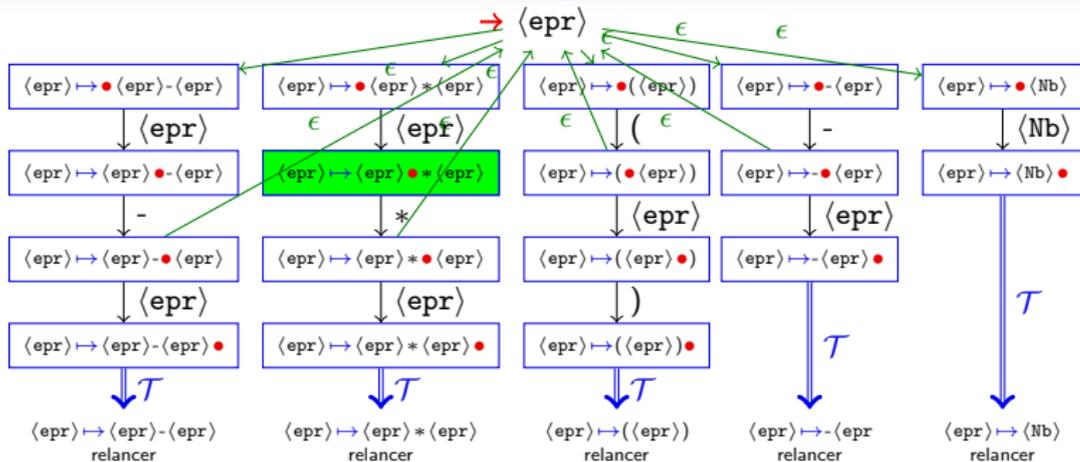
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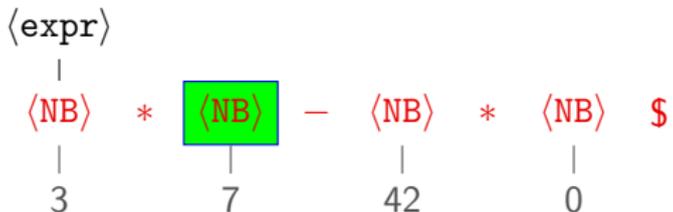
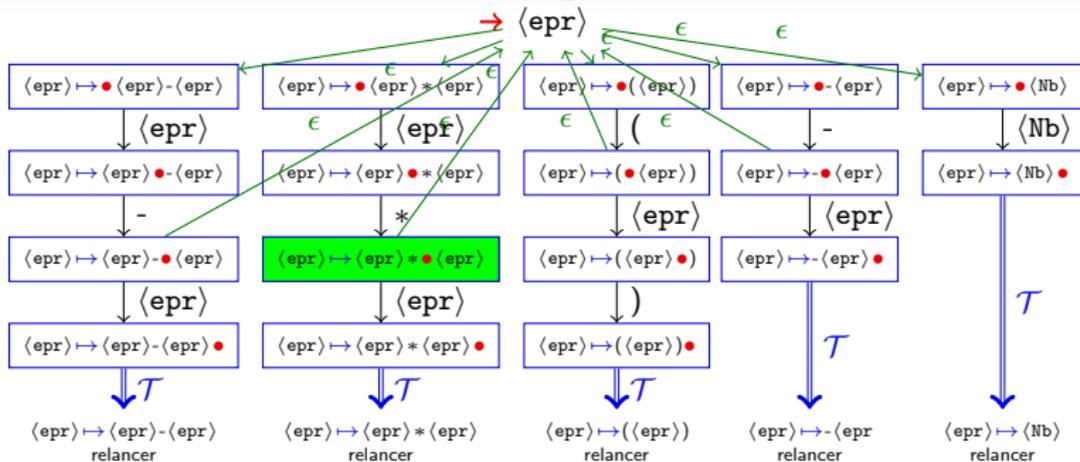
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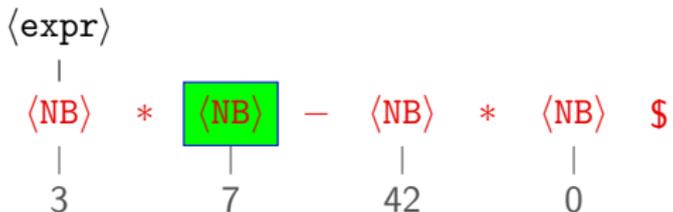
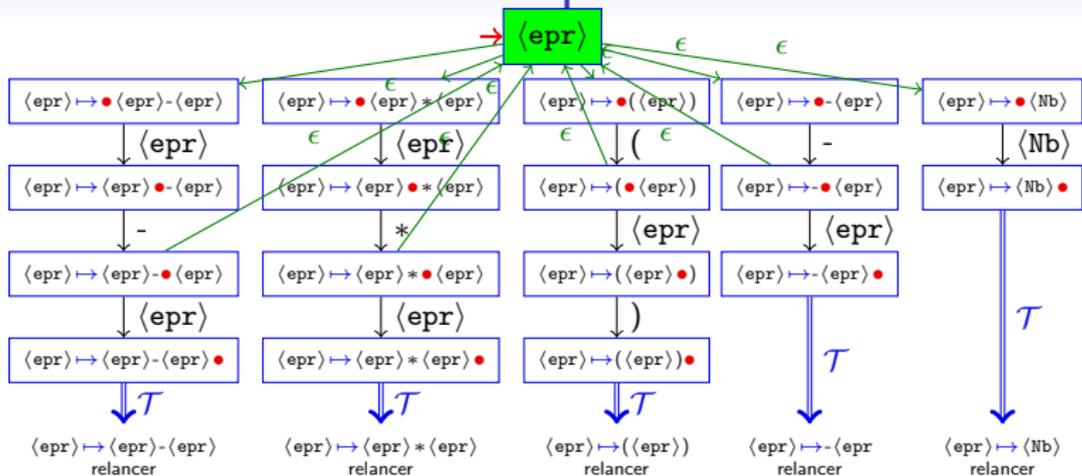
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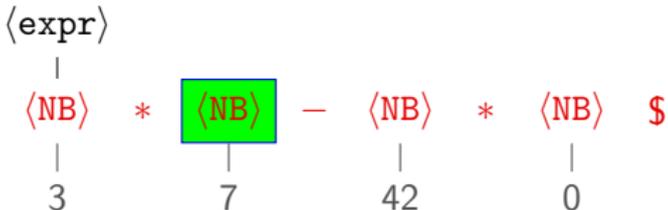
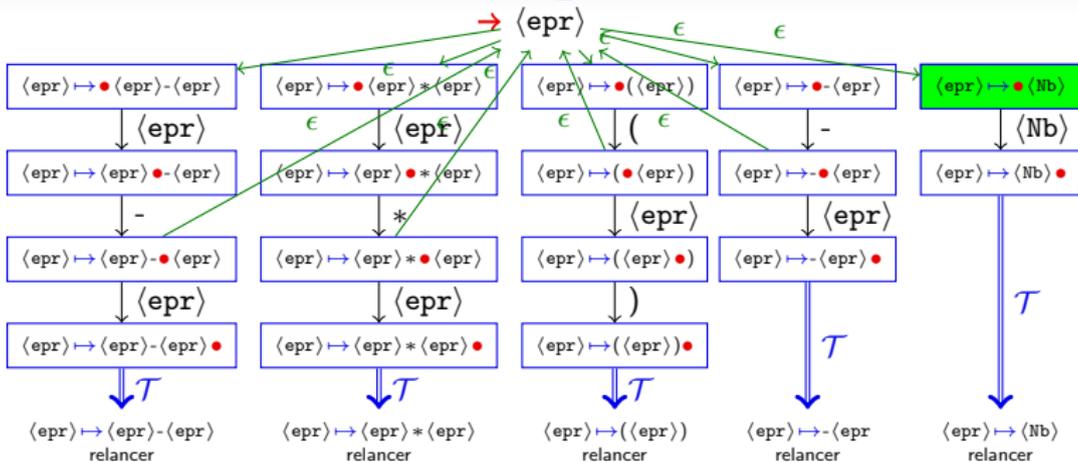
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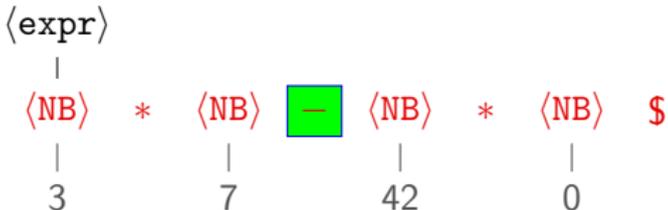
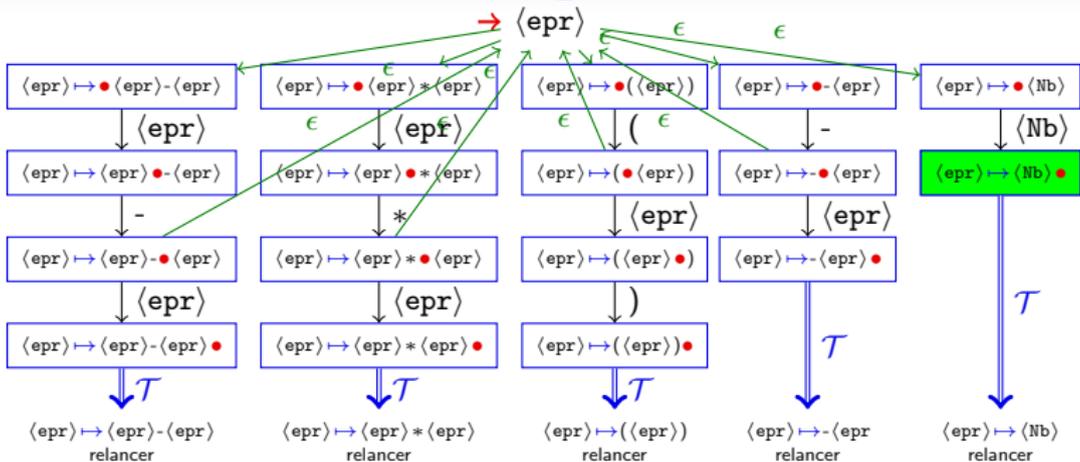
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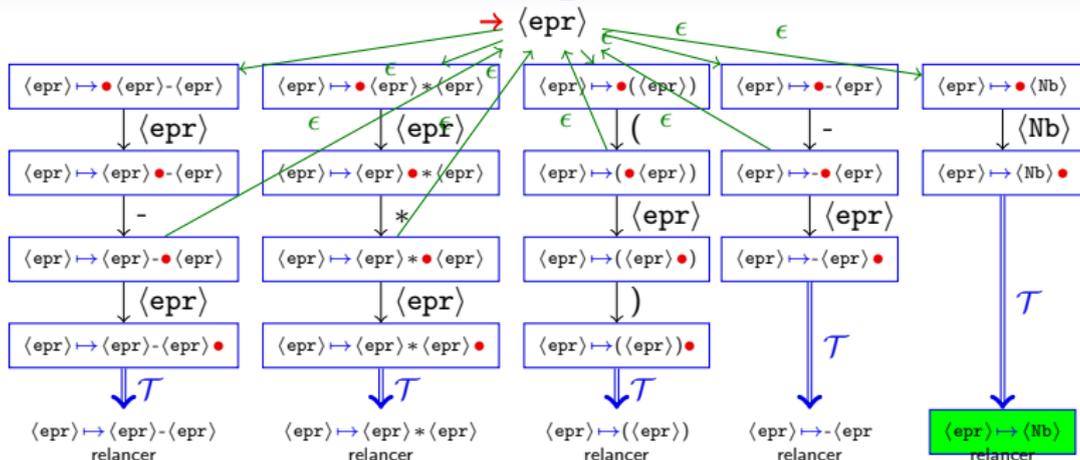
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Second attempt in motion

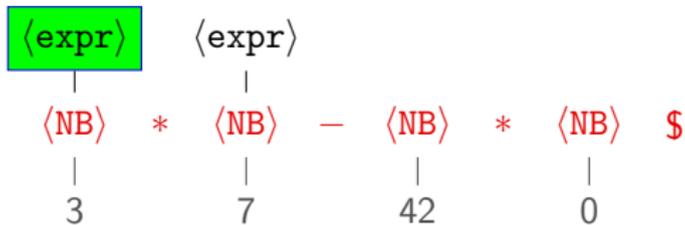
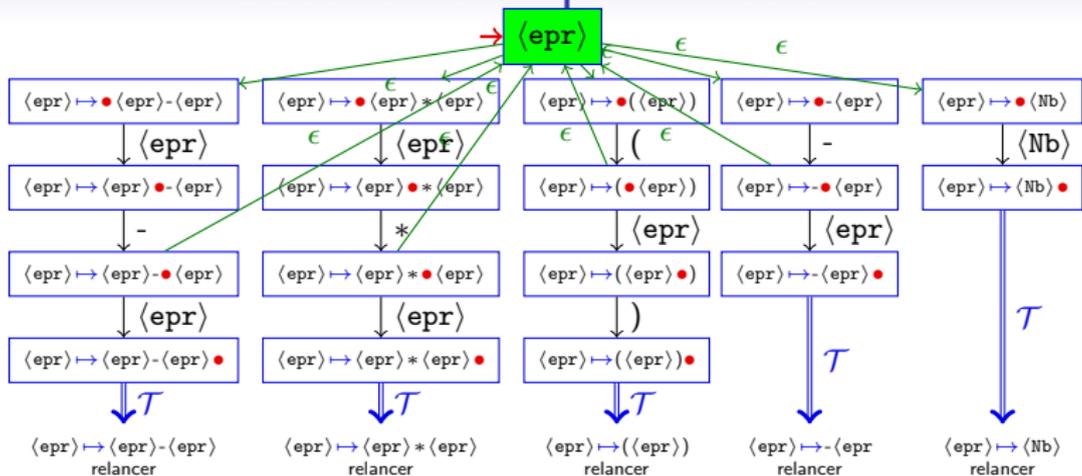


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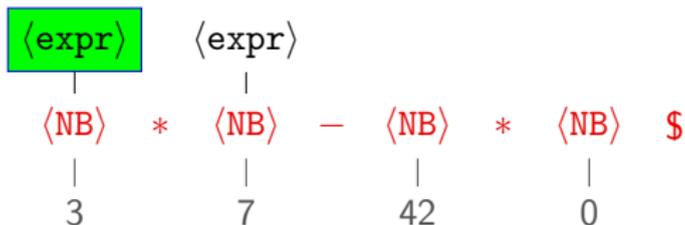
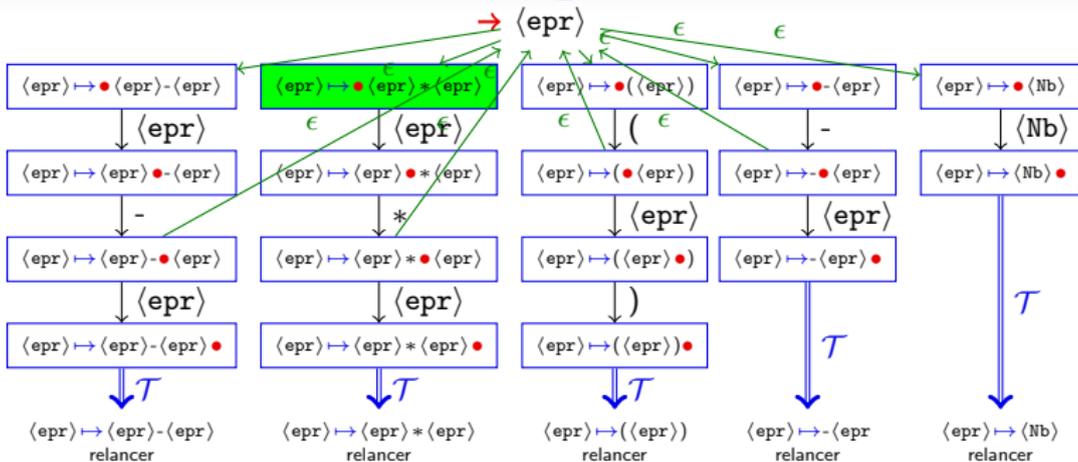


$\langle \text{expr} \rangle$ $\langle \text{expr} \rangle$
 | |
 $\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ - $\langle \text{NB} \rangle$ * $\langle \text{NB} \rangle$ \$
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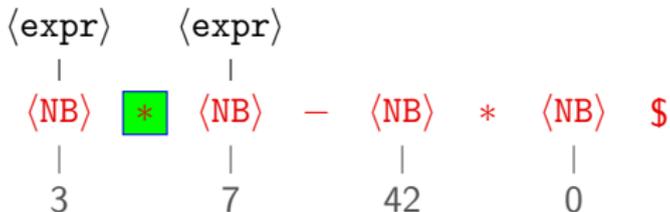
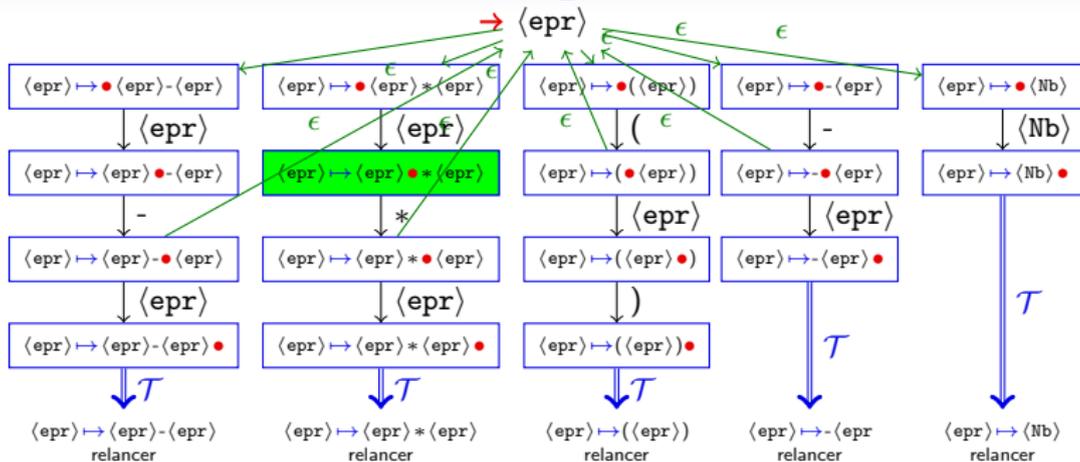
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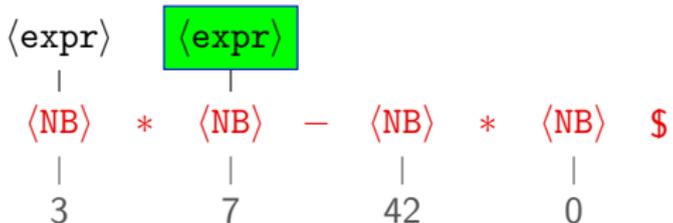
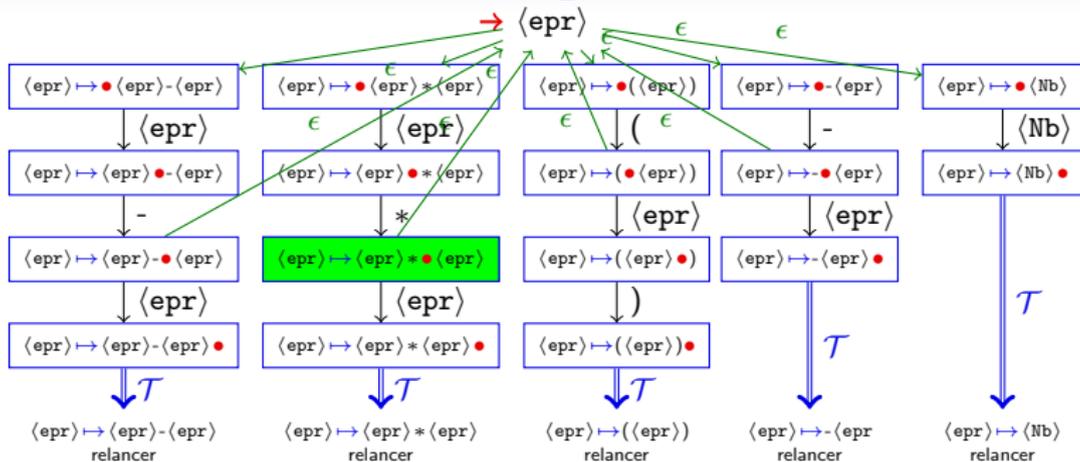
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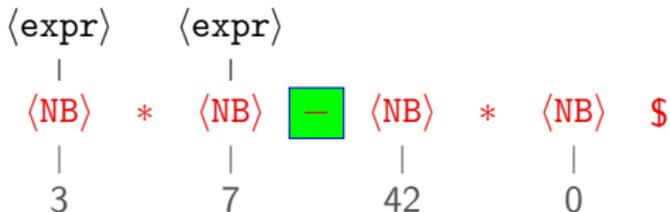
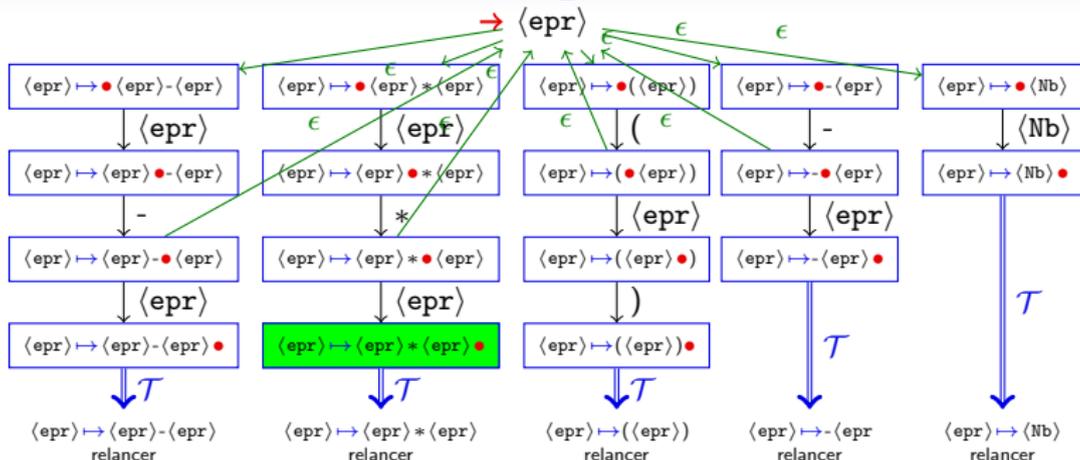
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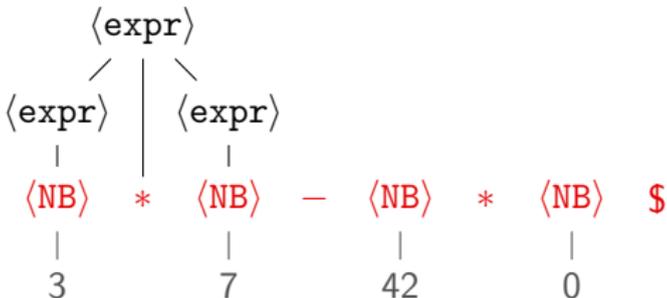
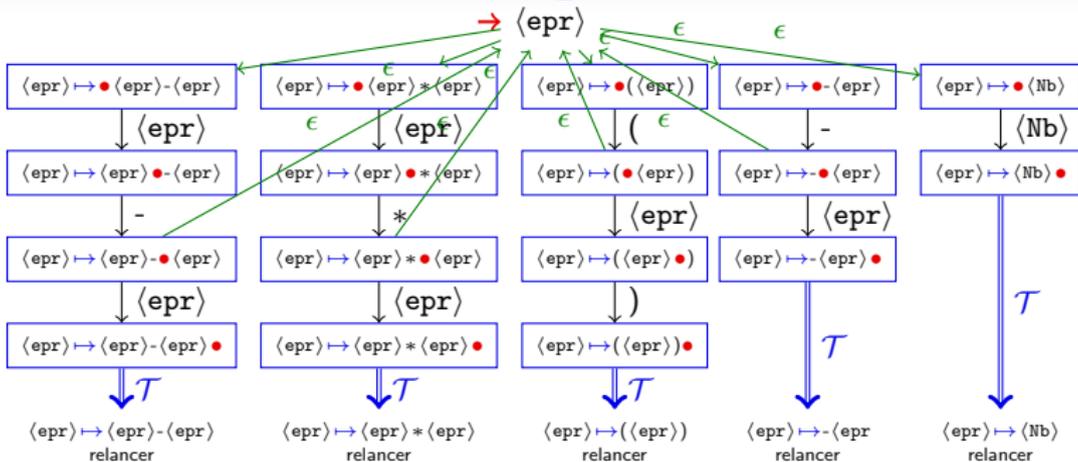
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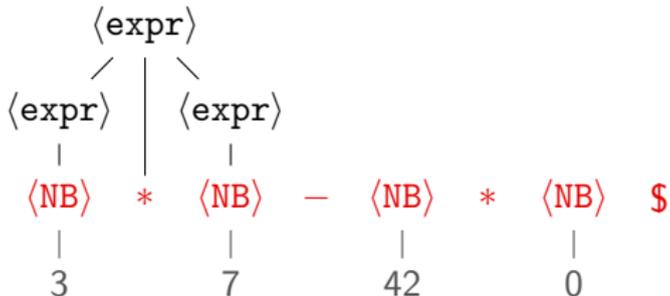
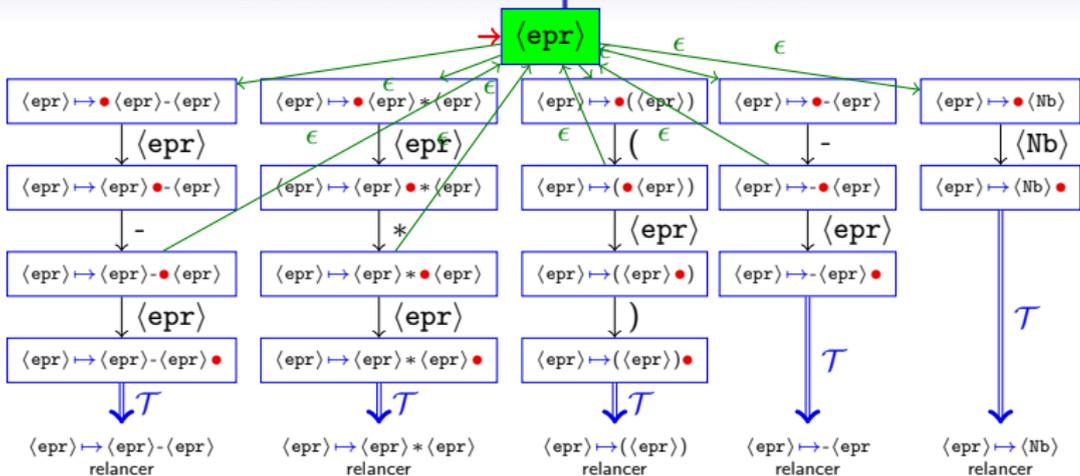
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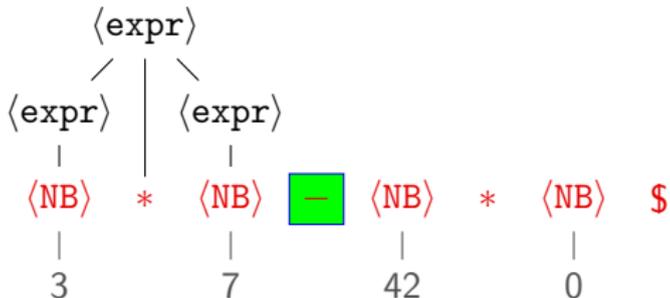
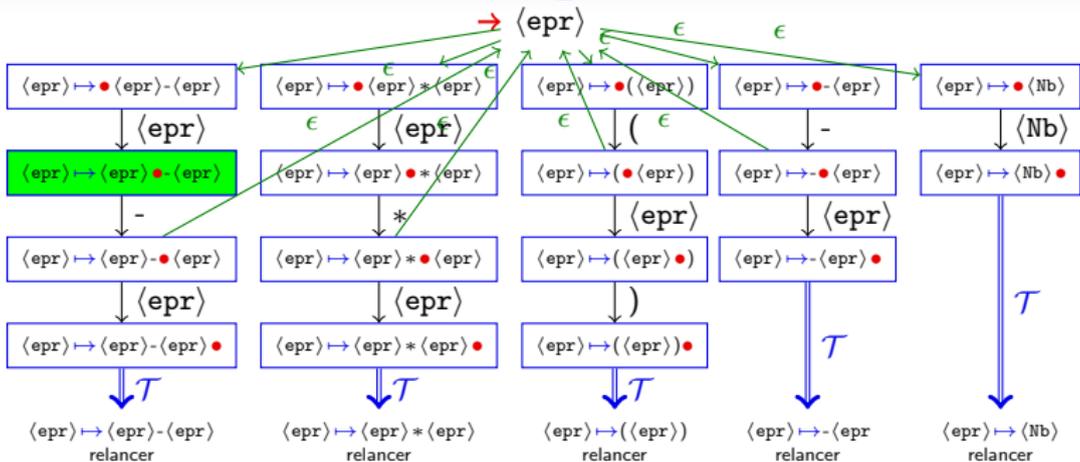
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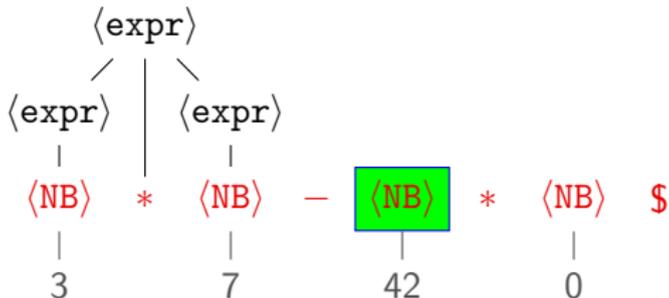
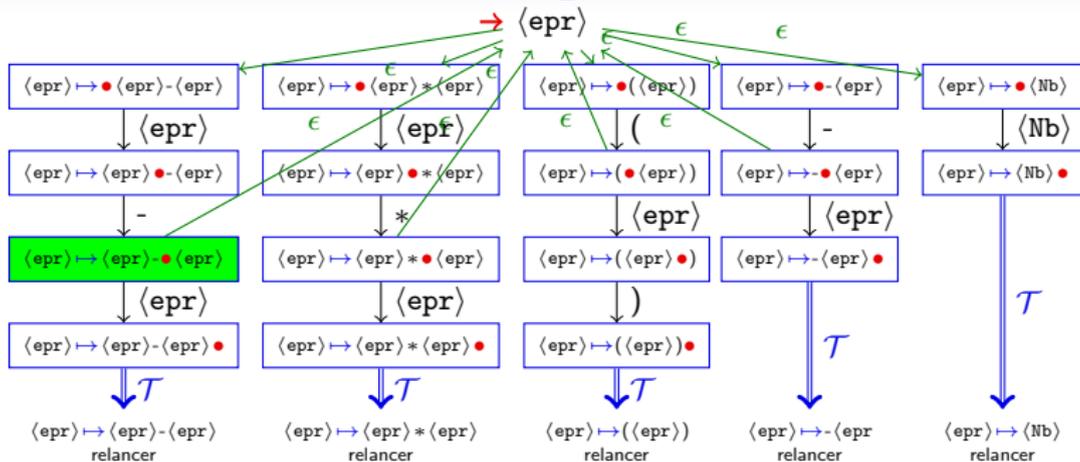
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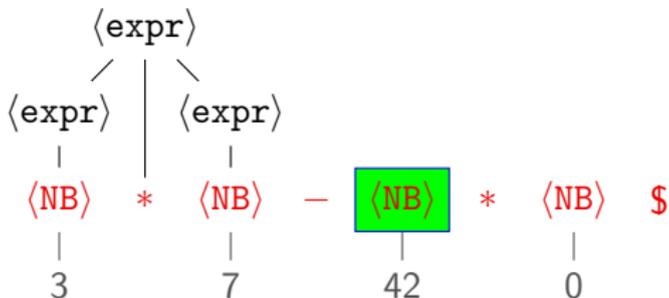
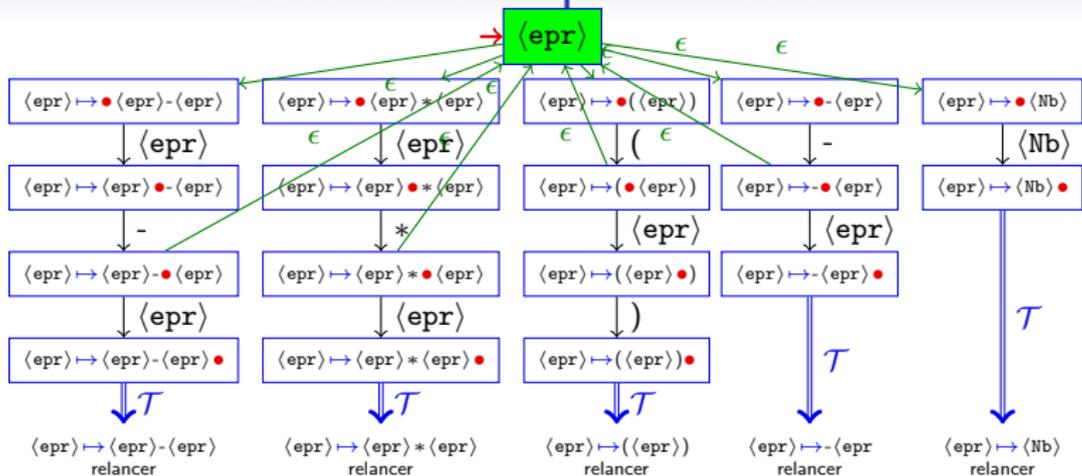
Second attempt in motion



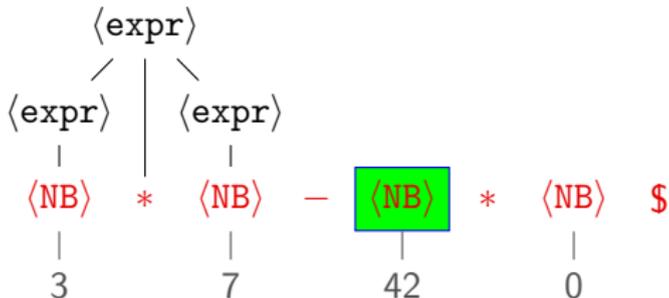
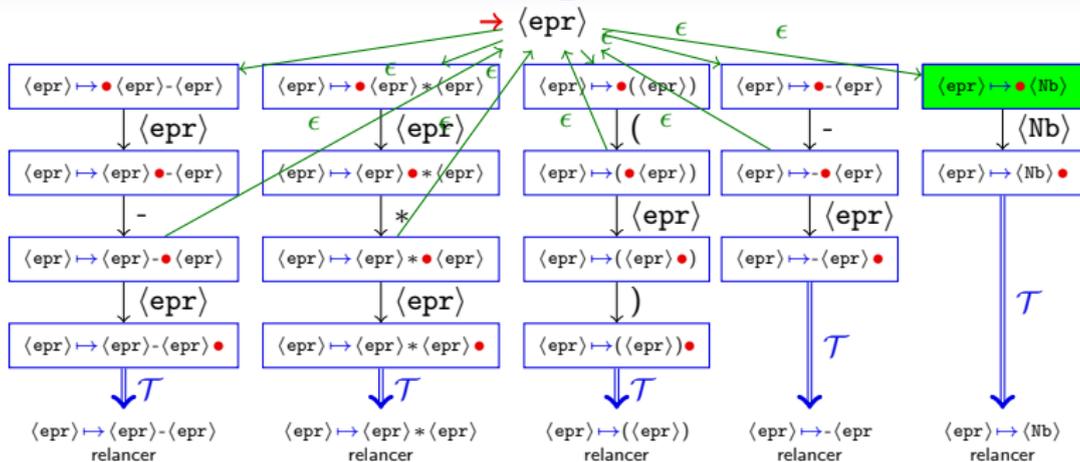
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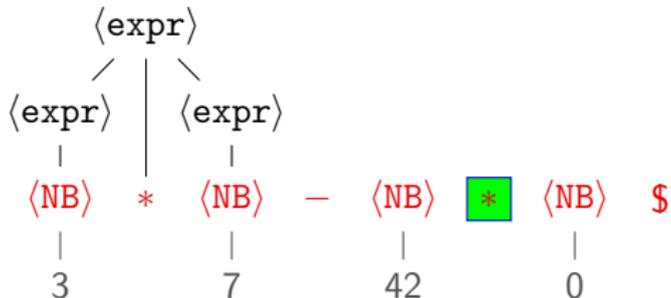
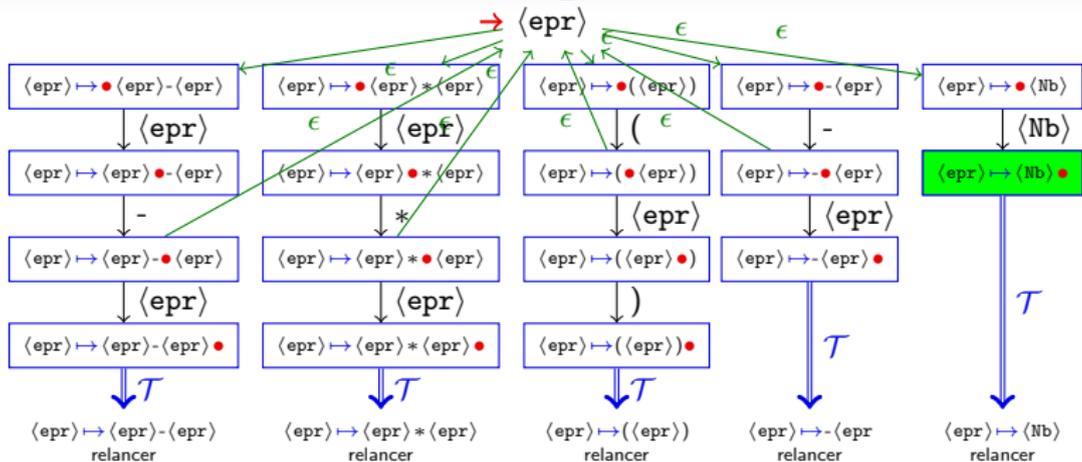
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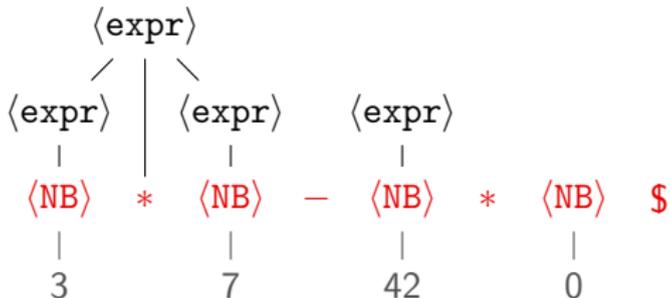
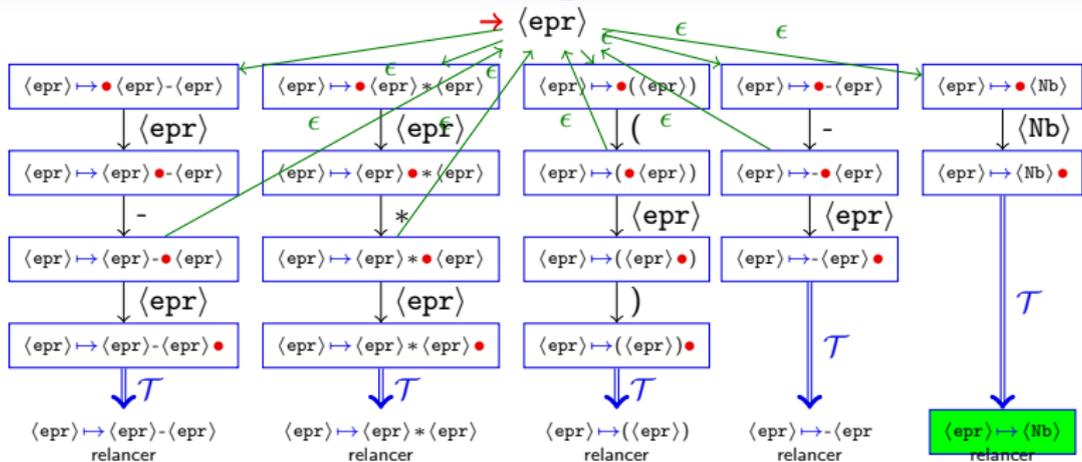
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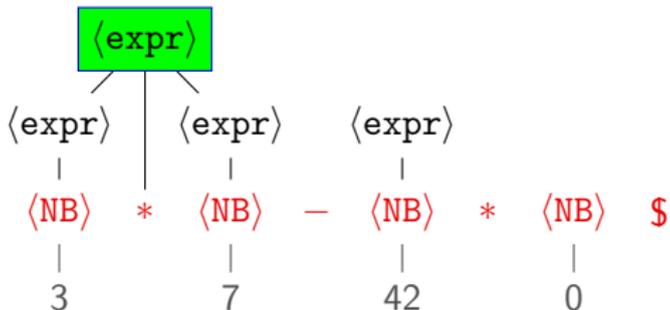
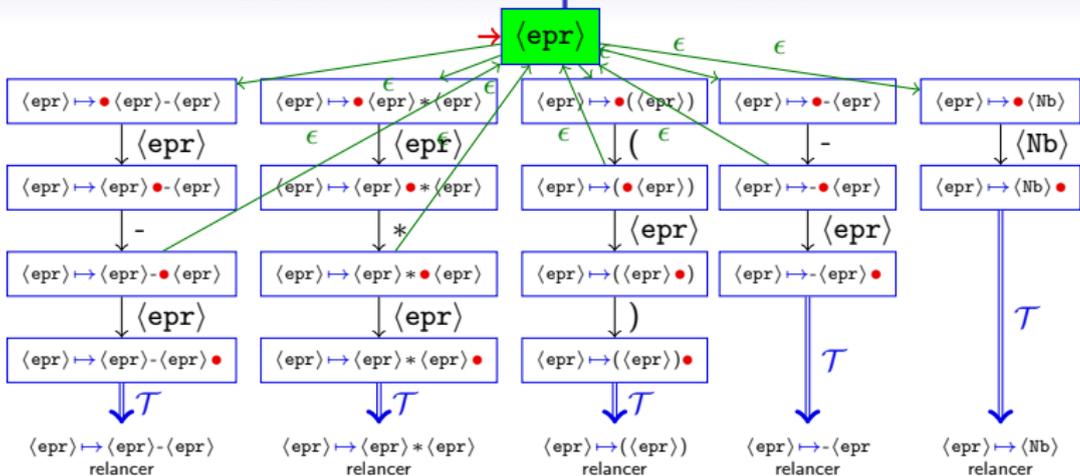
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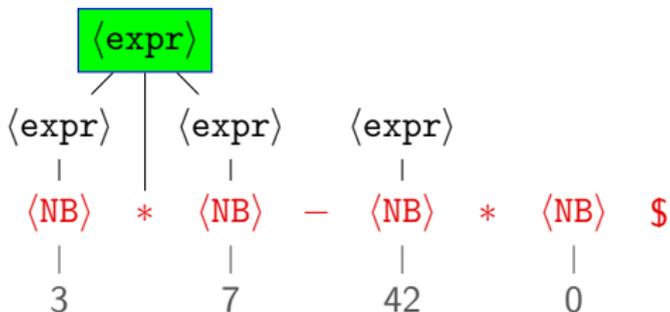
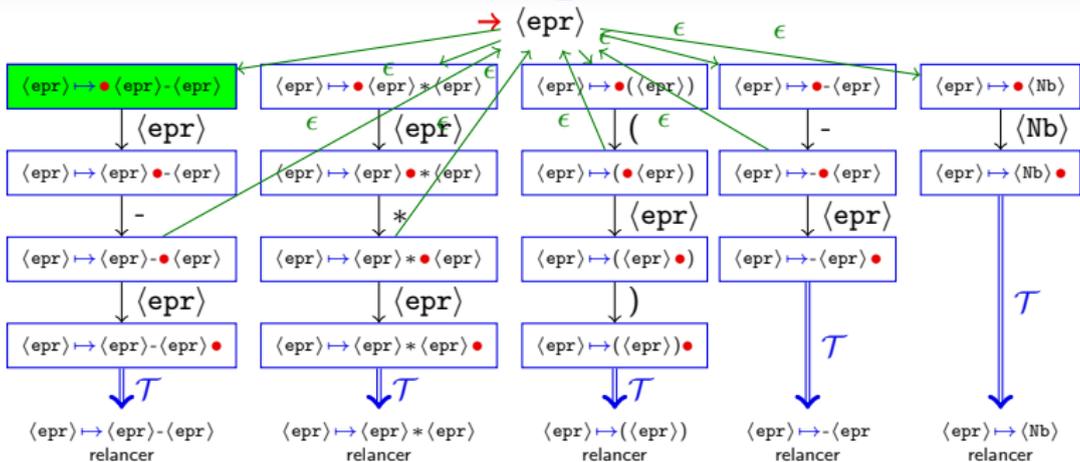
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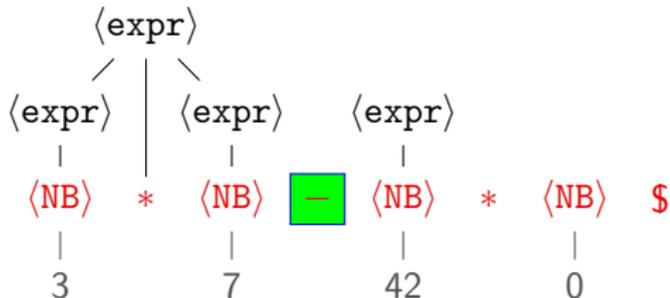
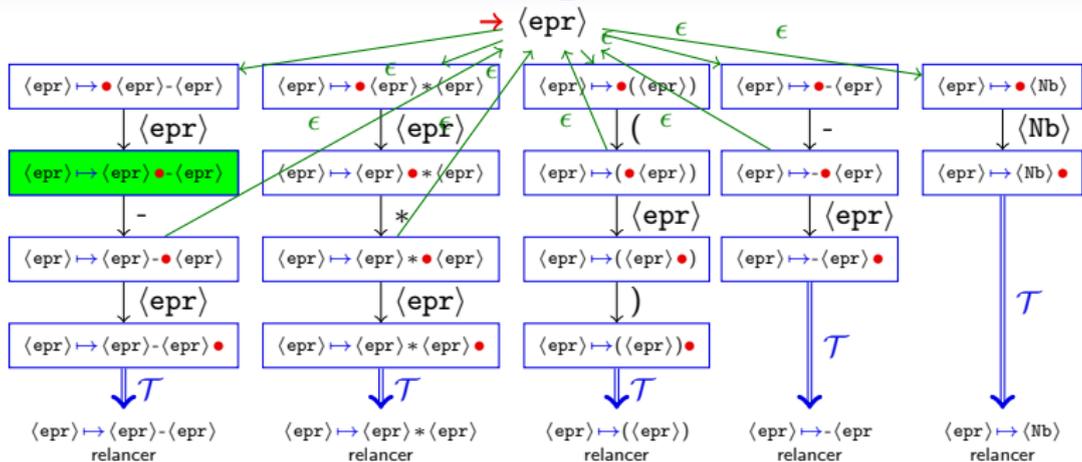
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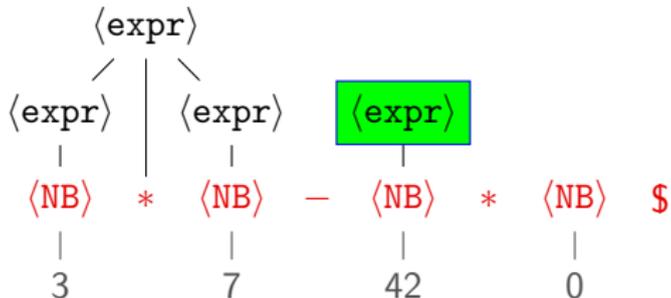
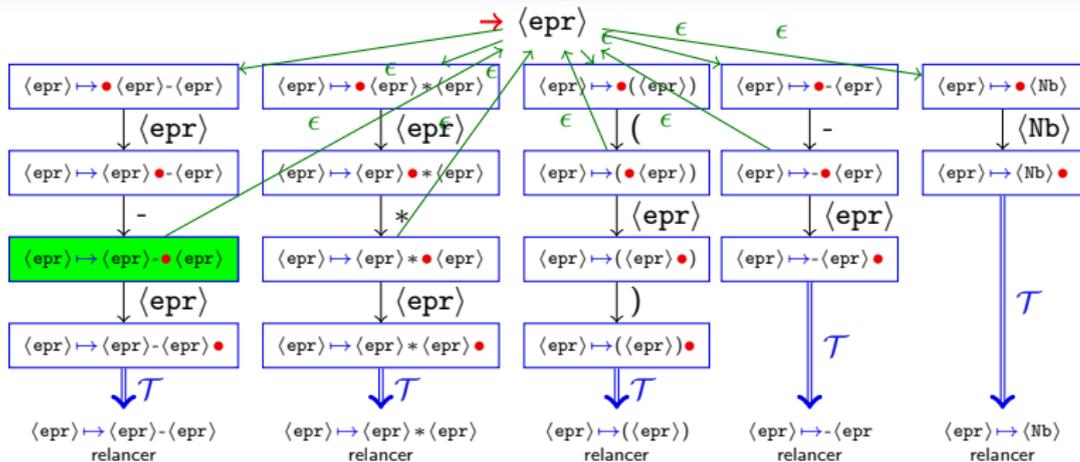
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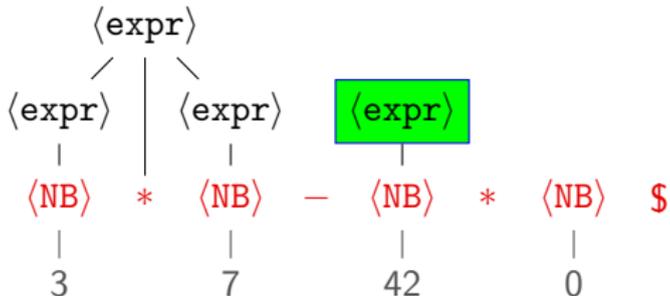
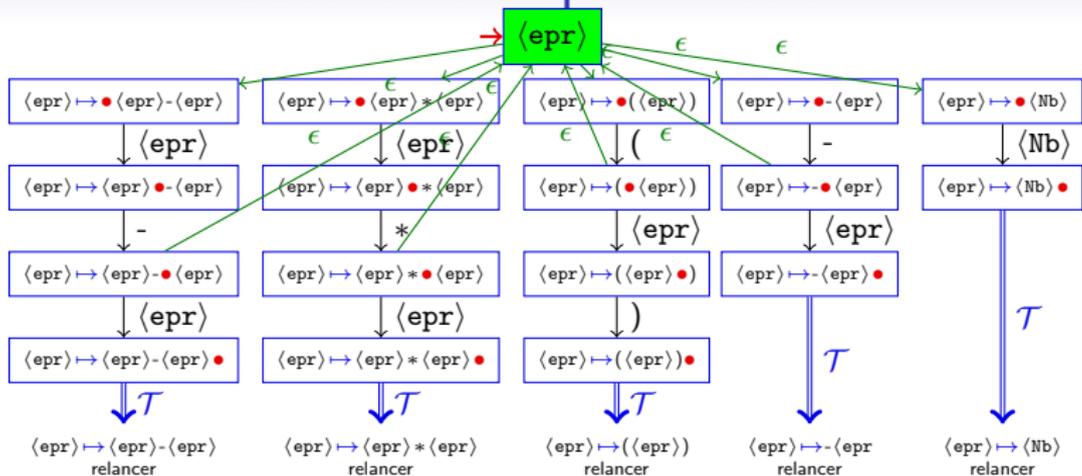
Second attempt in motion



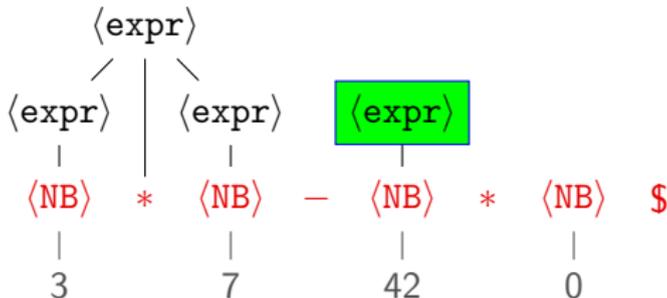
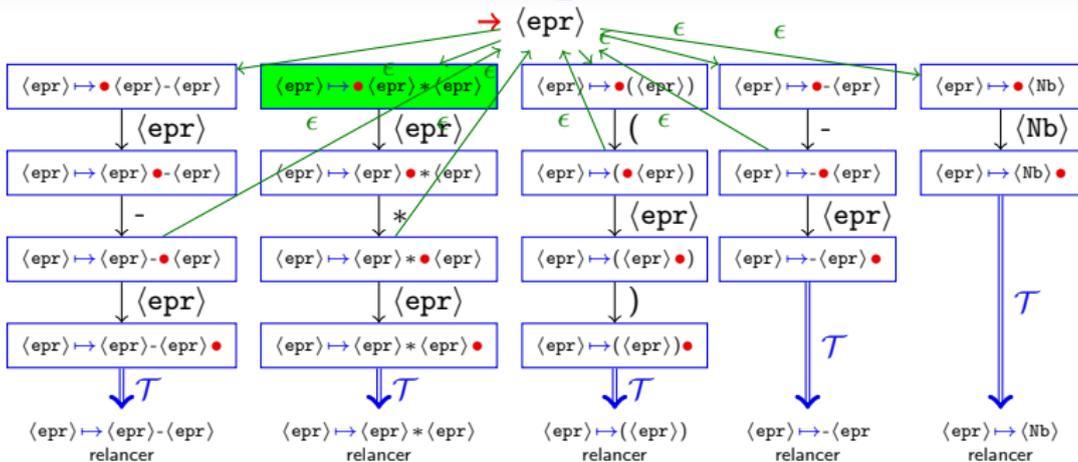
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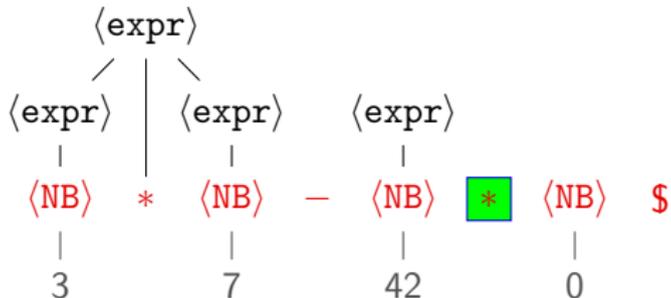
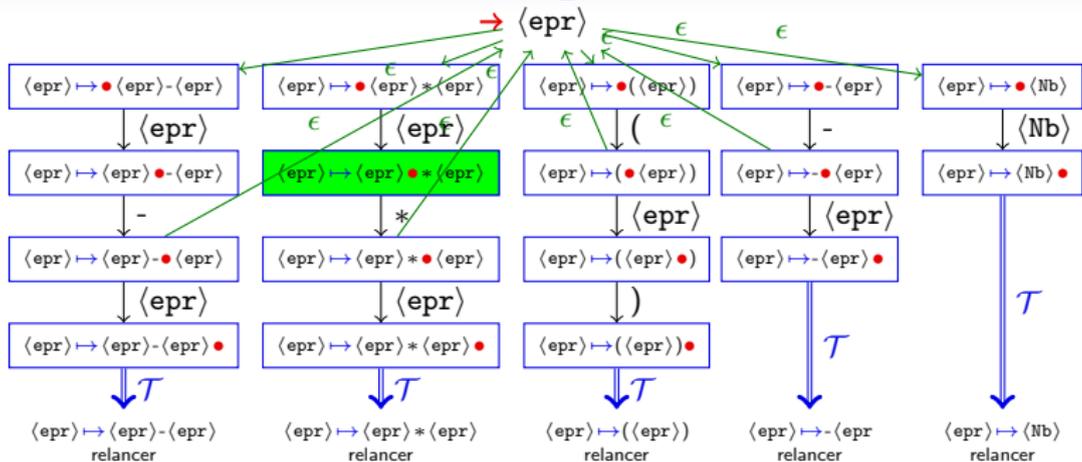
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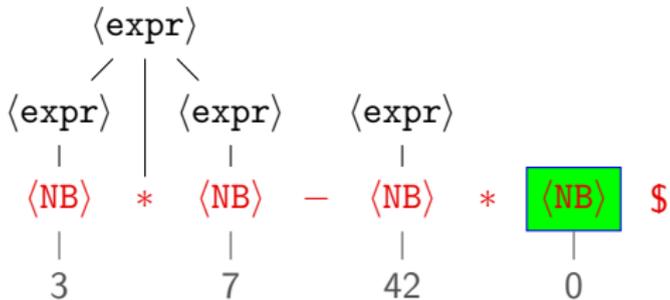
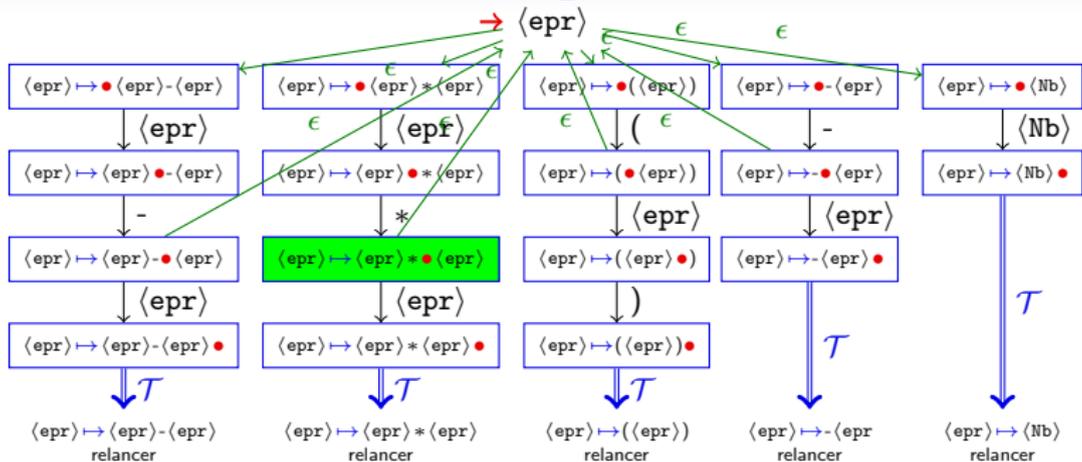
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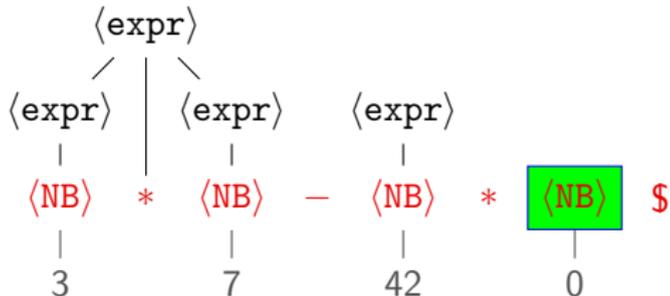
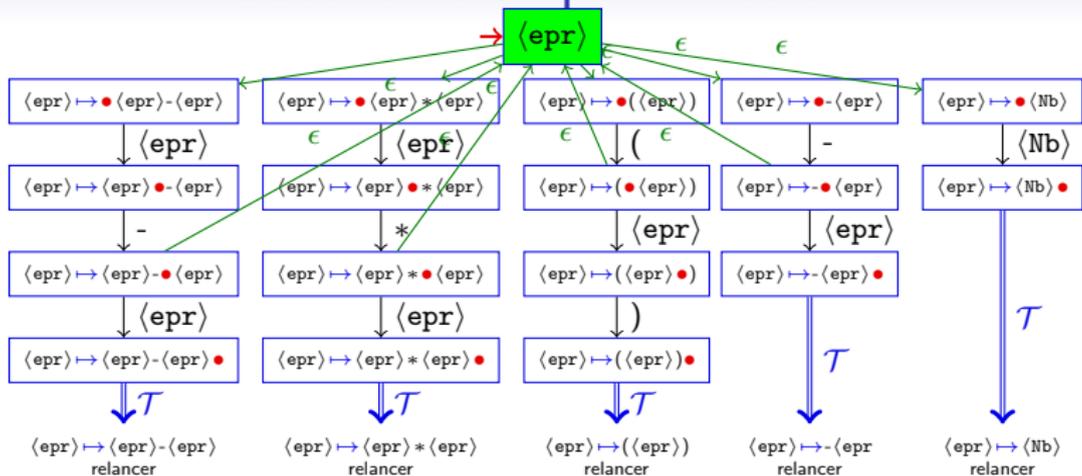
Second attempt in motion



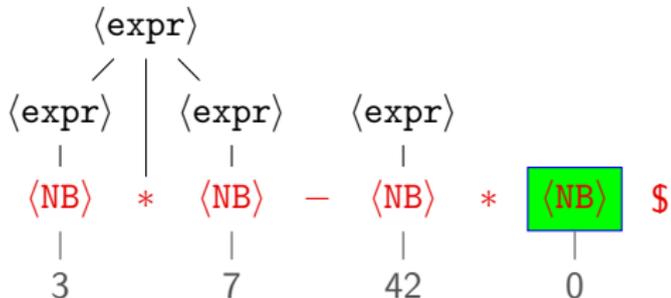
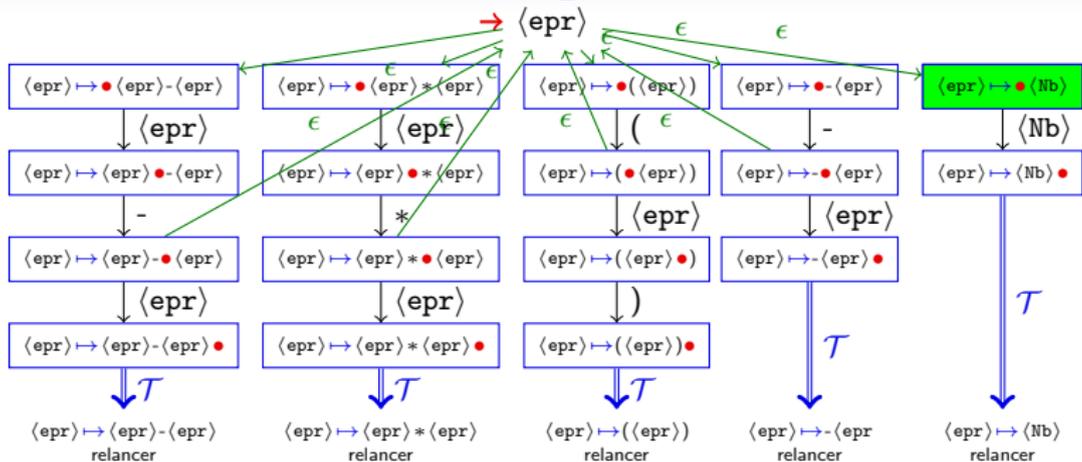
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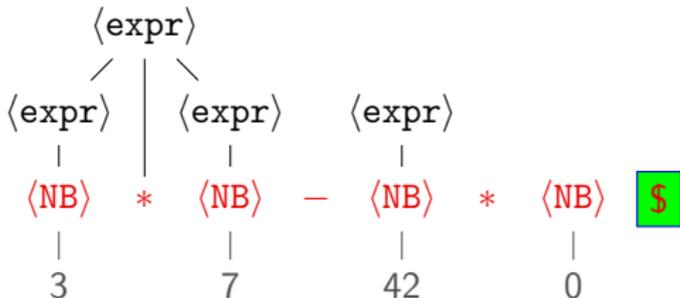
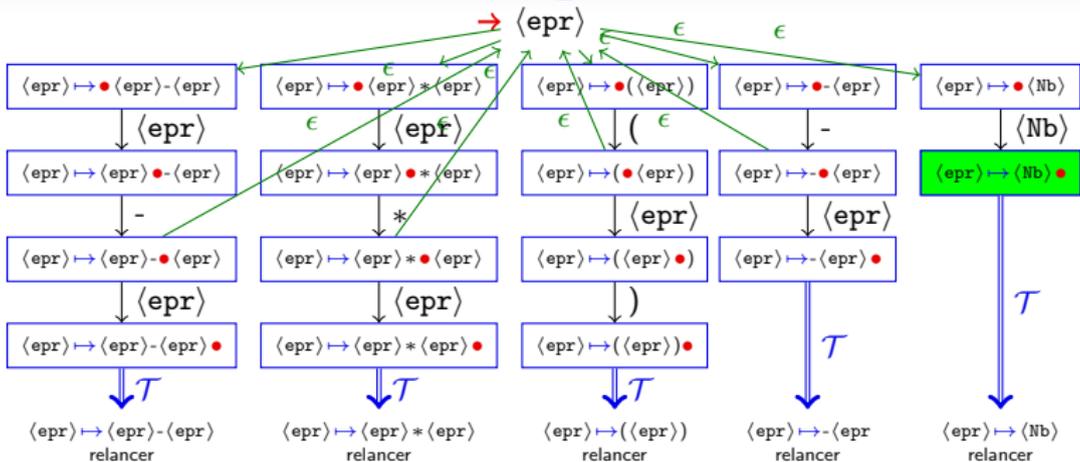
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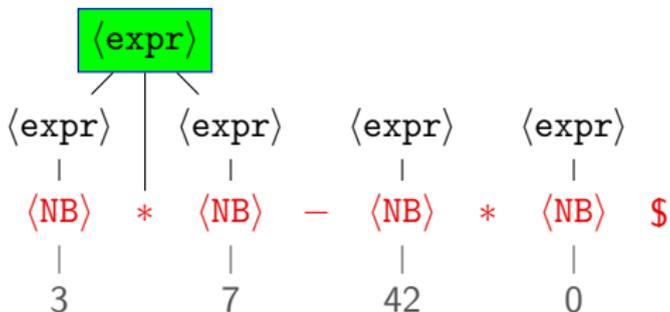
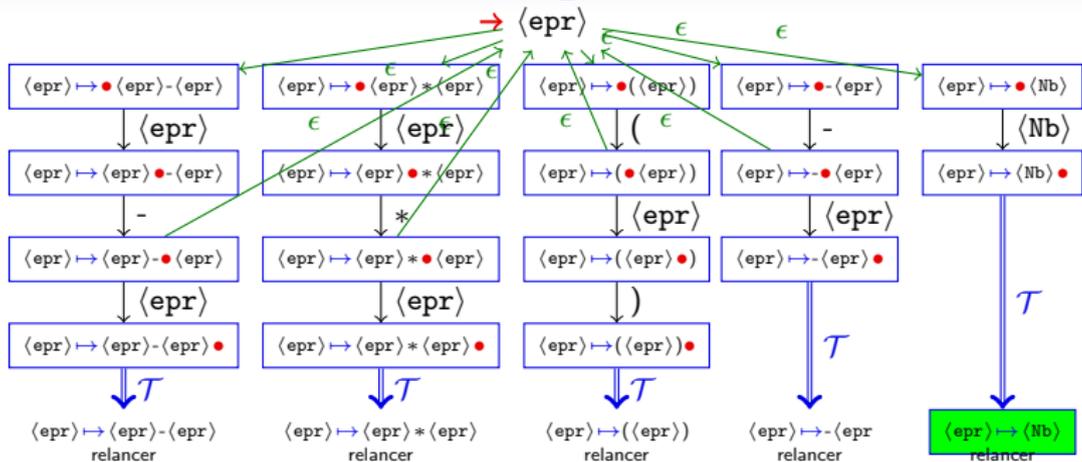
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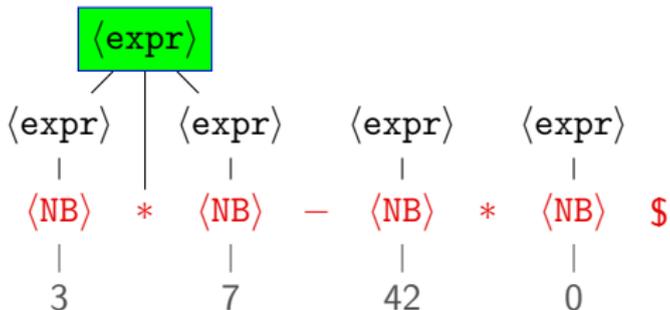
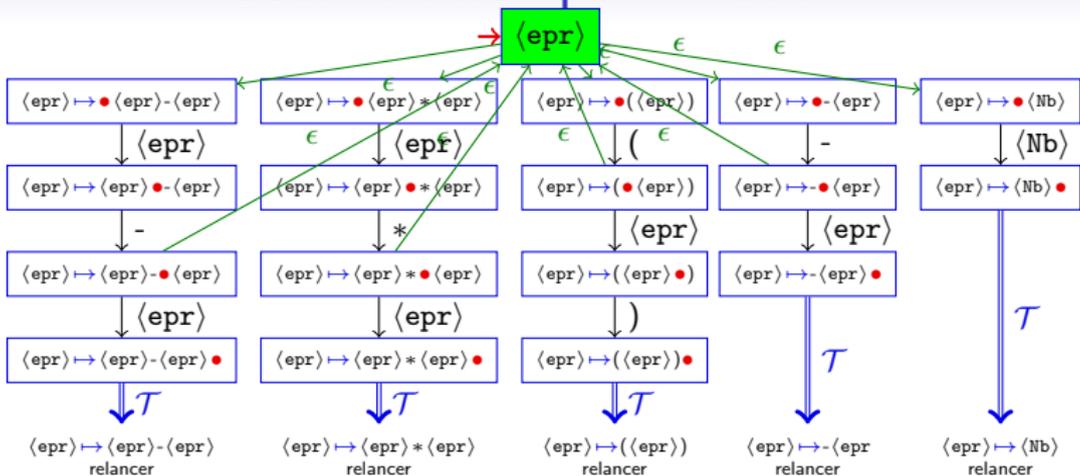
Second attempt in motion



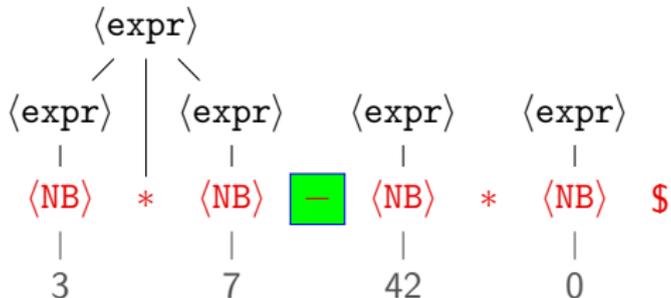
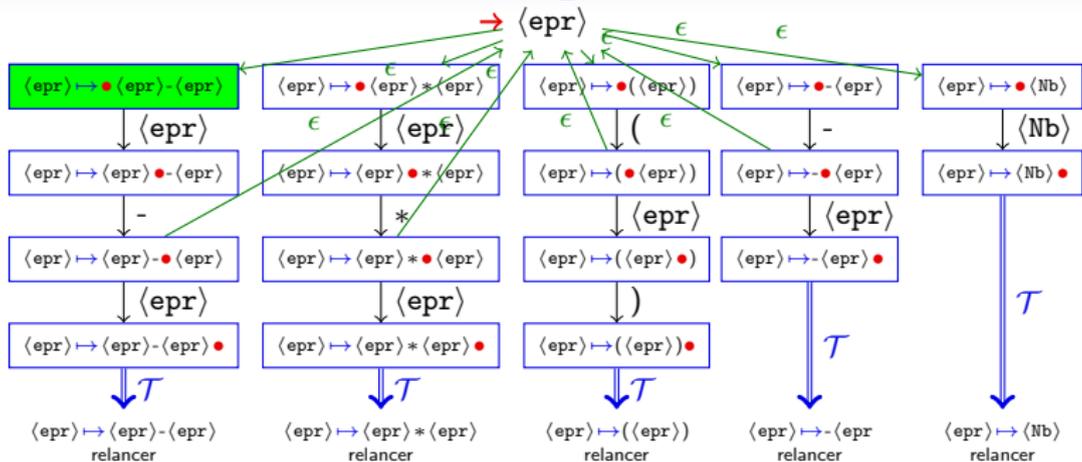
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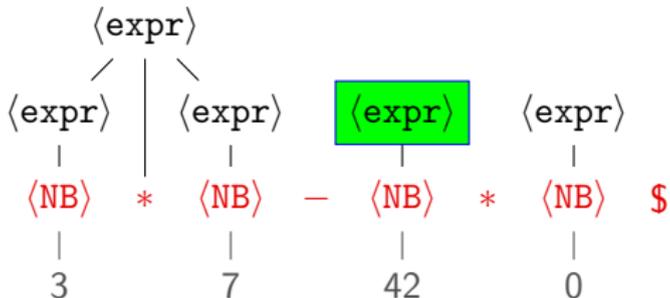
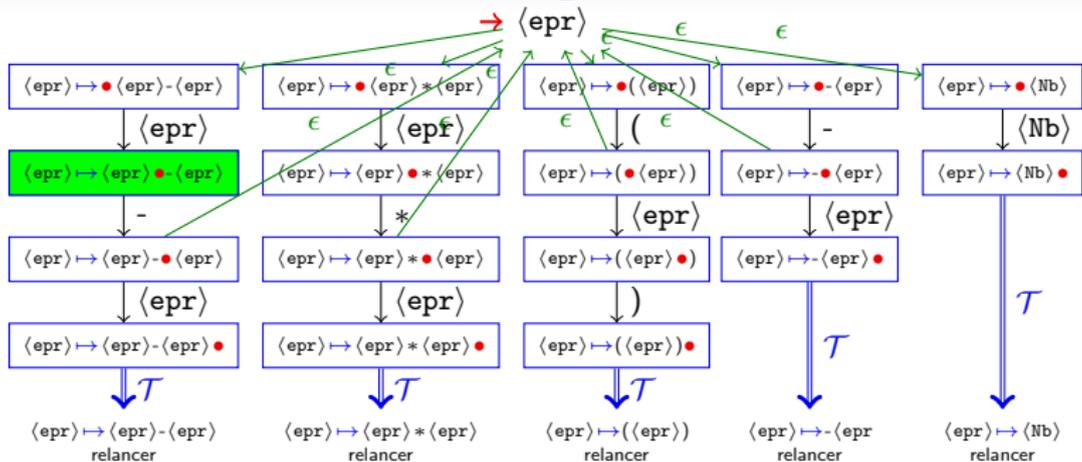
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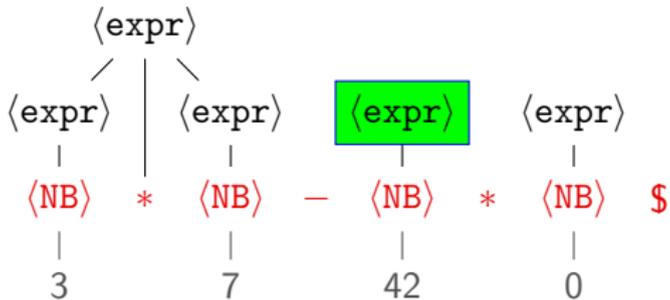
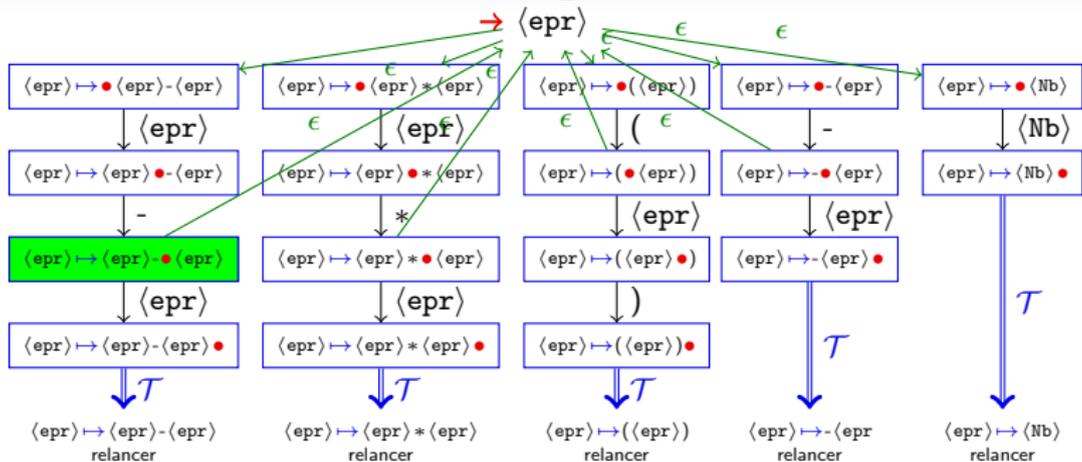
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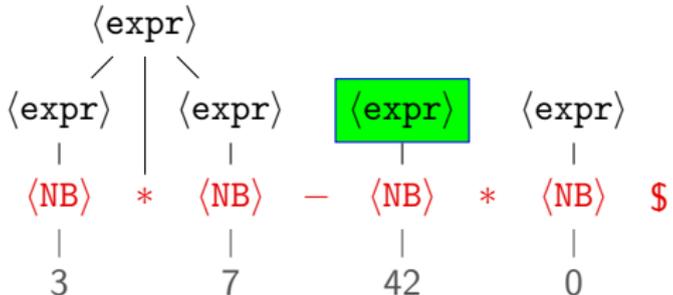
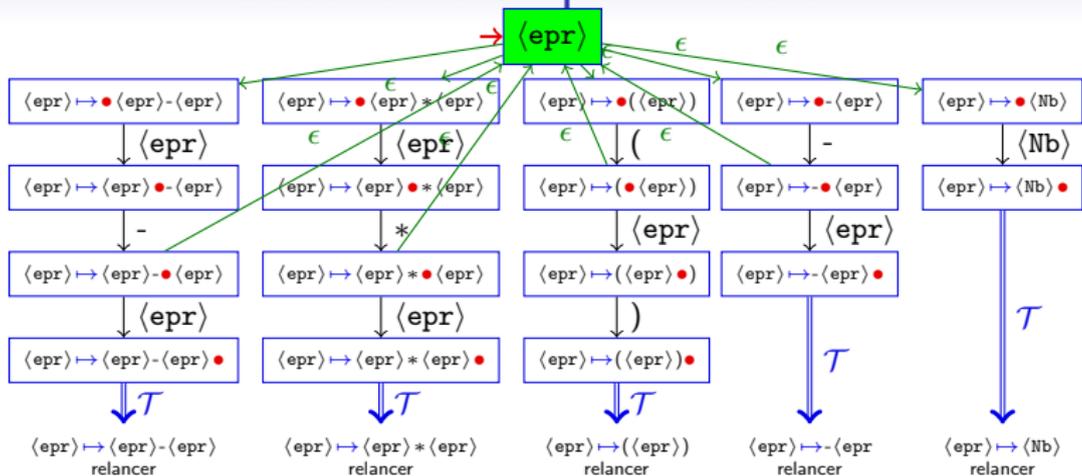
Second attempt in motion



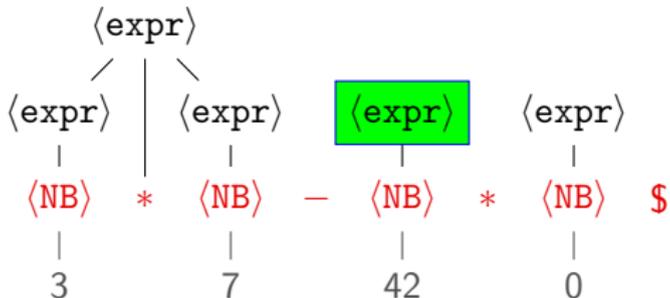
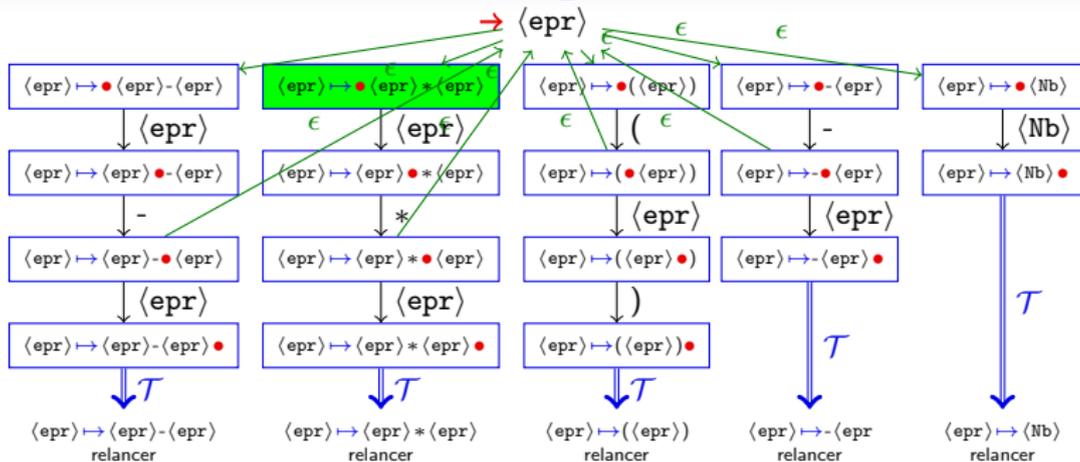
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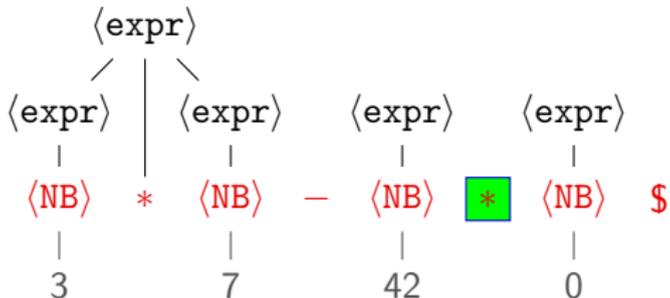
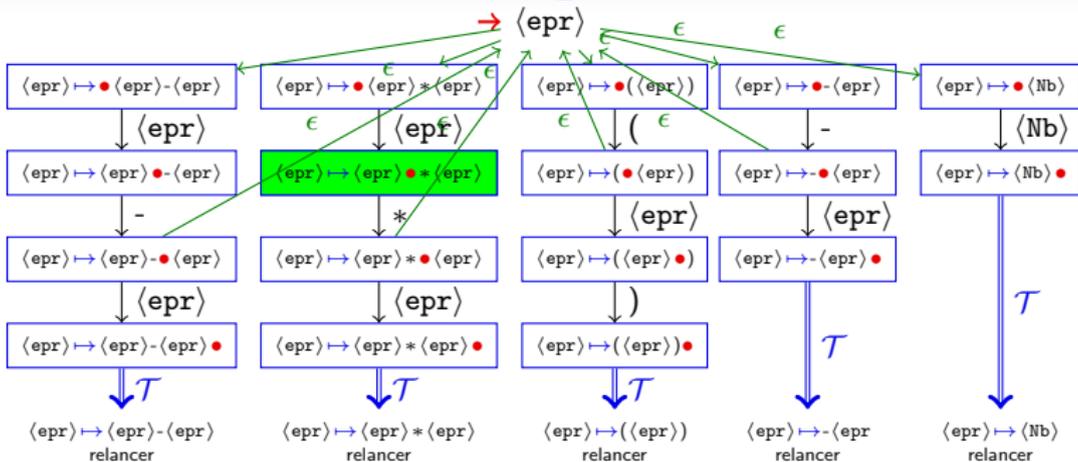
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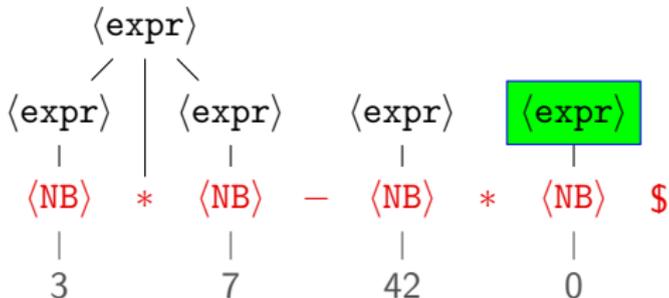
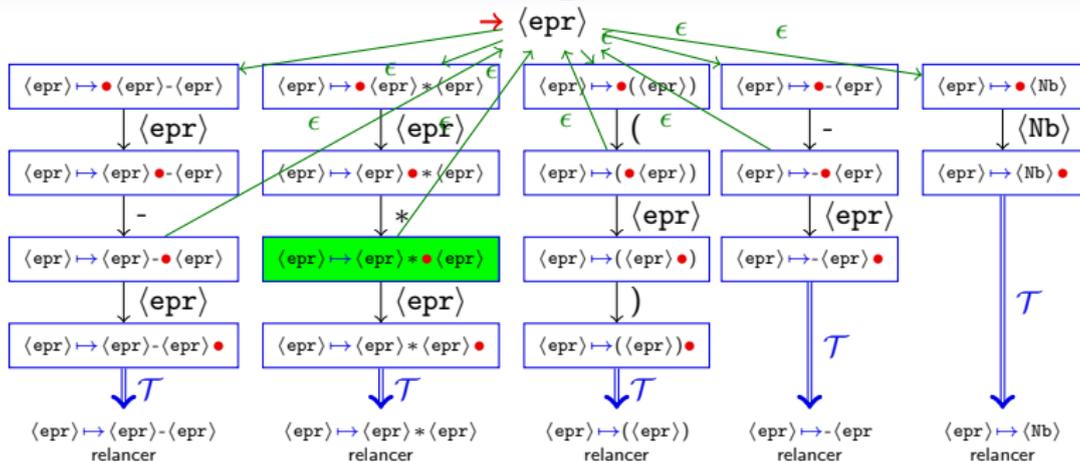
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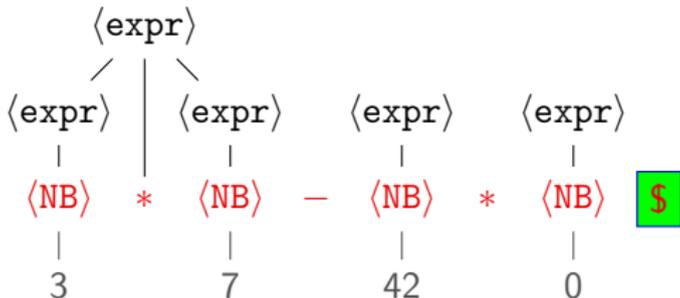
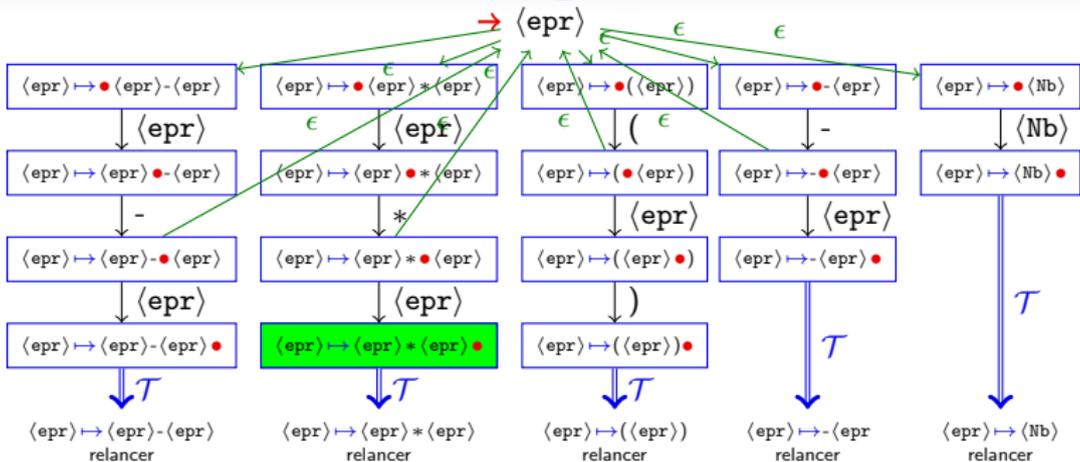
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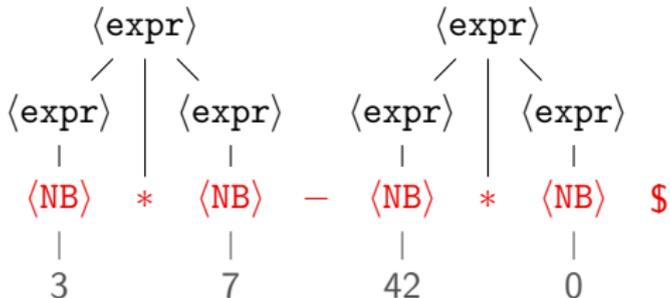
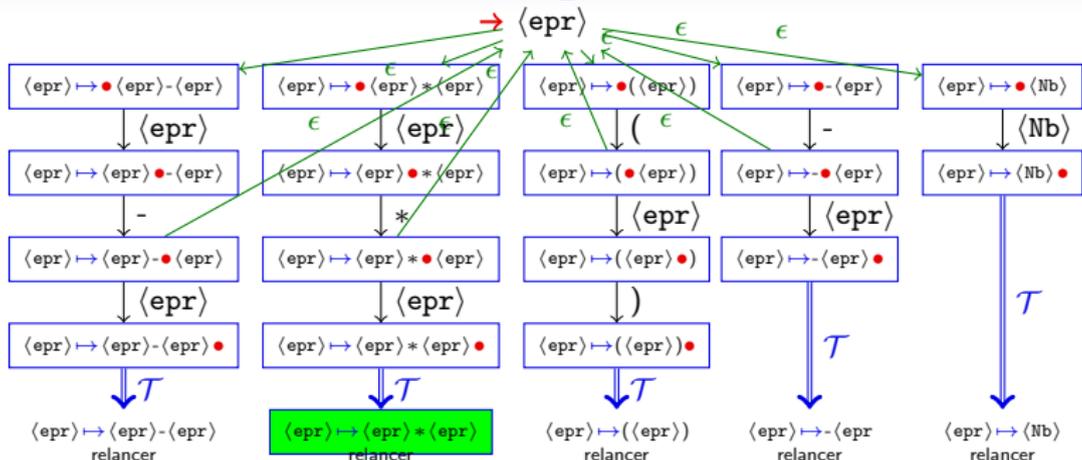
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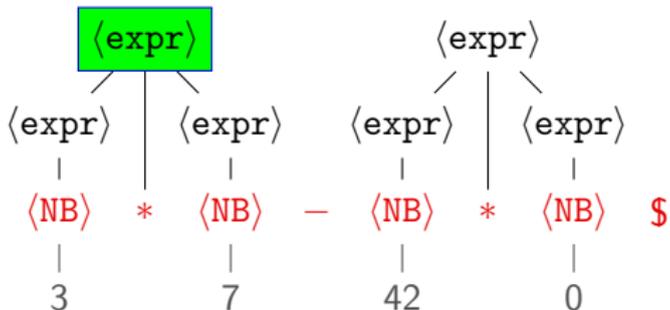
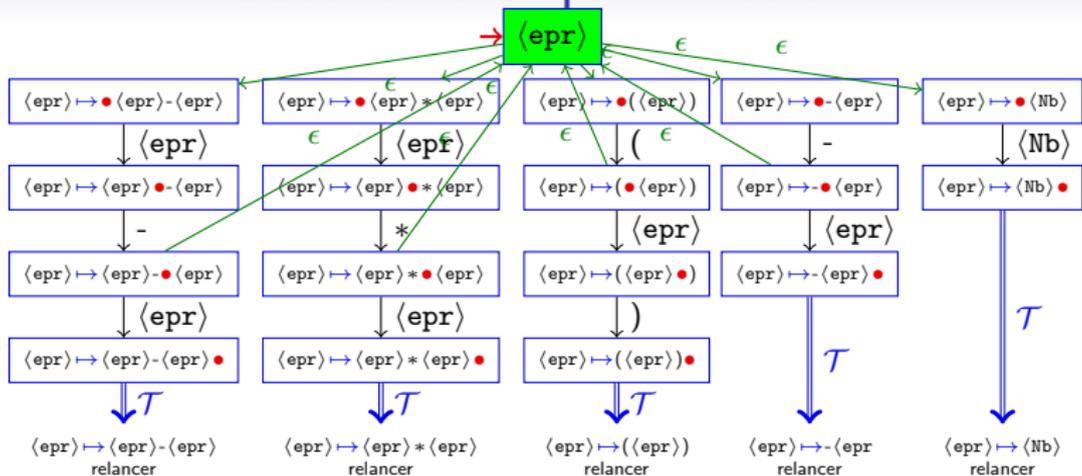
Second attempt in motion



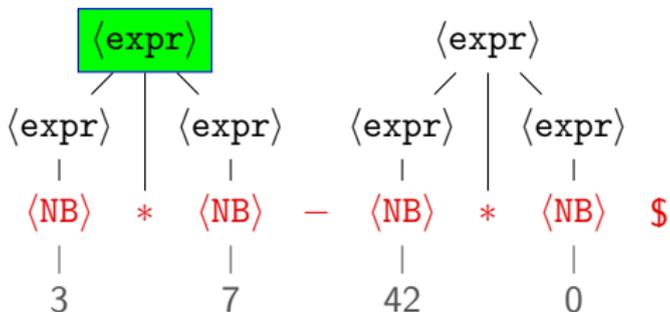
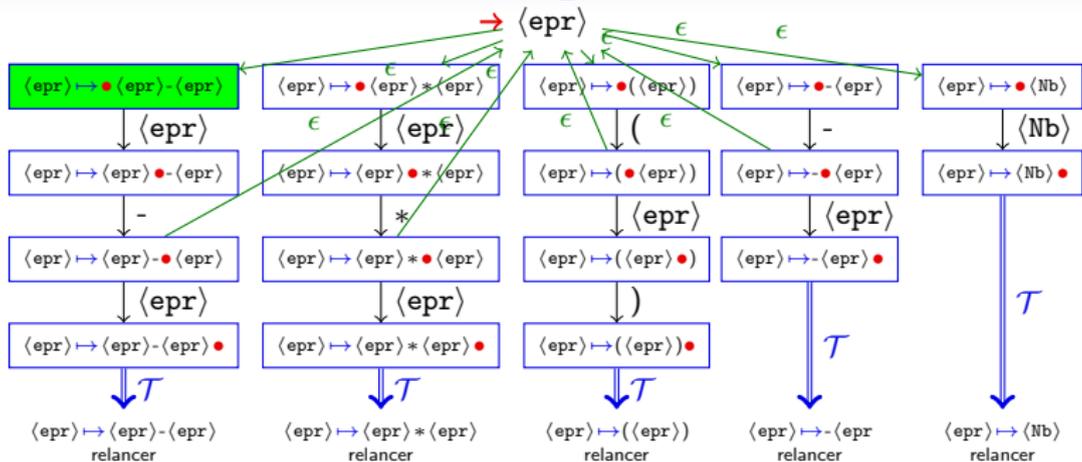
Second attempt in motion



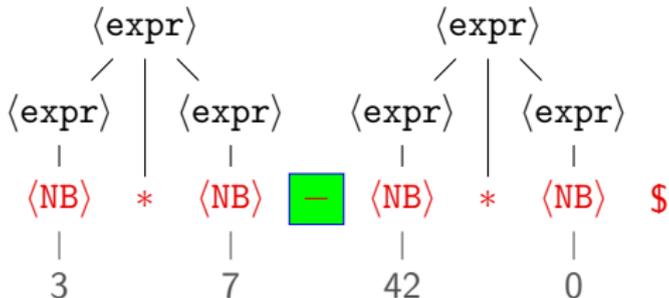
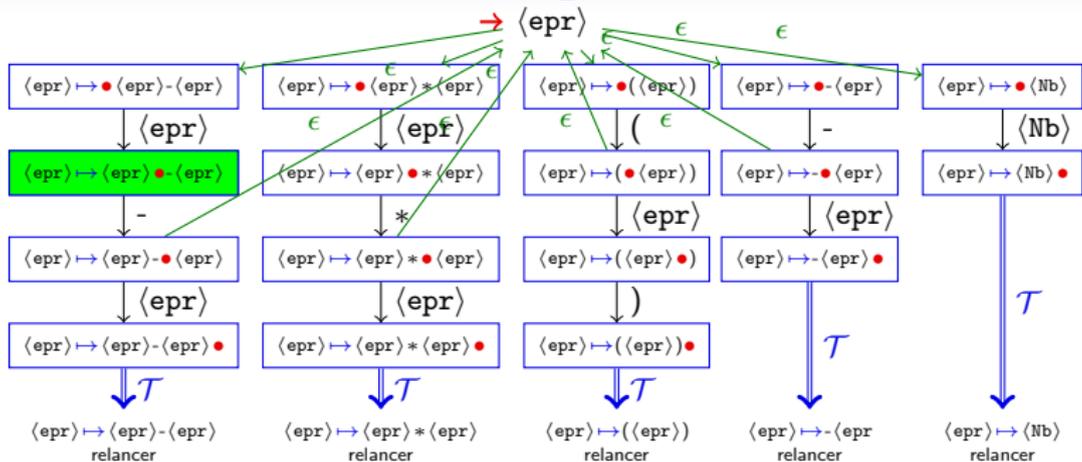
Second attempt in motion



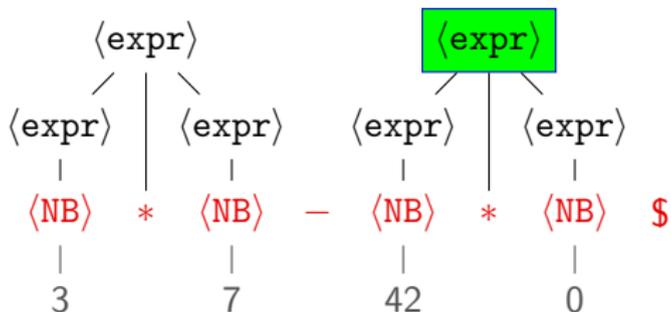
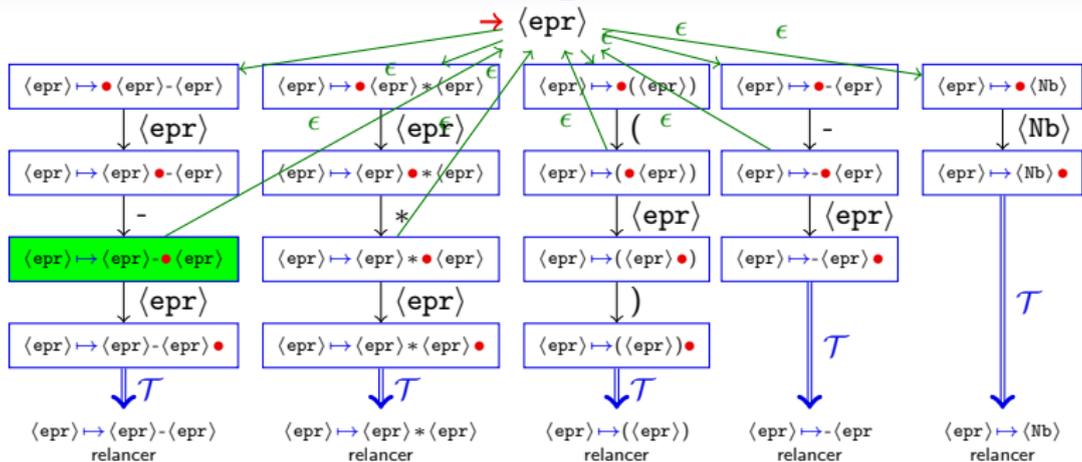
Second attempt in motion



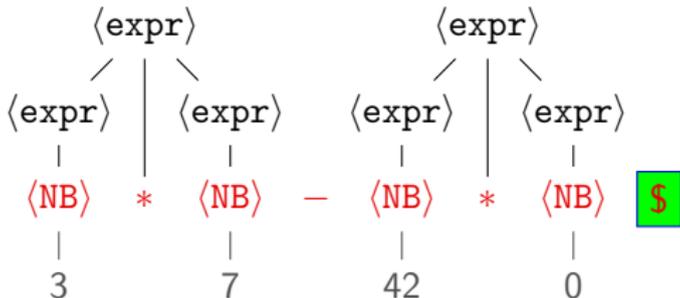
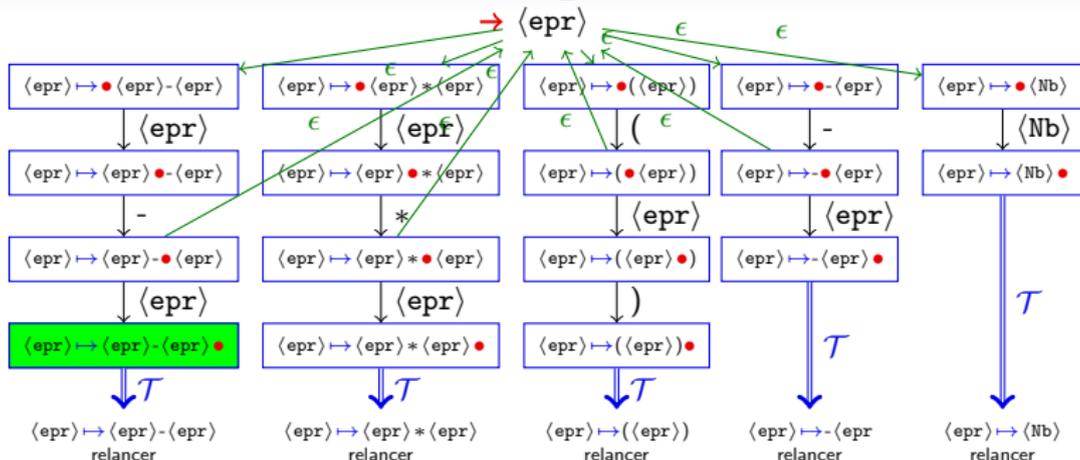
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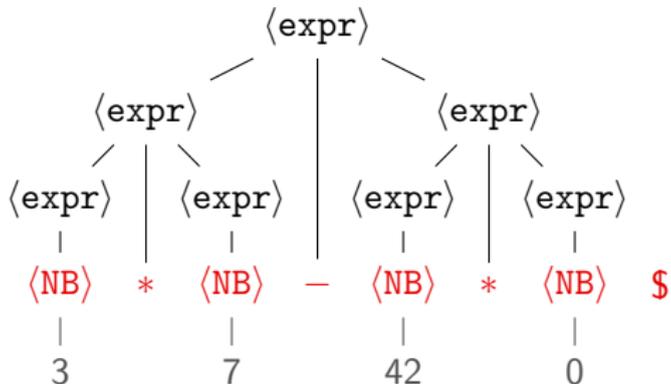
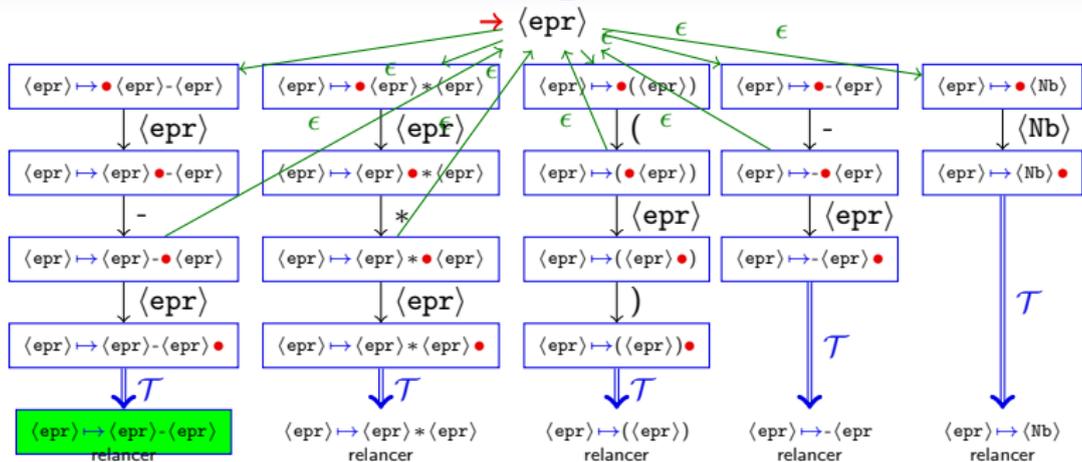
Second attempt in motion



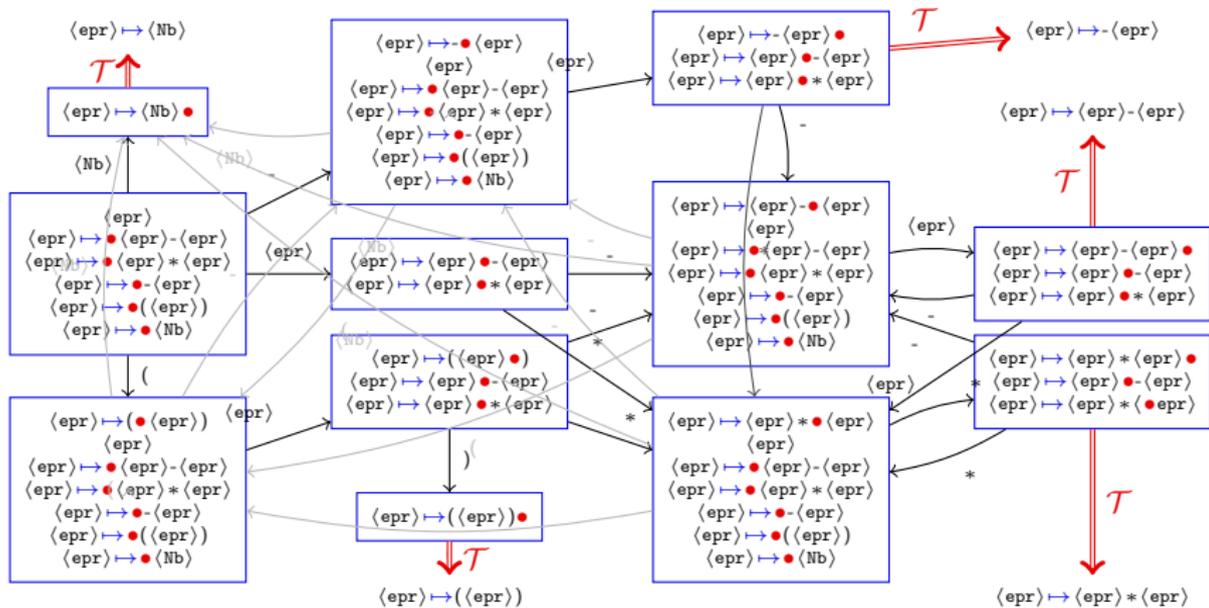
Second attempt in motion



Second attempt in motion



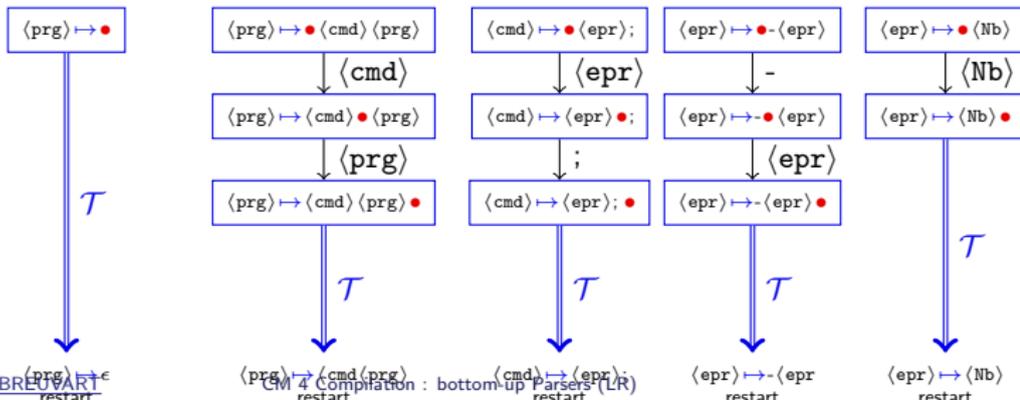
Pseudo-determinisation : LR₀ Parser



The Non-Deterministic Automaton

Let's try it again

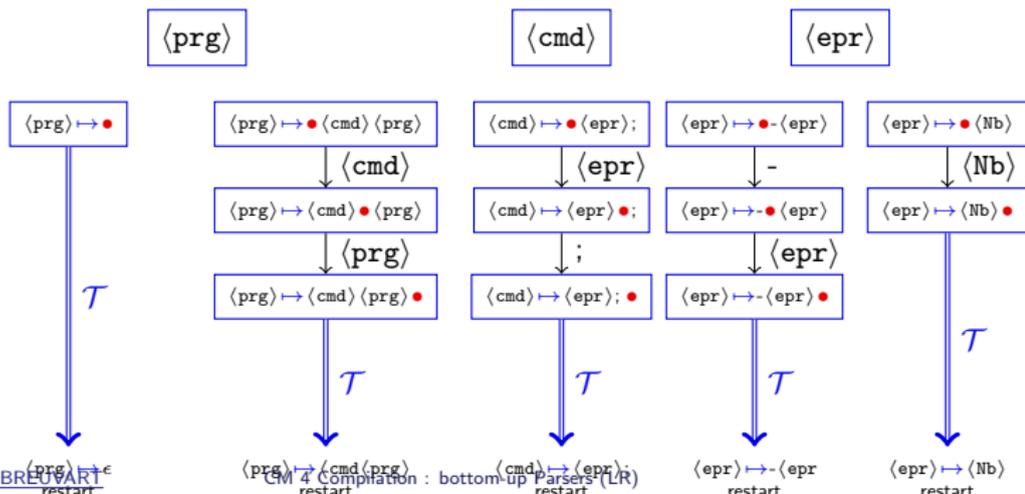
- shifts reading each rules,



The Non-Deterministic Automaton

Let's try it again

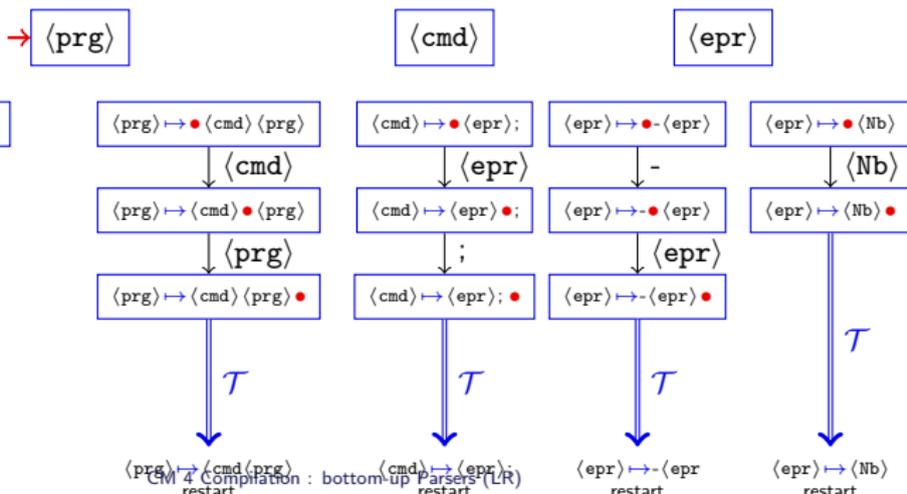
- shifts reading each rules,
- an additional state for each non-terminal N ,



The Non-Deterministic Automaton

Let's try it again

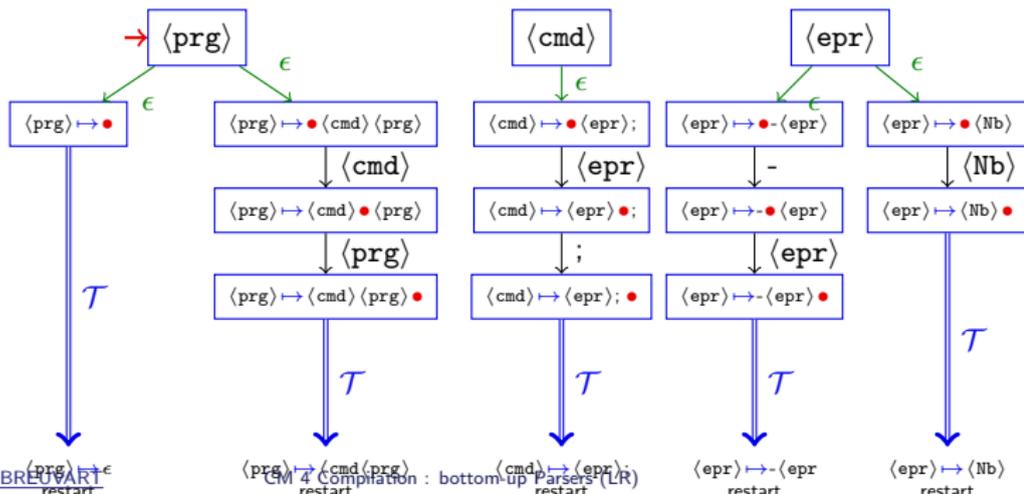
- shifts reading each rules,
- an additional state for each non-terminal N ,
- of which the principal is initial,



The Non-Deterministic Automaton

Let's try it again

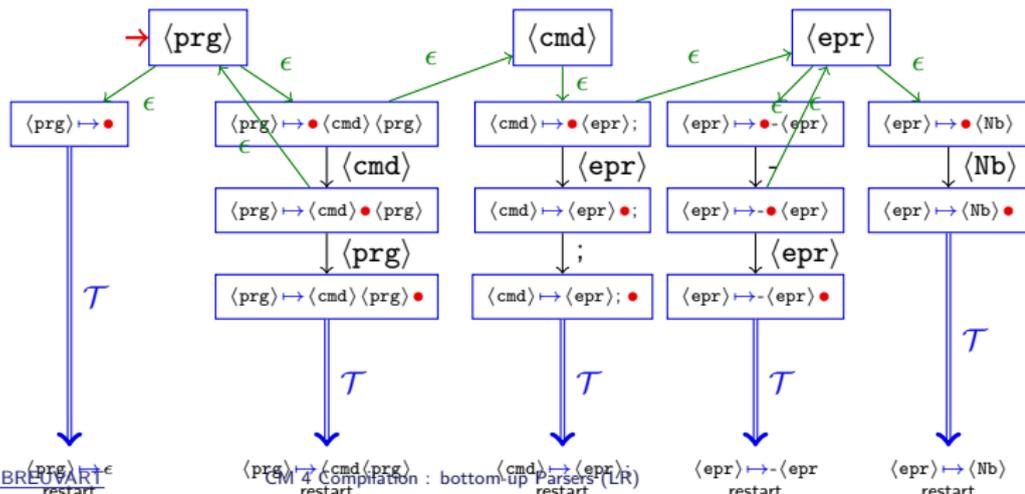
- shifts reading each rules,
- an additional state for each non-terminal N ,
- of which the principal is initial,
- add ϵ -transitions toward each rule,



The Non-Deterministic Automaton

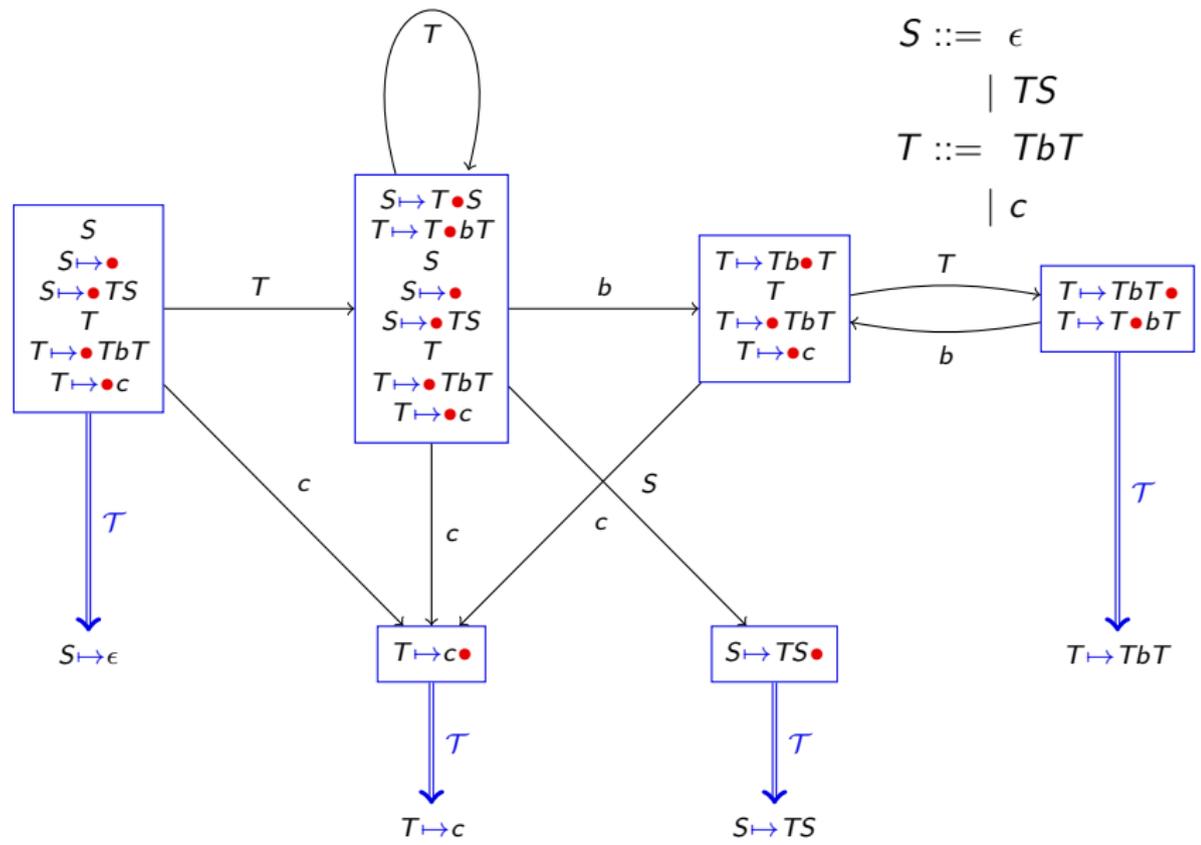
Let's try it again

- shifts reading each rules,
- an additional state for each non-terminal N ,
- of which the principal is initial,
- add ϵ -transitions toward each rule,
- for each state $M \mapsto w_1 \bullet N w_2$, add an ϵ -transition toward N

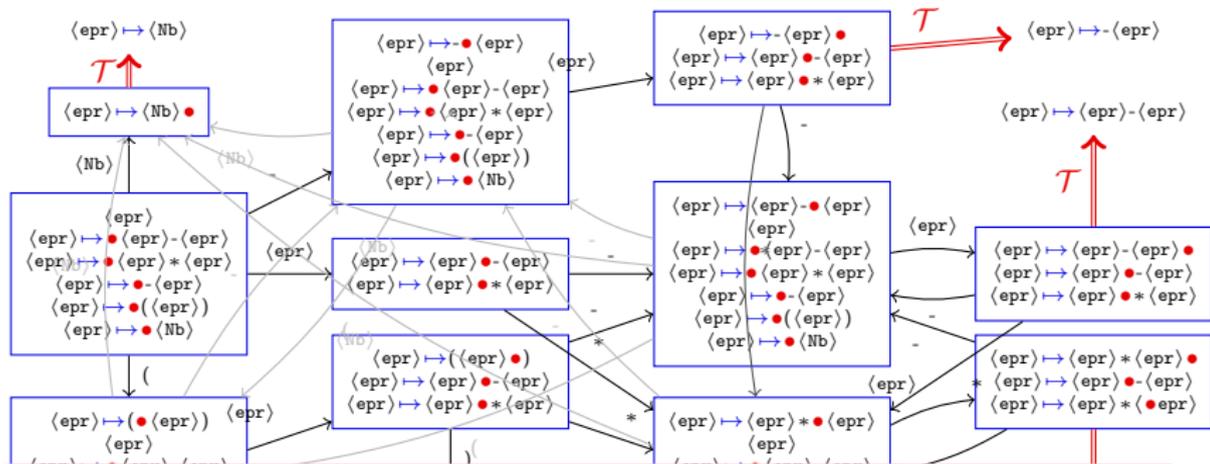


Pseudo-determinisation : Parser LR₀

$S ::= \epsilon$
 $\quad | TS$
 $T ::= TbT$
 $\quad | c$



Pseudo-determinisation : LR₀ Parser



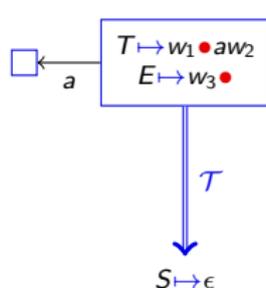
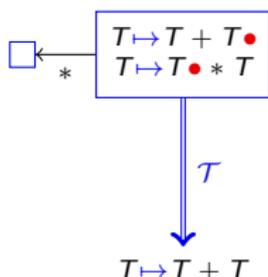
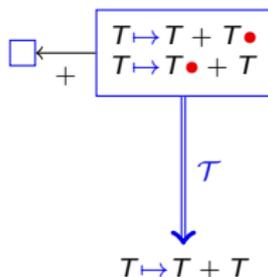
Conflict resolution

Remark: we will use the word “reduce” for “action” to match literature

- Precedence : solve some shift-action and action-action conflicts
- Associativity : solve other shift-action conflicts
- But not always sufficient to solve conflicts...

A grammar which LR₀ parser is deterministic is called a LR₀ grammar

Some usual conflicts



Associativity

right associativity :
 ↳ choose the shift

left associativity :
 ↳ choose the action

Precedence

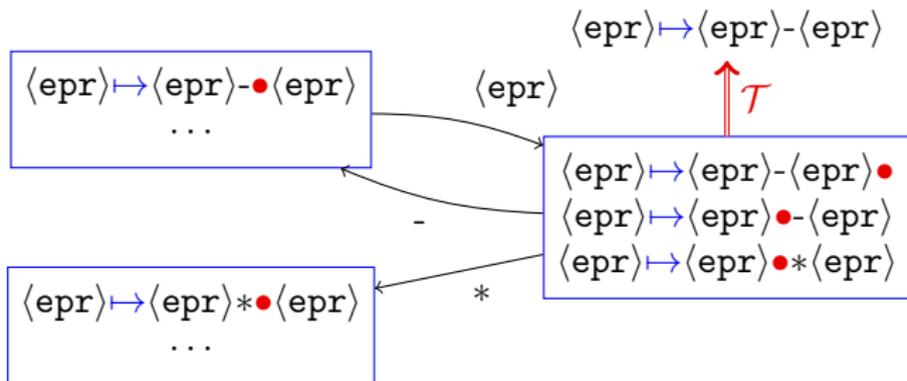
* precedence :
 ↳ choose the shift

+ precedence :
 ↳ choose the action

Not arising from ambiguity

eg, when no a after S
 Need of stronger algo
 ↳ SLR, LALR, LR1 ...

Conflicts solved by precedence and associativity



Shift/reduce from precedence

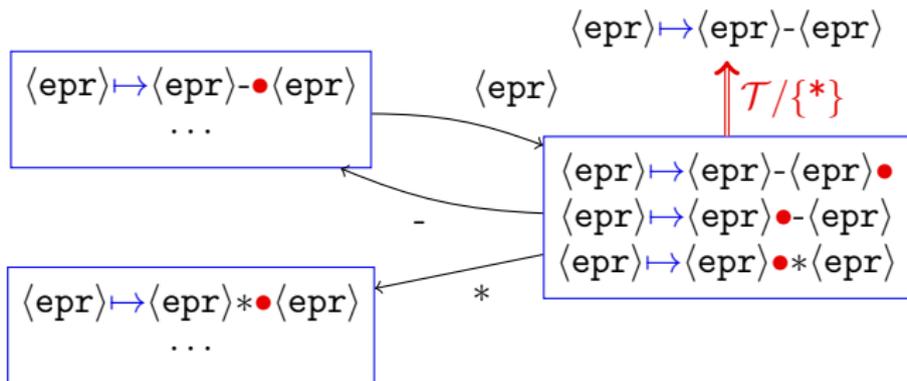
$\langle \text{epr} \rangle \mapsto \langle \text{epr} \rangle \bullet * \langle \text{epr} \rangle$

vs

$\langle \text{epr} \rangle \mapsto \langle \text{epr} \rangle - \langle \text{epr} \rangle \bullet$

Choose the prioritized rule

Conflicts solved by precedence and associativity



Shift/reduce from precedence

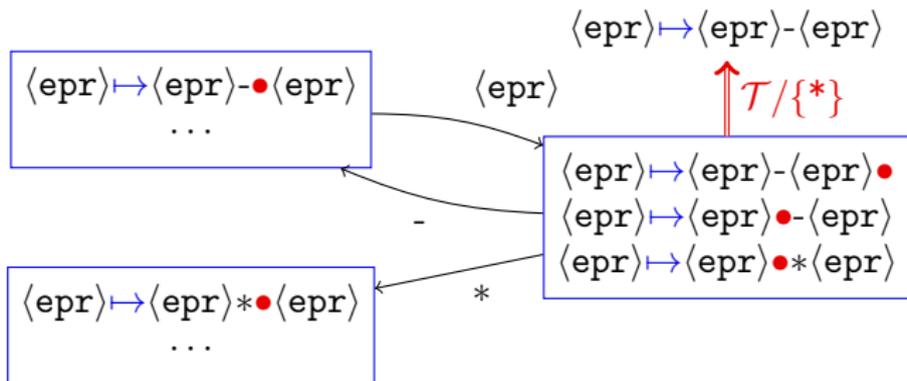
$\langle \text{expr} \rangle \rightarrow \langle \text{expr} \rangle \bullet * \langle \text{expr} \rangle$

vs

$\langle \text{expr} \rangle \rightarrow \langle \text{expr} \rangle - \langle \text{expr} \rangle \bullet$

Choose the prioritized rule

Conflicts solved by precedence and associativity



Shift/reduce from precedence

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle \bullet * \langle \text{expr} \rangle$

vs

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle - \langle \text{expr} \rangle \bullet$

Choose the prioritized rule

Shift/reduce from associativity

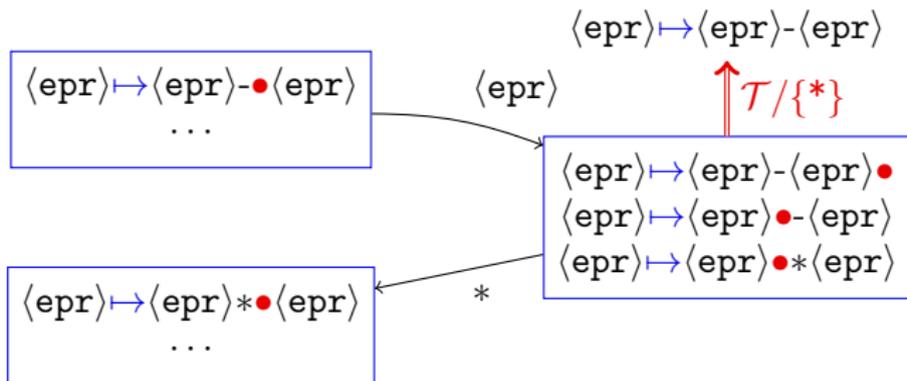
$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle \bullet - \langle \text{expr} \rangle$

vs

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle - \langle \text{expr} \rangle \bullet$

Choose the shift if right asso.
 Choose reduce reduce if right asso.

Conflicts solved by precedence and associativity



Shift/reduce from precedence

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle \bullet * \langle \text{expr} \rangle$

vs

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle - \langle \text{expr} \rangle \bullet$

Choose the prioritized rule

Shift/reduce from associativity

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle \bullet - \langle \text{expr} \rangle$

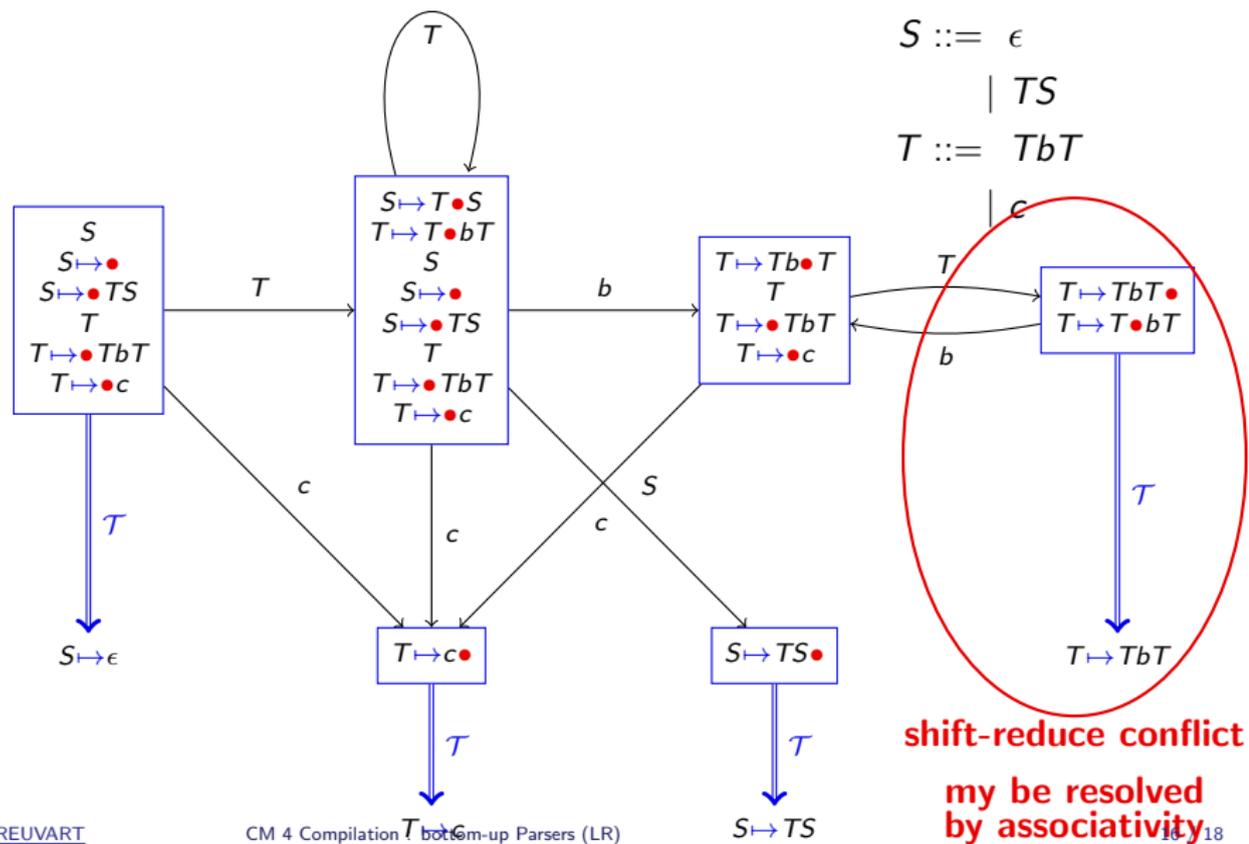
vs

$\langle \text{expr} \rangle \mapsto \langle \text{expr} \rangle - \langle \text{expr} \rangle \bullet$

Choose the shift if right asso.
 Choose reduce reduce if right asso.

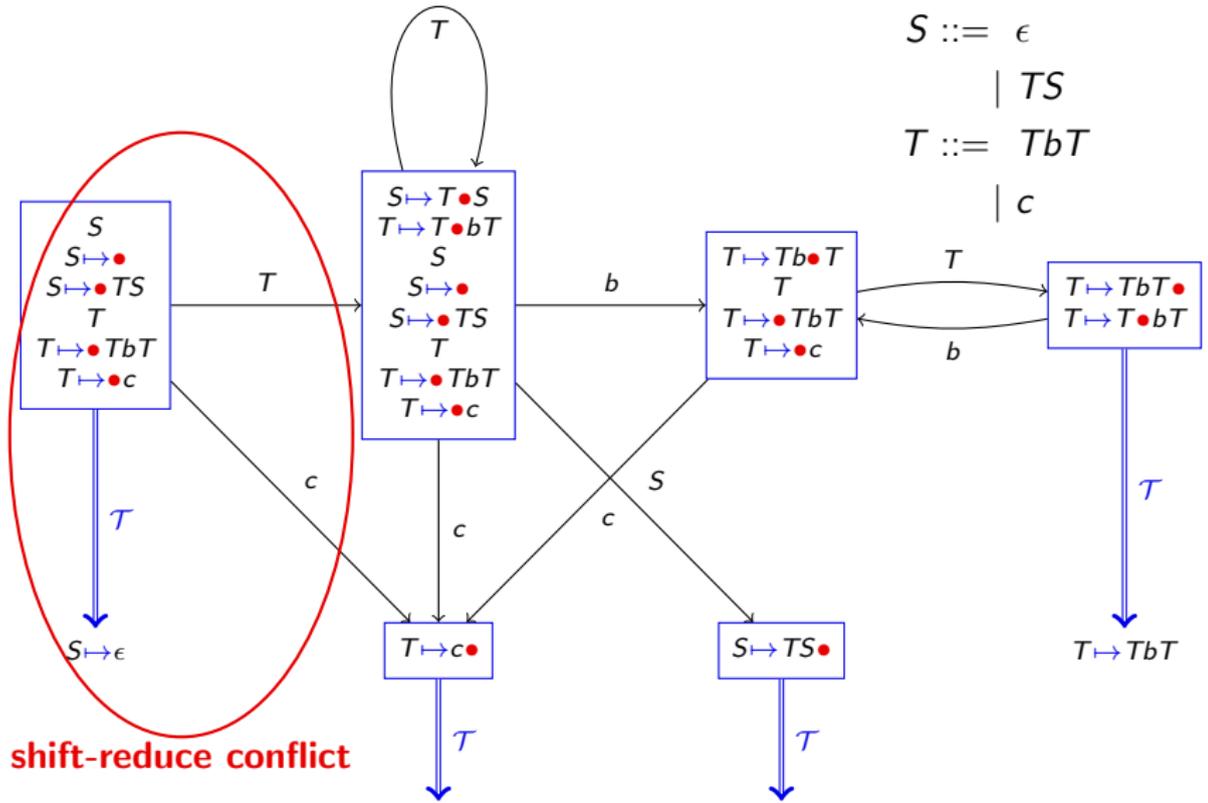
Warning: decision-making differs drastically from the lexer's.

Warning, "non-ambiguous" conflicts may remain



Warning, "non-ambiguous" conflicts may remain

$S ::= \epsilon$
 $\quad | TS$
 $T ::= TbT$
 $\quad | c$

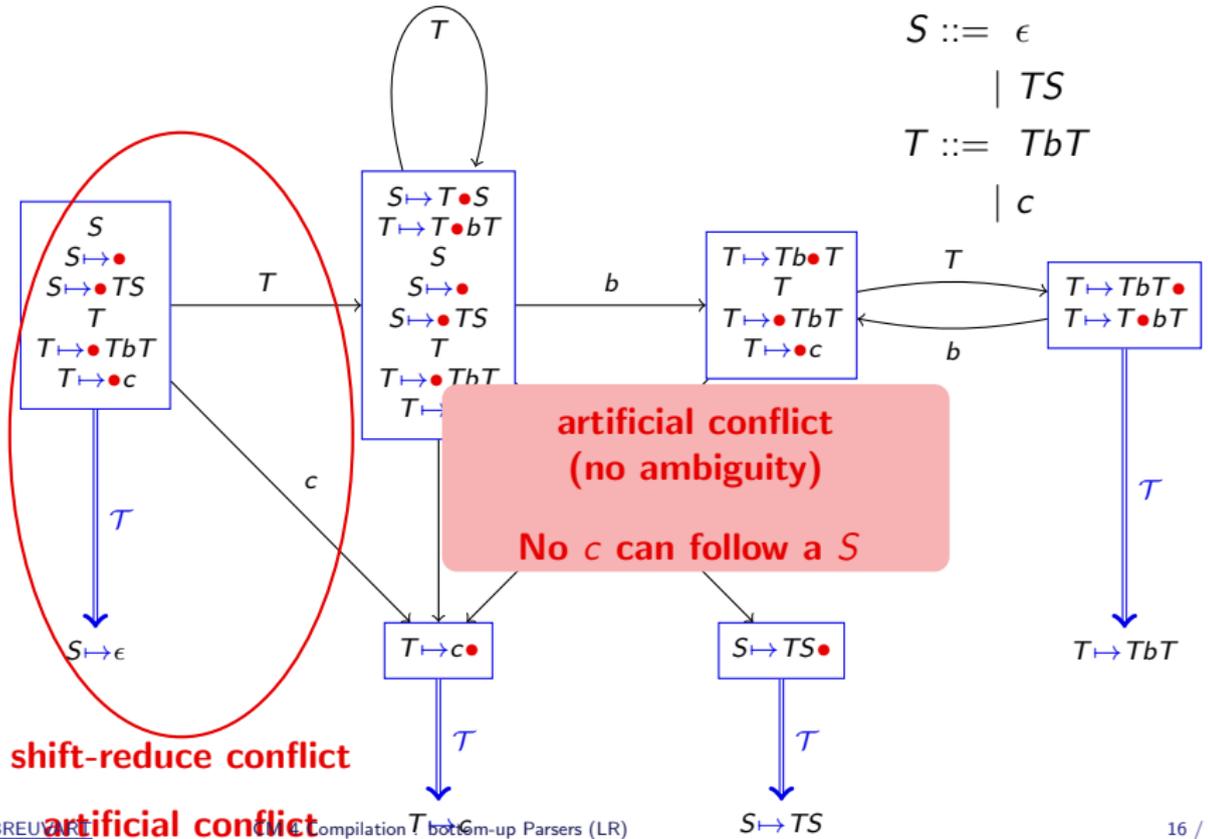


shift-reduce conflict

artificial conflict

Warning, "non-ambiguous" conflicts may remain

$S ::= \epsilon$
 $\quad | TS$
 $T ::= TbT$
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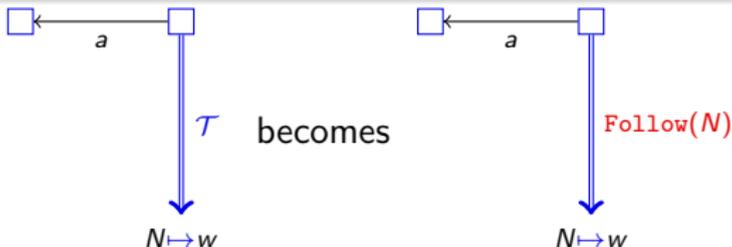
SLR Parser: narrowing conditions of actions

If a would-be NT can't be followed by peeked at terminal there is no reason to take the action

This is why we compute **“follows”** :
 the set of terminals that may eventually follow a given non-terminal.

Idea : narrowing reductions paths to *Follows* only

Same construction as LR₀ except that reduction action $N \mapsto w$ are are narrowed to $\text{Follow}(N)$ (before or after determinisation).



“Firsts” : terminals that may eventually start a non-terminal

Prior to “follows”, let’s look at easier “firsts”

Definition of $\text{First}_G(N) \subseteq \mathcal{T} \cup \{\epsilon\}$

$c \in \text{First}_G(N) \iff \left\{ \begin{array}{l} \text{there exists a syntactic tree } G \text{ rooted by } N \\ \text{which leftmost terminal leaf is } c. \end{array} \right.$

Example with

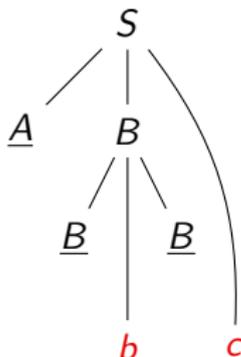
$S ::= ABc$

$A ::= \epsilon$

| aA

$B ::= \epsilon$

| BbB



Thus

$b \in \text{First}(S)$

“Follows” : terminals that may eventually follow a non-terminal.

Definitions of $\text{Follow}_G(N) \subseteq \cup\cup\{\$\}$

$c \in \text{Follow}_G(N) \iff \left\{ \begin{array}{l} \text{There exists a ST } G \text{ with an internal node } N \\ \text{which leftmost terminal leaf RIGHT OF } N \text{ is } c. \end{array} \right.$

Example ins

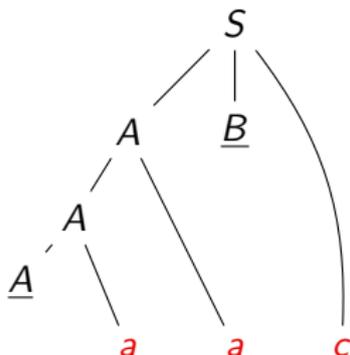
$S ::= ABC$

$A ::= \epsilon$

| aA

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| BbB



Thus

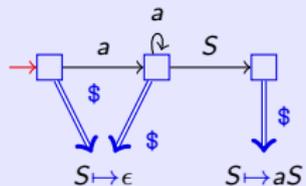
$a \in \text{Follow}(A)$

$c \in \text{Follow}(A)$

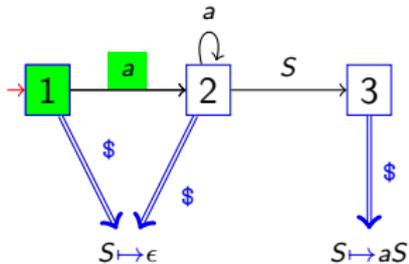
Optimization : linear time

The constructed SLR automaton can be of quadratic complexity

The grammar $S := aS|\epsilon$ produce the automaton :

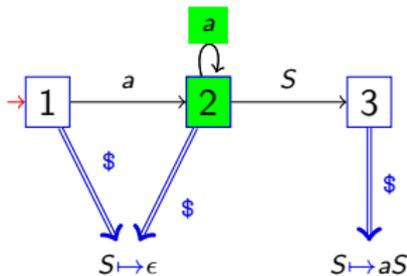


Example of non-linear execution



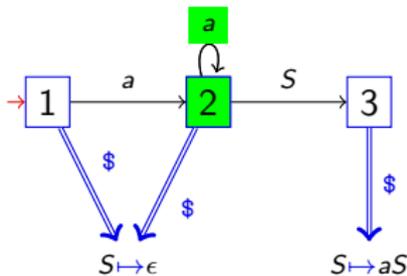
Mot lu : **a** a a a a a a a a a \$

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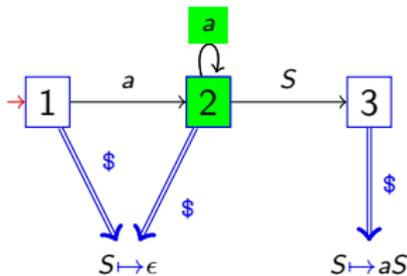
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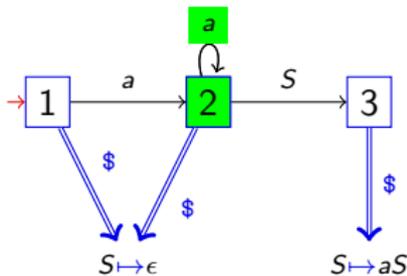
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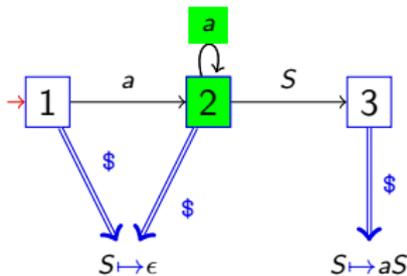
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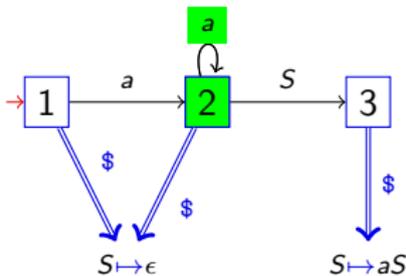
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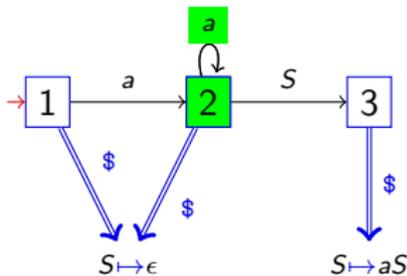
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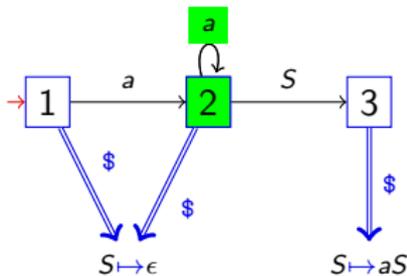
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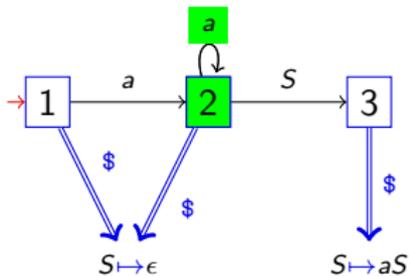
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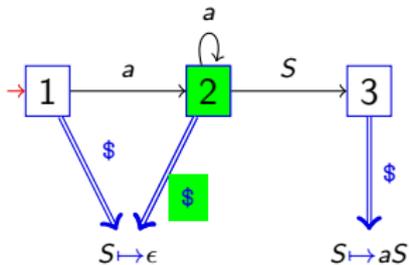
Mot lu : a a a a a a a a **a** a \$

Example of non-linear execution



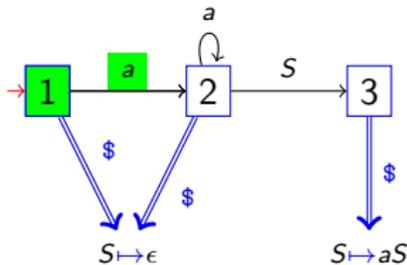
Mot lu : a a a a a a a a a **a** \$

Example of non-linear execution



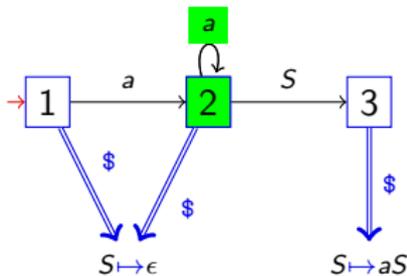
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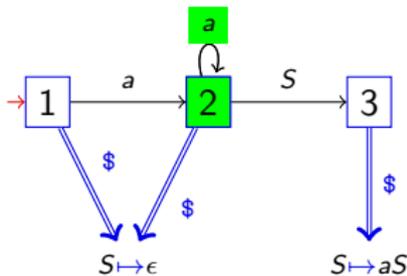
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Example of non-linear execution



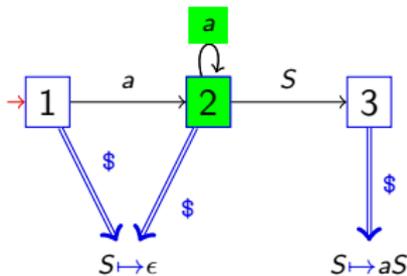
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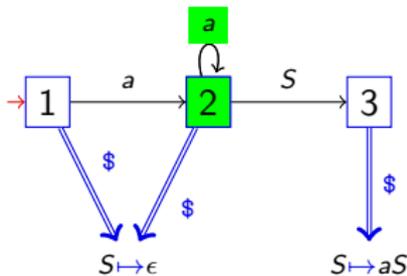
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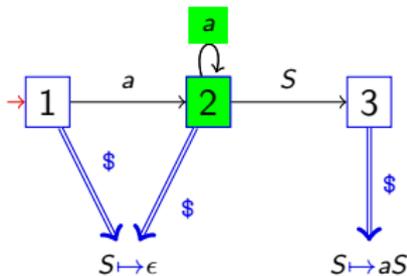
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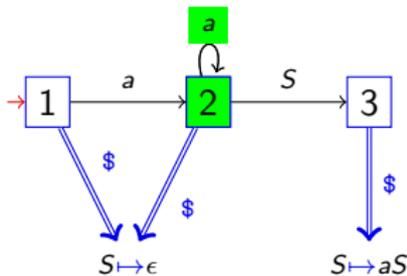
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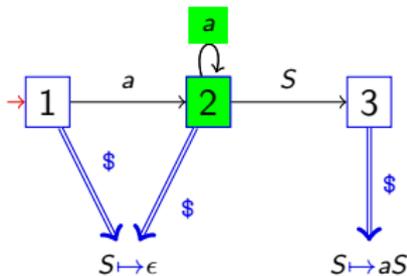
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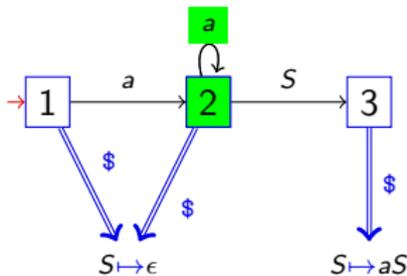
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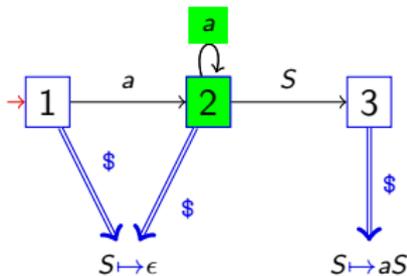
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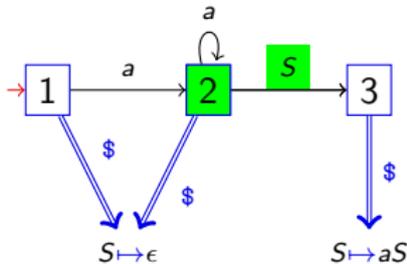
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Example of non-linear execution



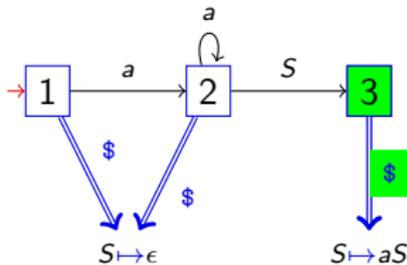
Mot lu : a a a a a a a a a **a** S \$

Example of non-linear execution



Mot lu : a a a a a a a a a a **S** \$

Example of non-linear execution

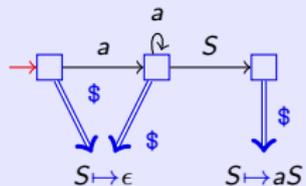


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Optimization : linear time

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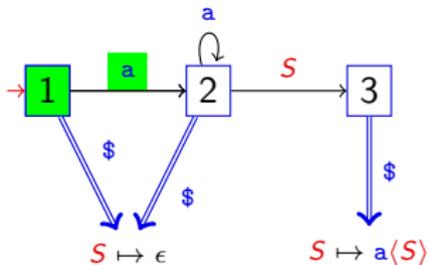


Solution

- In the buffer (which is now a stack), also memorizes the id of the state we came from.
- at the end of reduction, the automaton is restarted from the state given in the stack and on the created NT.

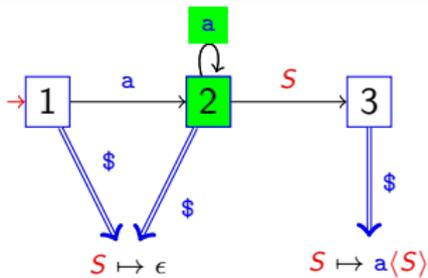
This is a stack automaton (with actions).

Example of linear execution



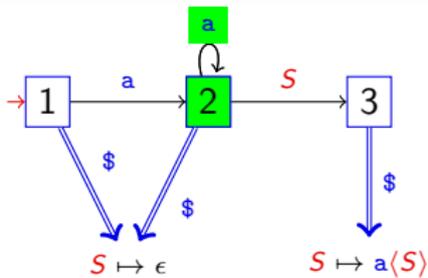
Mot lu : 1 **a** a a a a a a a a a \$

Example of linear execution



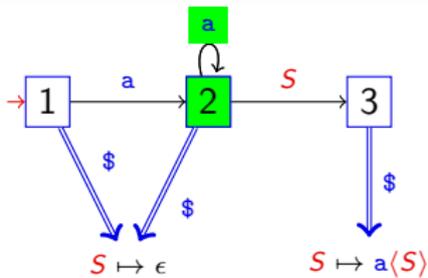
Mot lu : 1 a 2 **a** a a a a a a a a \$

Example of linear execution



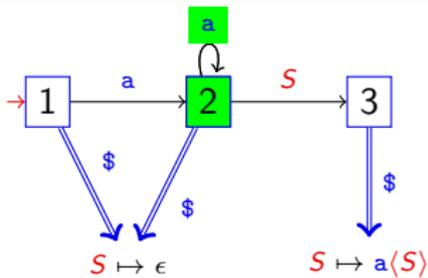
Mot lu : 1 a 2 a 2 a a a a a a a \$

Example of linear execution



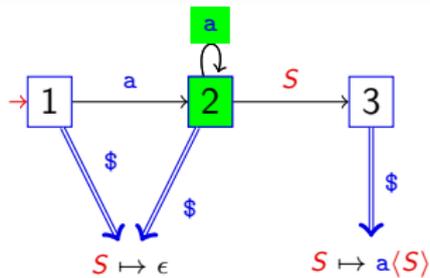
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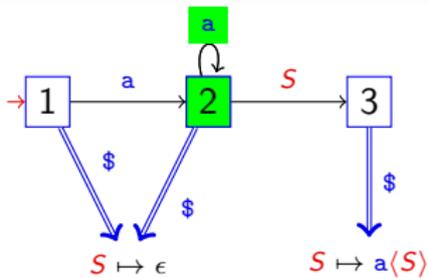
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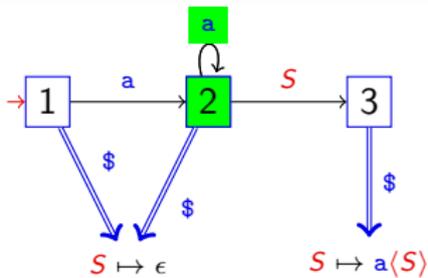
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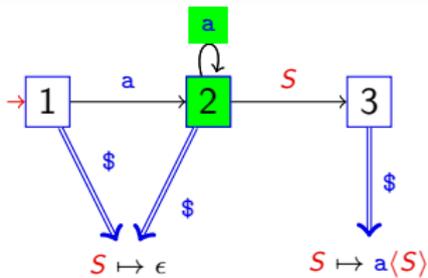
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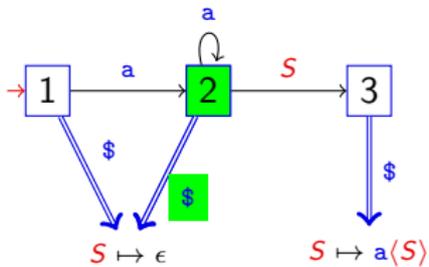
Mot lu : 1 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a a a \$

Example of linear execution



Mot lu : 1 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a a a \$

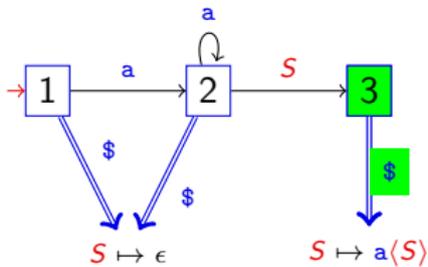
Example of linear execution



Mot lu : 1 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a 2



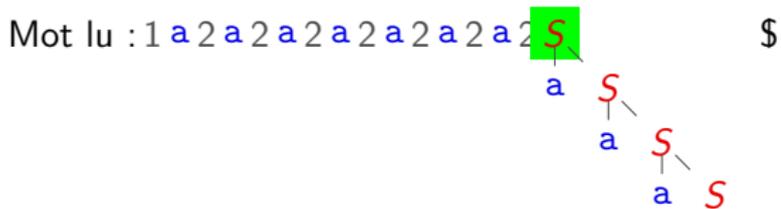
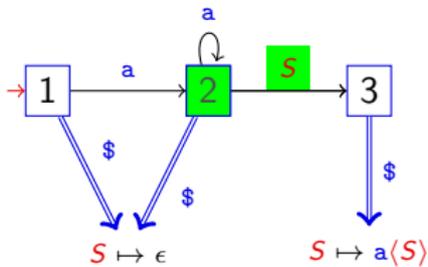
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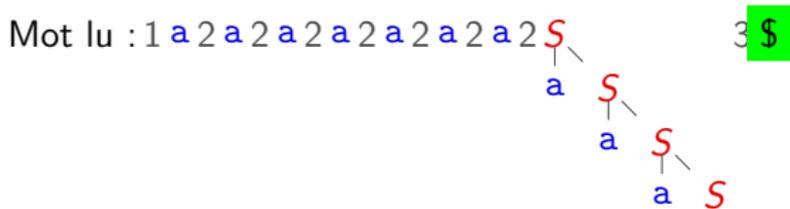
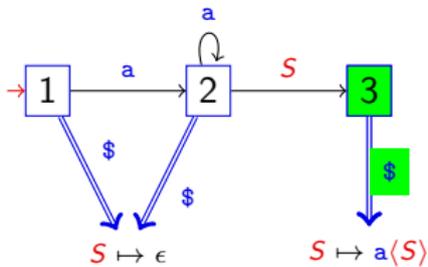
Mot lu : 1 a 2 a 2 a 2 a 2 a 2 a 2 a 2 a 2 S 3 \$

$$\begin{array}{c}
 S \\
 \swarrow \searrow \\
 a \quad S \\
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 \quad a \quad S
 \end{array}$$

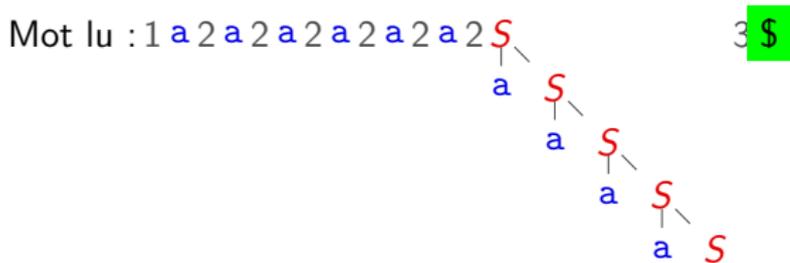
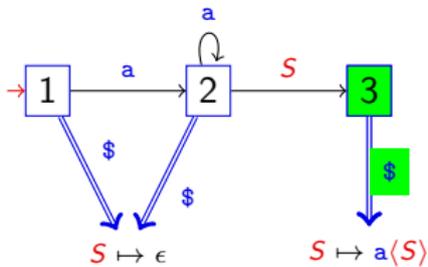
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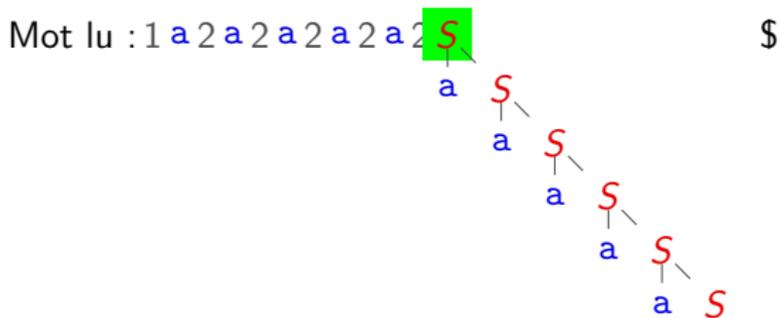
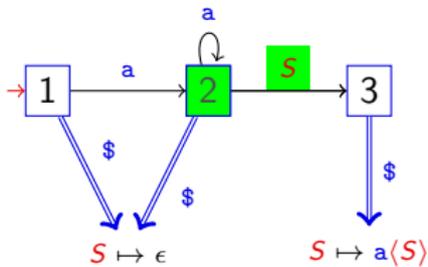
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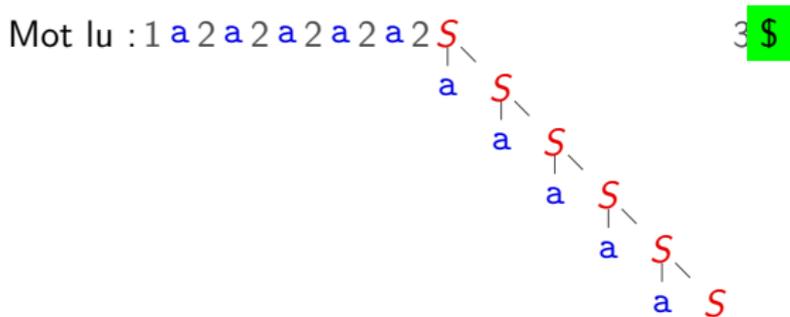
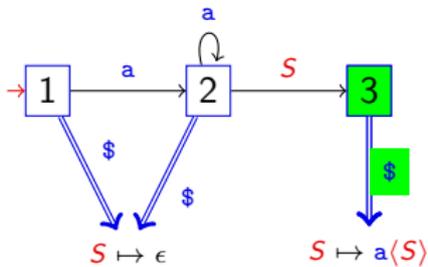
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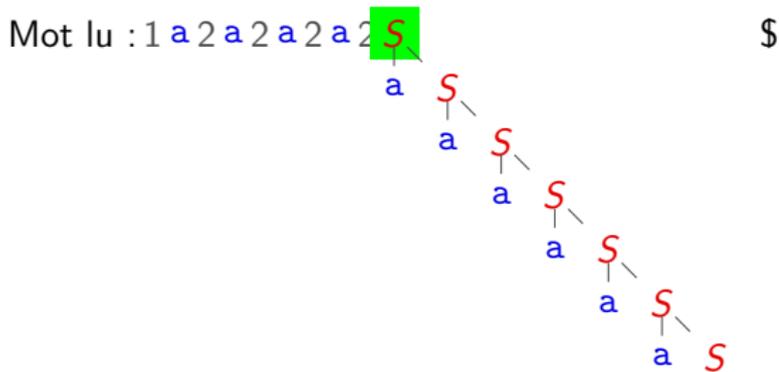
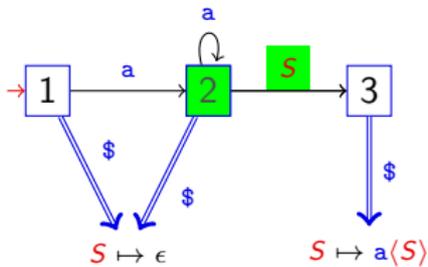
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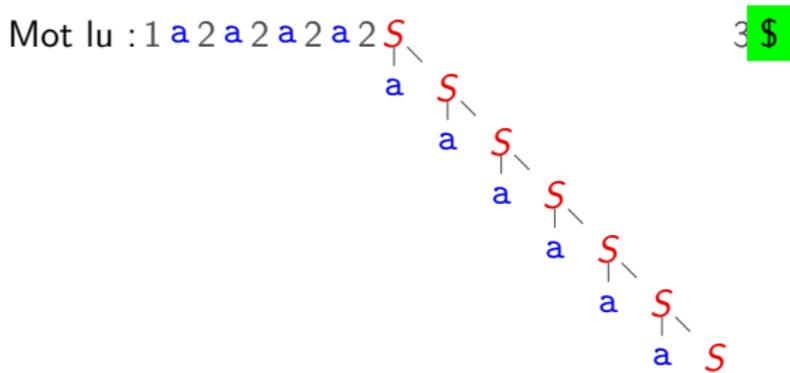
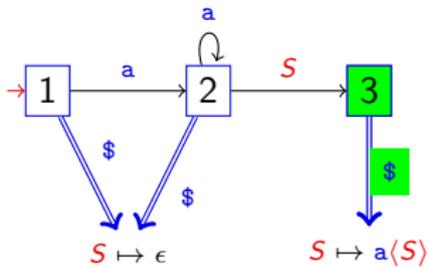
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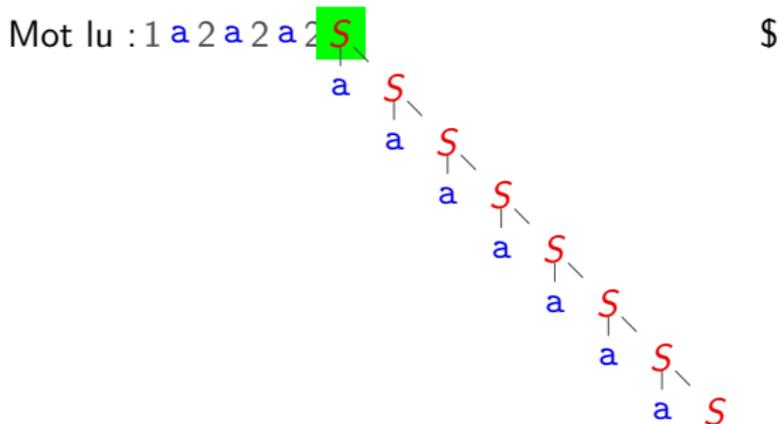
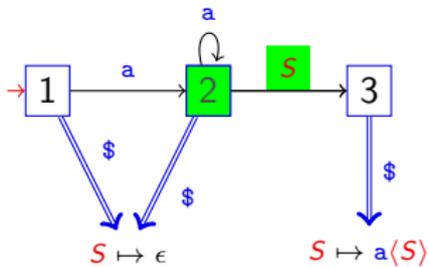
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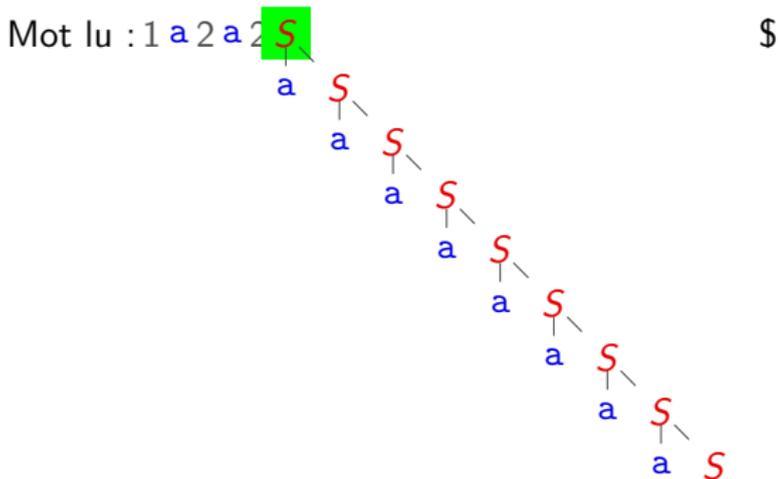
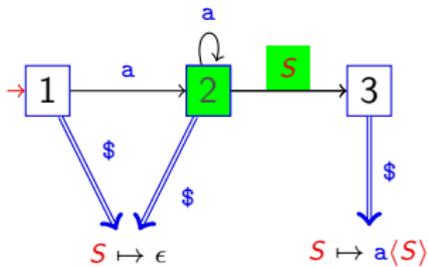
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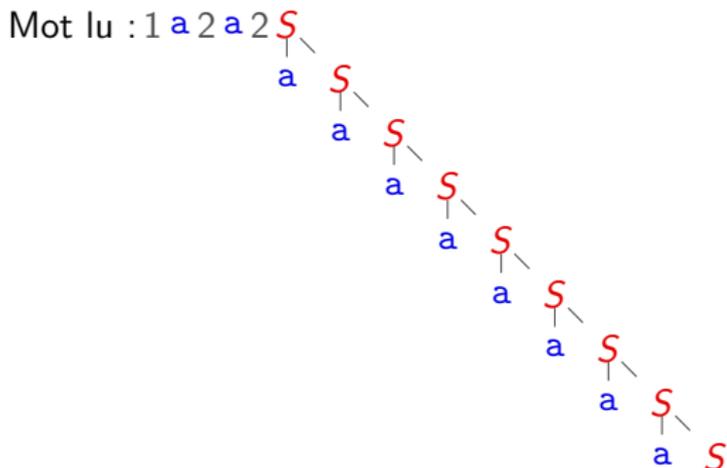
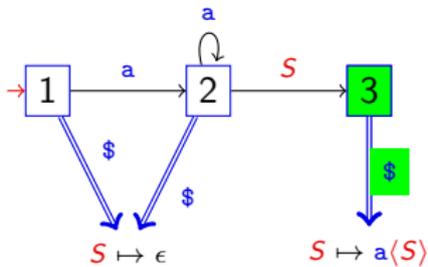
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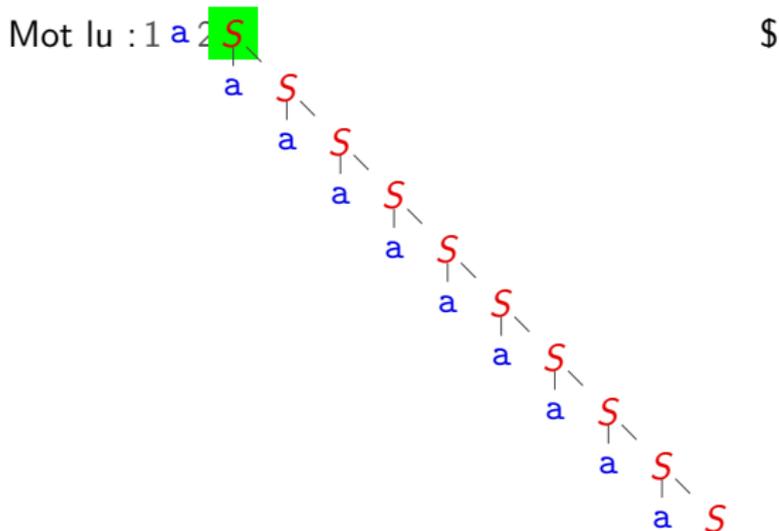
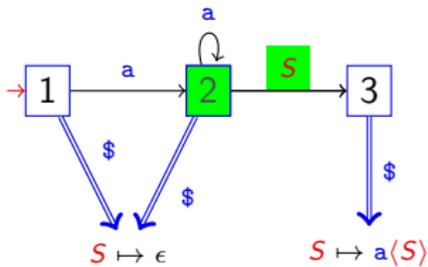
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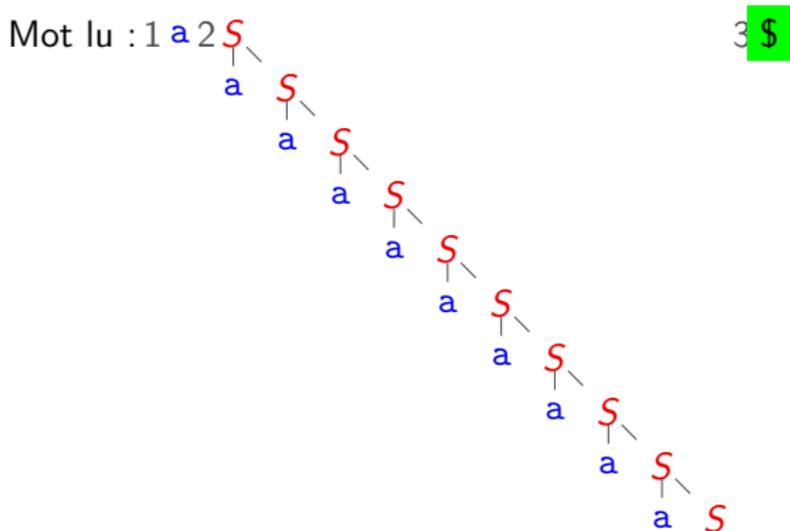
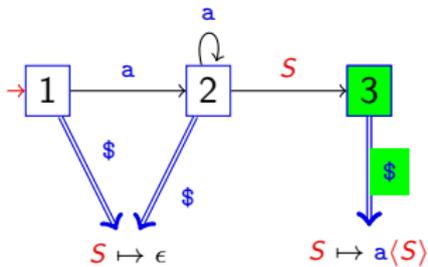
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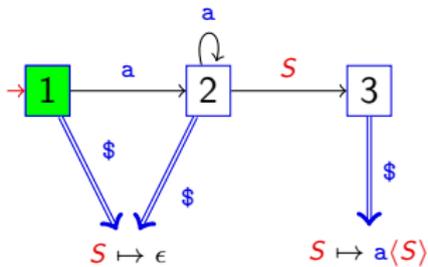
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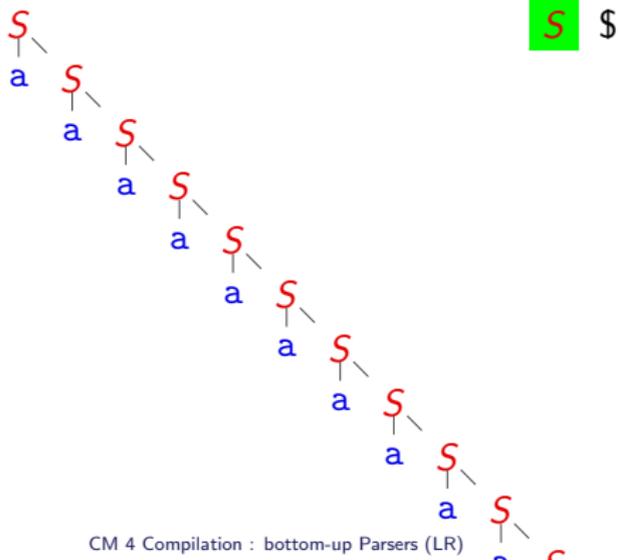
Example of linear execution



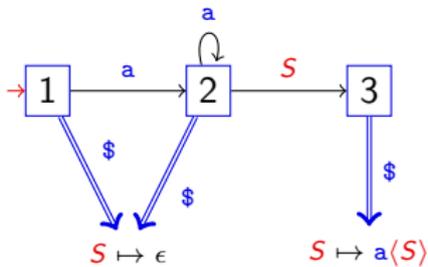
Example of linear execution



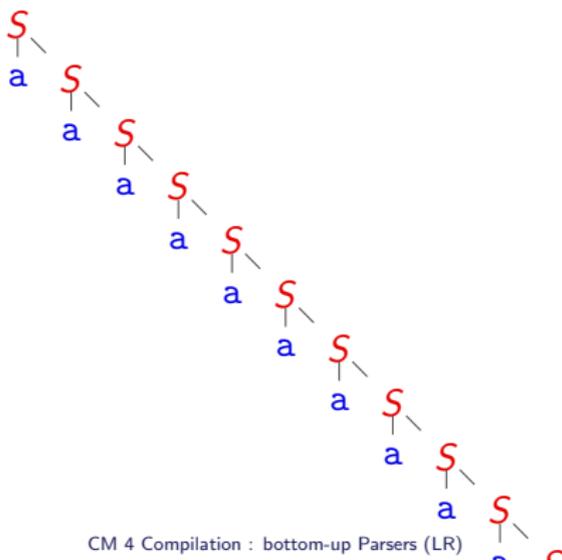
Mot lu :



Example of linear execution



Mot lu : S $\$$



Links to literature

Stack automata

The state idea are pushed into a stack

↔ Stack automata are required to recognize a grammar without backtracking

LR “GoTo”s = non-terminal shifts

The shift/goto table is the automaton table.

A “shift” labeled by a non-terminals is called “goto”.